

Permanent Counting Stations (PCS)

Microcomputer Programming Manual

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1/ INTRODUCTION

The purpose of this programming manual is to offer enough background information to a user to afford him or her a basic understanding of the system. The text does not deal with its respective subject in great detail, but, instead, tries to deal with the salient points. This turns out to be both an advantage and disadvantage: the brevity limits the quantity of text to be digested, but if the assumption that the reader has programming tendencies is in error, the reader may find portions difficult to follow because of the lack of development.

The manual deals with the completion of Phase II software. This version features up to 16 lanes of monitoring vehicle counts, long vehicles and speed. It does so by the manipulation of 26 routines. Of these, 10 were written directly for PCS, and the other 16 were taken from Caltrans District 11 software supplied for ramp metering. Modification to the Caltrans software ranges from minor to extensive, sometimes leaving little resemblance to the original form.

2/ SYSTEM OVERVIEW

The software for PCS was developed in a modular form. Each module treats a specific area of interest. Besides the tendency of single concept per module, there is also a distinction made for traffic direction. The routines carrying an 'A' suffix are Direction 2 routines, which are like Direction 1 with their references to memory offset. The exception to this convention is in 'PCS7' and 'PCS7A' where all volumes and all lengths, respectively, are dealt with.

2.1/ General Description

The routine layout, for the 26 routines, can be seen in Figure 2.1. The initialization routine is not called in the normal run of things; it must be invoked separately. Once the program is initialized and running, the amount of memory required depends on the size and configuration of the station. But generally, RAM Pages 00 through 04 are represented in Figures 2.2 through 2.6.

Page 0 holds the temporary storage area for PCS parameters in the general storage area, as well as some specific transient lane data. It also has the communications area, lane configuration and timing data.

Page 1 is the main storage area for lane data. It holds the various forms of the occupancy and volume. It also stores the long vehicle counts calculated by the 'PCS8' series program. All of the information is organized on a per-lane basis, first in Direction 1, then Direction 2.

Page 2 contains all the information for the calculation and classification of speed. There are the transition timing bytes for both directions, plus the roll over flag to ensure timing integrity. Also, there are static values for loop spacing, dimensioning and the threshold values used as standard to classify speeds. To that end, there is also the speed groups storage area which maintains a 3-byte count of each of the 12 speed categories, from >130 km/h to <30 km/h.

Page 3 is simply an extension of the previous page, since it deals with the daily storage of speed data. Whenever the 'HEADER' routine is



Figure 2.1/ Routine Layout

0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	SECURITY CODE														
1															
2	TIMING INFORMATION														
3															
4	LANE CONFIGURATION PARAMETERS														
5															
6	RESERVED FOR COMMUNICATION USE ONLY														
7															
8	DETECTOR ERROR FLAGS														
9															
A	GENERAL VARIABLE STORAGE AREA														
B															
C	UNVERIFIED AND VERIFIED LANE DATA														
D															
E	AVERAGE RUNNING TOTALS														
F															

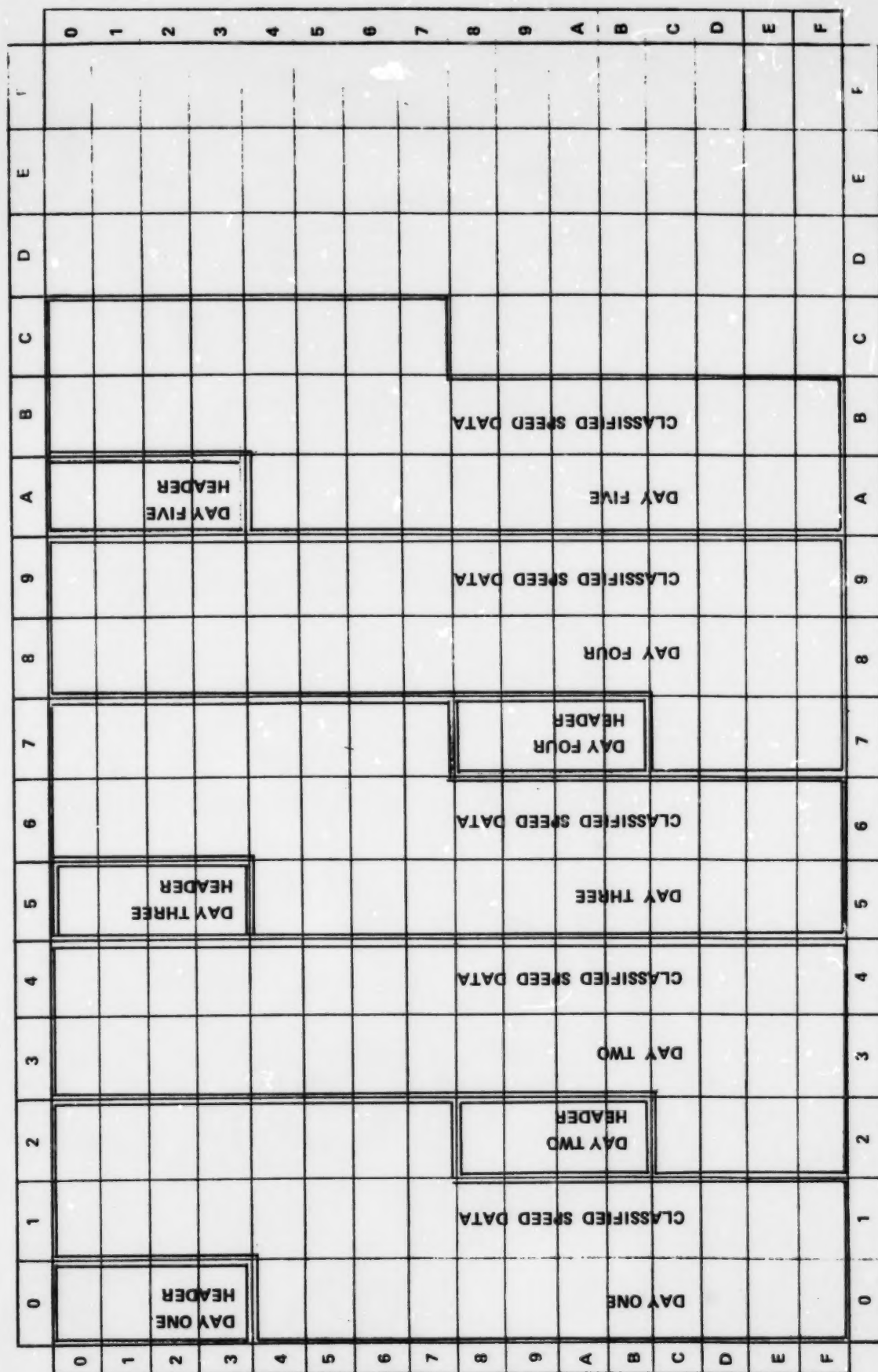
Figure 2.2/ Typical RAM Page $\phi\phi xy$

0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0															
1															
2															
3															
4															
5															
6															
7															
8															
9															
A															
B															
C															
D															
E															
F															
0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0															
1															
2															
3															
4															
5															
6															
7															
8															
9															
A															
B															
C															
D															
E															
F															
0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0															
1															
2															
3															
4															
5															
6															
7															
8															
9															
A															
B															
C															
D															
E															
F															

Figure 2.3/ Typical RAM Page $\phi 1xy$

	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0				DIRECTION ONE							MSB	ISB	LSB	> 130		
1			LANE TRANSITION TIMING BLOCK													
2				DIRECTION TWO												
3			LANE TRANSITION TIMING BLOCK													
4				DIRECTION ONE LOOP SPACINGS												
5				DIRECTION TWO LOOP SPACINGS								SPEED				
6				DIRECTION ONE LOOP DIMENSIONS								GROUP				
7				DIRECTION TWO LOOP DIMENSIONS								DATA				
8				DIRECTION ONE												
9				COUNTER ROLL OVER FLAG												
A				DIRECTION TWO												
B				COUNTER ROLL OVER FLAG										< 30		
C																
D																
E																
F																
	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F

Figure 2.4/ Typical RAM Page $\phi 2xy$

Figure 2.5/ Typical RAM Page $\phi 3xy$

DAY ONE VOLUME HEADER																0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0																															
1																															
2																															
3																															
4																															
5																															
6																															
7																															
8																															
9																															
A																															
B																															
C																															
D																															
E																															
F																															
0																															

Figure 2.6/ Typical RAM Page $\phi 4xy$

invoked, once every 24 h, its first duty is to transfer grouped speed data from Page 2 into the appropriate area in the speed transmit buffer. Day 1 is initialized to Location 0300 in all cases. The days are laid out as seen in Figure 2.5, where the sixth day would overlap Day 1, and so on.

Page 4 is the start of the volume counts. Day 1 is always initialized to 0400, while the position of the Day 2 header depends upon the size of the station and configuration chosen. This is also true for the long vehicle count buffer which follows, since it is identical in format to the volume buffer, but its origin is based on the size of the volume buffer.

2.2/ Road to Memory Lane Correlation

The system is designed to handle up to 16 lanes, resulting in the possibility of up to 32 loop detectors. The software relates the road configuration with the internal storage area. For a user, Page 1 needs, for the most part, no explanation, but the instantaneous values of Page 0 are not obvious.

Figure 2.7 demonstrates the relationship between the road and memory, which is useful to check the operation of the loop detector amplifiers and input software routines. Basically, the verified detector input data resides in Page 0, Row E, Columns A, B, C and D. These addresses are updated every 1/60 of a second and give a BCD version of the binary lane designation.

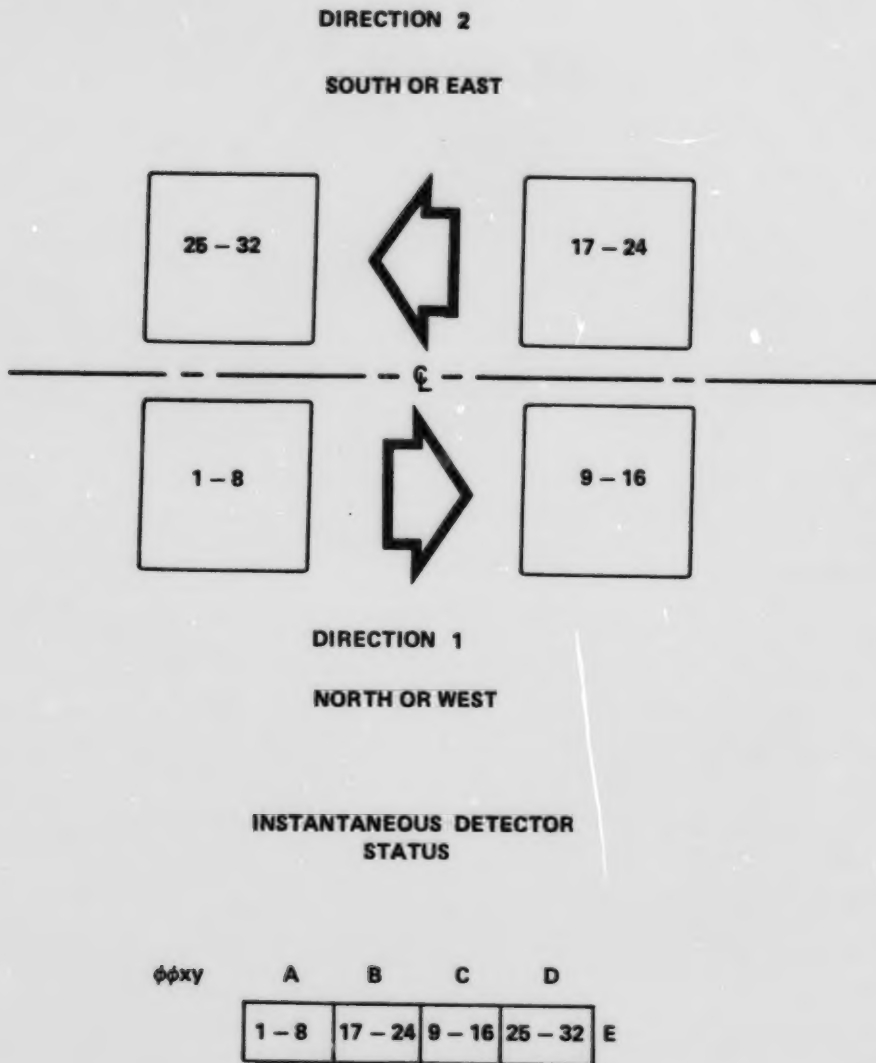
2.3/ Ode to Speed

A vehicle entering the test sections, besides being counted, is subjected to speed and length estimations which are determined by the following equations:

$$\text{Speed} = \frac{1}{2} \left[\frac{\text{LS}}{\text{B1E}} + \frac{\text{LS}}{\text{B1S}} \right] \quad (1)$$

where: LS = loop spacing

B1E = vehicle end transition timer



i.e., lane Direction 1 upstream located $\phi\phi_{AE}$

Figure 2.7/ Road to Memory Correlation

BIS = vehicle start transition timer

$$\text{Length} = \text{OCC} * \text{SPEED} - \text{LD} \quad (2)$$

where: OCC = vehicle occupancy of upstream detectors
LD = loop dimensions

Therefore, from Equation 1, any speed can be calculated given the requisite parameters. The units of km/h are not used, since loop spacing is in feet and timing is in 1/60 of a second counts. As a result, a new set of speed standards was derived. These standards are known as the threshold values, and are a result of all linear dimensions times eight and time in 1/60 of a second counts. These threshold values, translated into hex, are stored on RAM Page 2. A full speed conversion table is given in Figure 2.8, while a detailed example of one follows.

Given: vehicle travelling at 100 km/h (62.2 mph)

Objective: to determine the speed threshold values for given speeds

From (1):

$$S = \frac{1}{2} \left[\frac{LS}{BIE} + \frac{LS}{BIS} \right]$$

Where: LS = 20 ft. x 8 = 160 ft.

Now: BIE = BIS = passage time in sample intervals

$$\text{Therefore: } 62.2 \text{ mph} = \frac{62.2 \times 5280}{3600} = 91.2 \text{ ft./s}$$

$$\text{Passage Time} = \frac{20 \text{ ft.}}{91.2 \text{ ft.}} \times \frac{s}{ft.} = 219.2 \text{ ms}$$

Since: 219.2 ms is required to cover the test section, and the sampling rate is 1/60 of a second, the total number of counts is:

$$\text{Total number of counts} = \frac{219.2}{16.7} = 13.2 \text{ counts}$$

Therefore, threshold value from (1):

$$S = \frac{1}{2} \left[\frac{160 \text{ ft.}}{13} + \frac{160 \text{ ft.}}{13} \right]$$

$$S = 12.30$$

Note: The loop spacing and dimension values both are represented in memory by a hex value which is eight times the linear value in feet. The default value of LS is equivalent to 26 ft., while LD is equivalent to 6 ft.

km/h	mph	ft./s	ft.x 8 count	SPD	REM	Speed Group
130	80.8	118.5	15.8	15	48	>130
120	74.6	109.4	14.6	14	36	120 - 130
110	68.4	100.3	13.4	13	24	110 - 120
100	62.2	91.2	12.2	12	12	100 - 110
90	55.9	82	10.9	10	54	90 - 100
80	49.7	72.9	9.7	9	42	80 - 90
70	43.5	63.8	8.5	8	30	70 - 80
60	37.3	54.7	7.3	7	18	60 - 70
50	31.1	45.6	6.1	6	6	50 - 60
40	24.9	36.5	4.9	4	54	40 - 50
30	18.6	27.3	3.6	3	36	30 - 40
<30	<18.6	<27.3	<3.6	<3	36	<30

Figure 2.8/ Speed Conversion Table

2.4/ Lane Proportioning Constants

In order to provide the average lane information as in the 'PCS5' series of routines, a known contribution, from each lane, based on the number of lanes, must be made. These contributions are derived from the Lane Proportion Constants. Their derivation can be seen below:

PCLN1	0
PCLN2	128
PCLN3	171
PCLN4	192
PCLN5	205
PCLN6	213
PCLN7	219
PCLN8	224

For 1 Lane

2 Lanes	=	$(256-128)/256$	=	$128/256$	=	0.50
3 Lanes	=	$(256-171)/256$	=	$85/256$	=	0.33
4 Lanes	=	$(256-192)/256$	=	$64/256$	=	0.25
5 Lanes	=	$(256-205)/256$	=	$51/256$	=	0.20
6 Lanes	=	$(256-213)/256$	=	$43/256$	=	0.17
7 Lanes	=	$(256-219)/256$	=	$37/256$	=	0.14
8 Lanes	=	$(256-224)/256$	=	$32/256$	=	0.13

3/ RAM PAGES

In the following section, a detailed illustration of the first five RAM pages will be given. It will deal with RAM in greater detail than Section 2.1 and include parameter manipulation, where applicable, as well as the physical location.

3.1/ Page 00xy

As can be seen in Figure 3.1, this page is the storage area for general PCS parameters. It also has the communications area, lane configuration and timing data. The communication software is a separate entity, being independent of PCS operation. The timing information is controlled by an independent routine, while lane configuration is manipulated by the user. Figure 3.2 details the parameter location within the page.

3.2/ Page 01xy

As can be seen in Figure 3.3, Page 01xy is the main storage area for lane data. In Figure 3.4, the actual parameters stored are shown to comprise volume, occupancy rates, length and occupancy counts. The format for the RAM page is two direction data, with 16 lanes of 16 bytes of information per lane. Therefore, the rows represent a particular parameter for the lanes, while the column identifies the particular lane.

In the software, the base variable name is given as the address. All the base variables have been defined in the 'Equate' file (Appendix A). Therefore, to step through the lanes, all that is needed is to address the lane variable in an indexed mode. This is exactly what happens. With the use of two routines, 'SETUP' and 'NEXTLN,' the index value is set to access the highest lane. Then the index is decremented by 100 each time, in order to step through the lanes in ascending order. The process is the same for both directions, which are treated separately, except for the Direction 2 variables which have a 800 offset to locate them properly in memory.

0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	LANE CONFIGURATION PARAMETERS														
1															
2	TIMING INFORMATION														
3															
4	RESERVED FOR COMMUNICATION USE ONLY														
5															
6	DETECTOR ERROR FLAGS														
7															
8	GENERAL VARIABLE STORAGE AREA														
9															
A	UNVERIFIED AND VERIFIED LANE DATA														
B															
C	AVERAGE RUNNING TOTALS														
D															
E															
F															
0	SECURITY CODE														
1															
2															
3															
4															
5															
6															
7															
8															
9															
A															
B															
C															
D															
E															
F															

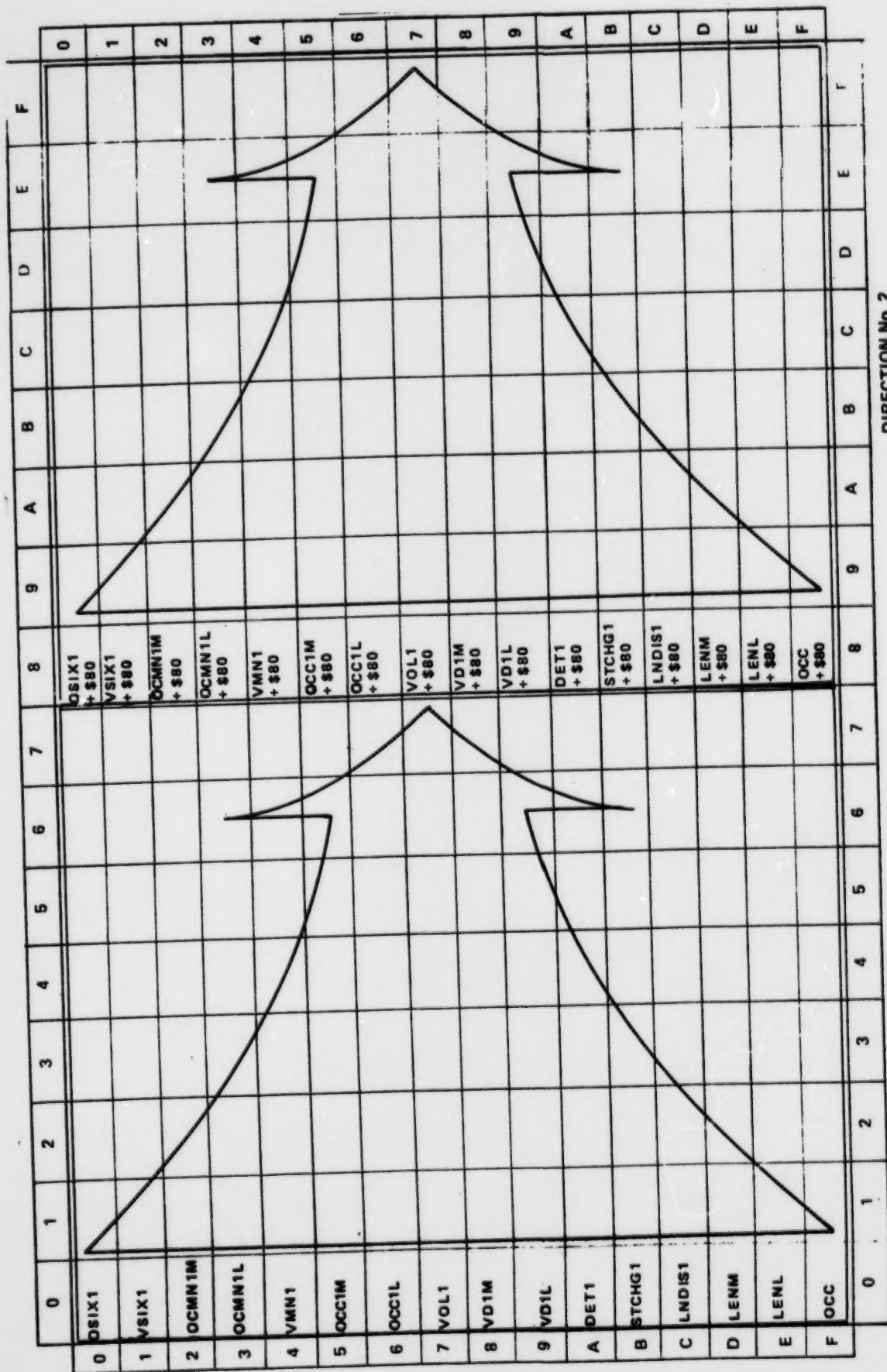
Figure 3.1/ General RAM Page φφxy

	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0		NLANE1						VOLDAY			SPC1	GO	DTCTRM	DTCTRL		
1		NLANE2						WW			VODAY1	GOT				
2		LDESW1									VODAY1+KAY2	GOA				XLANE
3	YEAR	LDESW2						VOBUF1			TRUCK	GOTA			COUNT1	PCW1
4	MONTH	NVOL1						VOBUF1+1			LENGTH				COUNT2	KAY1
5	DAO FMO	NVOL2						SPDDAY			SIZE	LENGTH+1			COUNT3	TEMP-01
6		VOLDW1						SPDAY1			PTRL	SPEED			COUNT4	TEMP-02
7		VOLDW1+1						SPDAY1+1			PTRL+1	SPEED+1			COUNT5	TEMP-03
8		VOLDW1+2						SPBUF	DETER1		PTR6	VODAYL			COUNT6	TEMP-04
9	DAO FWK	VOLDW1+3							DETER2		PTRS+1	VODAYL+				TEMP-05
A	HOUR	VOLDW1+4						LENDAY	DETER3		VODAYS				INDEX	TEMP-06
B	MINUTE	VOLDW1+5						LNDAY1	DETER4		QC1OCM	VODAYS+			INDEX+1	TEMP-07
C	SECOND	VOLDW1+6						LNDAY1+1			OC1OCL	DATA-0M	DATA-0L		AR1MOM	
D		VOLDW1+7						LNBUF1			PTR	DATA1M	DATA1L		AR1MOL	
E		LDNW1					MRAM	LNBUF1+1			PTR+1	DETINM	DETINL		AR1VM	
F		LDNW2						DAYMAX			CYCLE	STCHGM	STCHGL		AR1MVL	
	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F

Figure 3.2/ Detailed RAM: 00xy Organization

0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0															
1															
2															
3															
4															
5															
6															
7															
8															
9															
A															
B															
C															
D															
E															
F															
0															
1															
2															
3															
4															
5															
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C															
D															
E															
F															
0															
1															
2															
3															
4															
5															
6															
7															
8															
9															
A															
B															
C															
D															
E															
F															

Figure 3.3/ General RAM Page 01xy



3.3/ Page 02xy

Figure 3.5, the general organization of the RAM, concerns itself with the interests of speed, calculation and classification. Figure 3.6 associates the parameters with the quantities of the page. The 'E' and 'S' suffixes of the transition timers and roll over flags represent a vehicle's end or start. The information contained in these and the loop characteristic storage area is accessed with index addressing. Here, as on Page 1, 'SETUP' and 'NEXTLN' index the base address to select the proper lane column.

The speed concerns on the page, 'SPD', 'REM' and 'SPED,' use the same type of addressing mode, except it has no association with the lanes. In this case, the base address is simply incremented by 1 in order to step the pointers down through the column of information.

3.4/ Page 03xy

This page of RAM is dedicated to the daily storage of classified speed. In the general RAM illustration (Figure 3.7), the layout can be seen for a five-day cycle. Figure 3.8 illustrates what would be found at the end of the day of initialization. It shows the parameters which make up the header, and it illustrates the order in which the classified values are stored in the transmit buffer.

As the days progress, this identical structure would appear for every completed day, rolling over onto Day 1 for Day 6. The layout of the speed classification in this buffer is more readily understood when considered in conjunction with Section 3.3.

3.5/ Page 04xy

From Figures 3.9 and 3.10, little insight is gained with respect to the structuring of the page. The reason for this is, as previously mentioned, the structure depends on the size and configuration of the station. But there are some general facts about the first page of the volume transmit buffer.

[illegible]Figure 3.5/ General RAM Page $\phi 2xy$

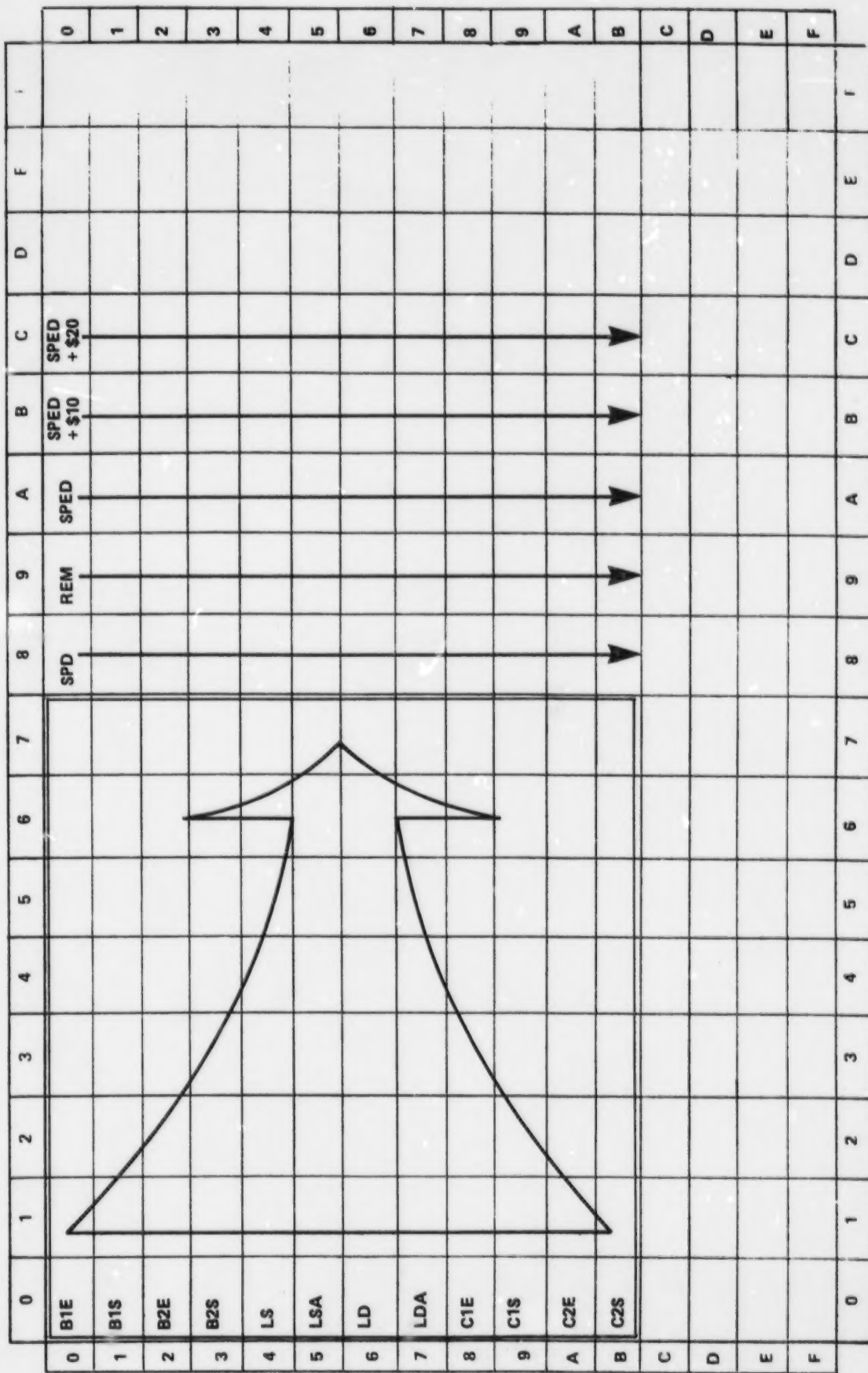


Figure 3.6/ Detailed RAM $\phi 2xy$ Organization

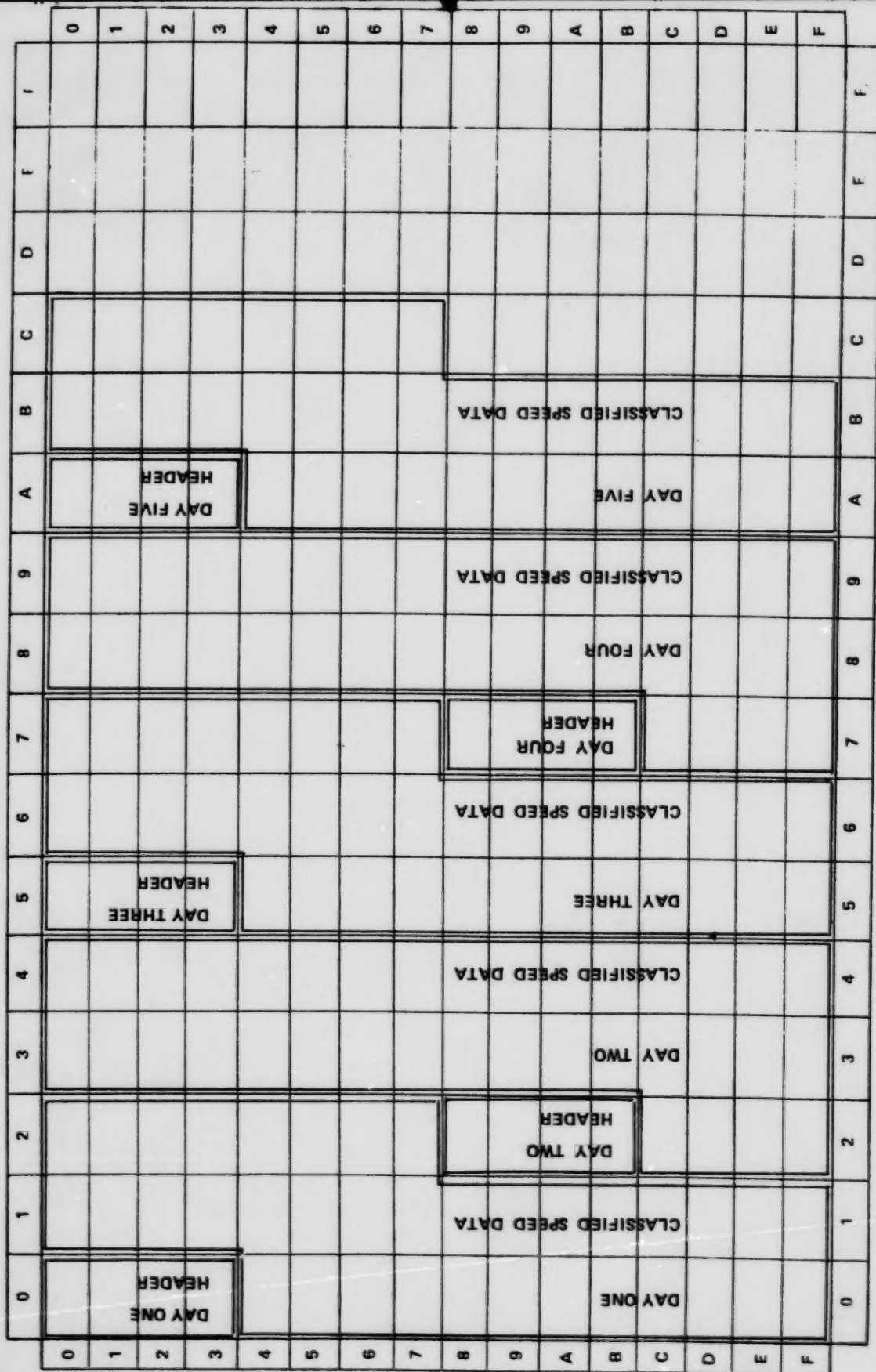


Figure 3.7/ General RAM Page $\phi 3xy$

	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	I
0	YEAR	SPED,4	SPED + \$10,9														0
1	MONTH	SPED + \$10,4	SPED + \$20,9														1
2	DAOFMO	SPED + \$20,4	SPED,A														2
3	DAOFWK	SPED,5	SPED + \$10,A														3
4	SPED	SPED + \$10,5	SPED + \$20,A														4
5	SPED + \$10	SPED + \$20,5	SPED,8														5
6	SPED + \$20	SPED,6	SPED + \$10,8														6
7	SPED,1	SPED + \$10,6	SPED + \$20,8														7
8	SPED + \$10,1	SPED + \$20,6															8
9	SPED + \$20	SPED,7															9
A	SPED,2	SPED + \$10,7															A
B	SPED + \$10,2	SPED + \$20,7															B
C	SPED + \$20,2	SPED,8															C
D	SPED,3	SPED + \$10,8															D
E	SPED + \$10,3	SPED + \$20,8															E
F	SPED + \$20,3	SPED,9															F
	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F	I

Figure 3.8/ Detailed RAM 43xy-Organization

DAY ONE VOLUME HEADER																	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0																																
1																																
2																																
3			DAY ONE																													
4			VOLUME																													
5			TRANSMIT																													
6			BUFFER																													
7																																
8																																
9																																
A																																
B																																
C																																
D																																
E																																
F																																
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Figure 3.9/ General RAM Page 4xy

	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
0	YEAR															
1	MONTH															
2	DAOFMO															
3	DAOFWK															
4																
5																
6																
7																
8																
9																
A																
B																
C																
D																
E																
F																
	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F

Figure 3.10/ Detailed RAM $\phi 4 \times y$ Organization

The buffer always starts with its initial header at 0400. It takes on the same type of format as seen in 03xy, with respect to the five-day cycle. Internally, though, the difference is dramatic. Two bytes are allocated for each value count sum, in each direction, which is determined by the user's configuration. But independent of the size, the Direction 1 sums appear first, followed by Direction 2.

4/ OPERATING PROCEDURES

Under normal operations, a user must define the physical layout of the loop detectors and impose the data handling format he/she requires. In starting up a new system, or when changes have been made to the system, a system initialization is also required. But, if the controller has just been powered down and back up again, system initialization is not required, since the battery backup maintains the value of RAM.

For example, suppose it was necessary to define a configuration of a situation as illustrated in Figure 4.1. The first step is to enter the Security Code 07,05 into Addresses 01,02. Assuming the time is correct, the next step is the definition of the configuration as in Figure 4.1.

Parameter	Address	Value
NLANE1	10	3
NLANE2	11	3
LDESW1	12	7
LDESW2	13	7
NVOL1	14	2
NVOL2	15	2
VOLDW1	16	3
VOLDW2	17	4
VOLDW3	18	3
VOLDW4	19	4
VOLDW5	1A	0
VOLDW6	1B	0
VOLDW7	1C	0
VOLDW8	1D	0
LDNW1	1E	7
LDNW2	1F	7

A detailed description of the parameter above can be found in Section 6.7.3. Basically, 'NLANE1/2' means that there are three lanes in each direction. The 'LDESW1/2' indicates which lanes are equipped with loop detectors. In the three lanes, there are two summed counts,

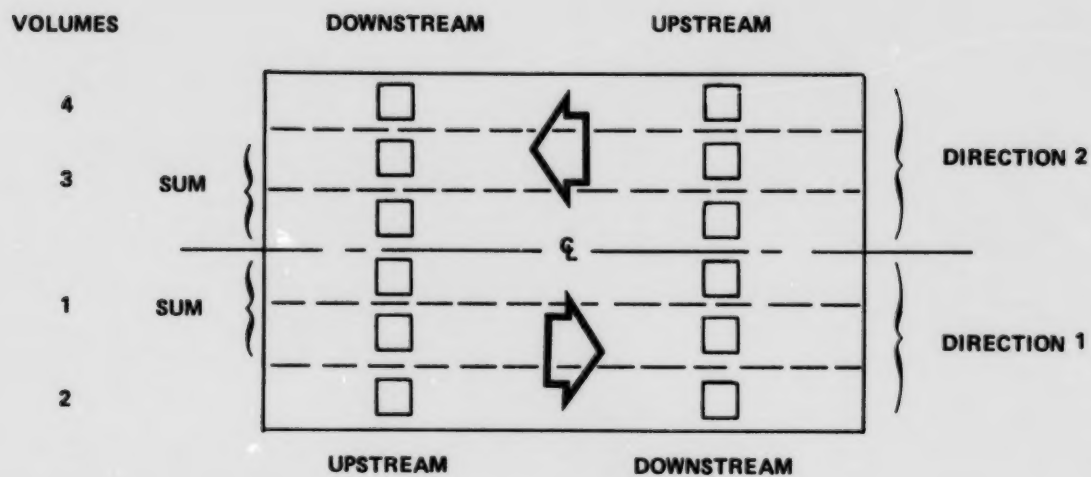


Figure 4.1/ Typical Lane Configuration

indicated by 'NVOL1/2,' and which lanes are associated for these counts is found in the 'VOLDW' series. It is very important that the unused portions of the 'VOLDW' series parameters, in Cases 5 through 8, be defined as zero. And last, there are the downstream description bytes found in 'LDNW1/2.' These entries followed by an initialization (any non-zero value in 06D) would start the system functioning as desired.

The only other variables which a user may like to change are the loop spacings 'LS' and loop dimensions 'LD.' Once the desired values (Section 2.3) are calculated, they may be entered in the appropriate memory locations (Section 3.3).

5/ ROUTINE SUMMARY

5.1/ Lane Data Pointer Initialization

Routine Request: 'SETUP'

Options: None

Function

Prior to accessing the lane and/or lane data area, the lane pointer must be reset to a datum. This is done by using this routine, which assigns the pointer a value of 0170. All lane information resides on Page 01, and Column 70 happens to be Lane 8 in Direction 1. Therefore, the various functions associated with a lane can be accessed in successive addresses of the appropriate column. Areas for Direction 2 are treated in a similar manner, with the addition of an \$80 offset.

Comments

This is a very simple routine that serves a vital service. It should be kept in mind when examining the lane scanning provided by 'SETUP' and 'NEXTLN' that it is from the highest lane number in a particular direction to the lowest lane number.

5.2/ Lane Scan Control

Routine Request: 'NEXTLN'

Options: None

Function

If any portion of the software requires the lanes or lane data to be scanned, whether for input or data manipulation, this routine should be exercised. It will, when called, step through the lanes in descending order, highest to lowest, updating the address pointer INDEX, INDEX + 1.

As in the 'SETUP' description, lane data can be accessed from the base address, and the Direction 2 information requires the addition of an \$80 offset.

Comments

Since the subroutine requires the use of Accumulator 'A', its contents, defined by the calling routine, are pushed into the stack at the outset of 'NEXTLN' and pulled before the subroutine relinquishes control. This ensures the error-free operation of the calling routine.

5.3/ 8-Bit Multiplication

Routine Request: 'MULT'

Options: None

Function

This routine multiplies the 8-bit unsigned number in Memory Location 00F8 by the 8-bit unsigned number in Memory Location 00F9, and then places the 8 most significant bits of the result in Memory Location 00FA and the 8 least significant bits in Memory Location 00FB.

Comments

To run this algorithm on a system with a 1 MHz clock takes between 190 and 230 μ s.

5.4/ 8-Bit Division

Routine Request: 'DIV'

Options: None

Function

This routine divides the 8-bit unsigned number in Memory Location 00F9 by the unsigned 8-bit number in Memory Location 00F8. It stores the quotient in Memory Location 00FA and the remainder in Memory Location 00FB.

Comments

The algorithm takes between 170 and 210 μ s to divide, with a 1 MHz clock.

Ensure that the divisor and dividend are correctly assigned, since it is the usual source of unexpected results.

5.5/ 16-Bit Number Comparison

Routine Request: 'CMP16'

Options: None

Function

This generalized comparison routine operates on 8 bits at a time. The most significant byte of the indexed number is compared to the number stored in Memory Location 00F6, and unless the quantities are equal, the process can clear or set the carry bit to indicate the outcome. If they are equal, the least significant byte of the indexed number is compared to the value in Memory Location 00F7. If the indexed value is greater than the memory location value, the carry bit is set; otherwise, it is cleared.

Comments

Remember that if the carry bit is clear, the values can be equal as well as the Memory Location 00F6, 00F7 being greater than the indexed value.

5.6/ Lane Proportioning Control

Routine Request: 'PRPRT'

Options: (a) 8-bit proportioning
(b) 16-bit proportioning

Function

The subroutine performs the operation $N = N(1-PCW/256)$, where N represents the number to be proportioned, and PCW the proportion of 'N' to be subtracted. Upon completion, Accumulator 'A' holds the MSB proportion of 'N,' and Accumulator 'B' holds the LSB proportion.

Comments

The routine is capable of handling both 8- and 16-bit numbers determined by the index register.

5.7/ System Initialization

Routine Request: 'INIT'

Options: Lane configuration

Function

The purpose of this routine is three-fold. It is required to:

- clear memory,
- assign definitions and calculate variables, and
- output the first header.

It is desirable to clear memory in bulk since many of the parameters on Page 0 must be initialized to zero anyway. Also, it clears the transmit buffers to avoid getting erroneous data in the unused hours of the initial day.

Since the programs to follow require predetermined values, dealing with lane configuration and the like, the routine is the logical place for the calculation and the definition of parameters.

The third function, initial header output, naturally belongs here because it is not required in the cyclic nature of the normal operating routines.

Comments

To invoke the initialization routine, the Memory Address \$06D must be set to any non-zero value. When this is done and the 'INIT' routine completed, the value of \$06D is restored to zero.

It should be noted that the memory clearing portion has an arbitrary upper limit of \$07DF, which represents 2K bytes of memory minus the stack location. As a result, the routine will not clear transmit buffers which occupy addresses higher than this location, which is not critical, but undesirable.

5.8/ Speed Output and Header Control

Routine Request: 'HEADER'

Options: None

Function

For the purpose of identifying a particular day's data, it is preceded in memory by a header block. This consists of 4 bytes as is appropriate for the particular day's data:

- 1/ current calendar year,
- 2/ current calendar month,
- 3/ day of the month, and
- 4/ day of the week.

Along the same lines, a myriad of pointers must be updated, by the routine, to keep header data, days of data, cycle and position in the circular buffer valid.

'HEADER' is also called upon to output the speed data into its transmit buffer. Since speed is only provided once a day, and 'HEADER' is run once a day, their association is natural.

Comments

'HEADER' is called as a 24 h routine. Values in the header block are represented in BCD.

5.9/ Detector Input Scan Control

Routine Request: 'INPUT'

Options: None

Function

As its name implies, this routine is responsible for the acquisition of detector signals. It does so by providing the correspondence between hardware detector assignments, port and bit numbers, and internal software detector assignments.

Comments

The 'INPUT' routine is called in the 1/60 of a second time slot by 'PCS2.'

5.10/ Single Error Correction Routine

Routine Request: 'PCS2'

Options: None

Function

This process screens incoming raw data by checking for valid vehicle transition data sequences. By considering three sequential data sets, valid and spurious data can be separated and indicated through state change information. The result of the exercise is that verified data are ready for further processing.

Comments

The correction routine is called every 1/60 of a second.

5.11/ Upstream Detector Servicing Routine

Routine Request: 'PCS3'

Options: None

Function

At the point of initiating the 'PCS3' series of programs, valid data have been established and are now ready to be acted upon. This routine, when appropriate, adjusts volume counts, starts vehicle transition timing and secures occupancy for speed and length routines.

Comments

The routine is executed at a call rate of 1/60 of a second.

5.12/ Downstream Detector Servicing Routine

Routine Request: 'PCS3B'

Options: None

Function

This version of the 'PCS3' series of programs is responsible for indicating that timing data for a vehicle are ready for processing. This is done by manipulating the transition timing flags, which is the sole responsibility of the downstream detectors.

Comments

The routine is executed at a call rate of 1/60 of a second.

5.13/ Lane Data Handling Routine

Routine Request: 'PCS4'

Options: None

Function

The 6 s volume/occupancy counts are added to the 1 min and hourly counts by this routine. In the case of hourly volume counts, the routine derives absolute counts as well as running totals. Occupancy, on the other hand, is not compiled in hourly format.

Comments

For understanding of the running total data, the routine 'PRPRT/PRPRT8' should be digested, as 'PCS4' relies on it very heavily.

The execution rate of this data handling routine is 6 s.

5.14/ Average Running Total Routine

Routine Request: 'PCS5'

Options: Number of lanes for average

Function

This very straightforward routine simply takes the running totals for all the eligible lanes and averages them over the number of lanes desired.

Comments

These values generated have no application in Phase II software as it stands. But in case PCS is required to perform some control features in the future, it was thought to be more appropriate to incorporate these values during its development rather than later.

This routine functions at a execution rate of 6 s.

5.15/ Detector Failure Check Routine

Routine Request: 'PCS6'

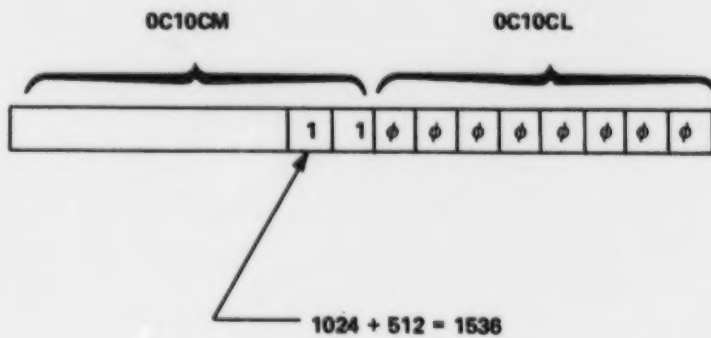
Options: Occupancy limit threshold

Function

This routine checks the lane's detector status. Only a simple test is conducted on the incoming signal from the loop detectors and their amplifiers. Although the routine has provisions to expand to many more failure checks, the only one present now is if the lane appears to be occupied greater than a pre-defined time. The threshold limit 'OC10CM/OC10CL' is located in \$09B/09C and defined in 'INIT.'

Comments

The default value is set for approximately 43% of the 1 min occupancy (Figure 5.1).



SINCE: MAXIMUM OCCUPANCY FOR 1 MIN IS $60 \times 60 = 3600$

THEREFORE: $1536 \div 3600 \times 100 = 42.6\%$

Figure 5.1/ Occupancy Limit Threshold

5.16/ Hourly Data Transfer Routine

Routine Request: 'PCS7'

Options: None

Function

The information concerning lane volumes is transferred to the transmit buffer with the use of this routine. It calculates the appropriate time slot and then inserts the volume data, summed where required, for both directions, into the appropriate day of the transmit buffer.

Comments

The long vehicle counts are treated identically to the volume counts described above and are handled by 'PCS7A.'

5.17/ Vehicle Speed and Length Classification

Routine Request: 'PCS8'

Options: None

Function

Data which have been received from the lanes are manipulated to calculate the vehicles' speed and to determine whether or not the vehicles exceed 6.5 m in length. In vehicle length, a vehicle either increments the count, or is excluded, whereas for speed, there are 12 speed ranges.

Comments

Long vehicle counts are loaded into the transmit buffer by 'PCS7A,' while speed is done on a daily basis by 'HEADER.'

6/ ROUTINE DESCRIPTION

6.1/ 'Setup'

6.1.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 163, Line 260, extending to Line 263.

6.1.2/ Program Explanation

Since the PCS system is capable of scanning up to 16 lanes and does so on a constant basis, a need was perceived for a routine to initialize the data pointer. The function is required in 15 different locations throughout the software, which reinforced the need for the subroutine 'SETUP.'

The routine starts by defining its origin to be at C060. Then the index register is loaded immediately with the hex value of 0170. The 2-byte assignment defines the RAM Page 01 as well as the seventh column which is seen in the second byte 70. As can be seen in Section 3.2, this sets the lane data pointer at base of highest lane. With this datum established, indexed addressing techniques are employed to move the pointer down a particular column. Different columns are chosen by exercising another subroutine, 'NEXTLN,' which will be dealt with subsequently.

This routine is terminated by the return from subroutine statement which, as its name implies, returns control to the routine which originally was called 'SETUP.'

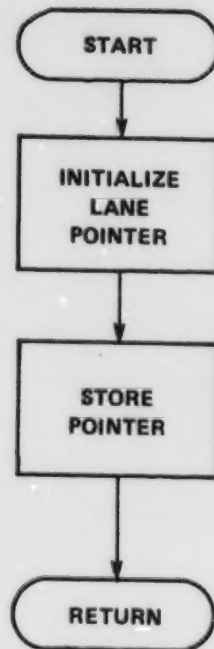
6.1.3/ Parameter Index

Routine: 'SETUP'

Description: Initializes lane data pointer.

Parameter	Description
INDEX	- this parameter along with INDEX+1 stores the 16-bit code used by the index register to allow accessing of lane data.

6.1.4/ Flow Chart



6.2/ 'NEXTLN'

6.2.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 163, Line 240, extending to Line 252.

6.2.2/ Program Explanation

After calling the subroutine 'SETUP,' the lane pointer is defined to indicate the highest lane, which is Number 8, in Memory Location 0170. The subroutine 'NEXTLN' allows various routines to sequentially step down through the lanes and their data storage areas. This capability is required in 17 different locations throughout the software; therefore, 'NEXTLN' is justifiably an independent subroutine.

First, the origin of C030 is defined. Then the value of Accumulator A is saved. This precaution is taken because the routine requires the use of the accumulator and doesn't know its status with the main calling routine. Therefore, to avoid any possible errors, the subroutine saves the value in the stack and restores it to Accumulator A before returning from the subroutine. With the value stored, the routine sets about modifying the lane pointer.

First, the least significant byte of the current value is loaded into the accumulator. If the test to see if it is already the last lane fails, then a value of 10 hexidecimals is subtracted from it. Such a subtraction effectively shifts the pointer to the next lane data column in descending order. Having completed this, the new, least significant byte of the pointer is stored in INDEX+1, and then the complete new pointer is loaded into the index register.

Routines which use this subroutine test the carry bit to determine whether a complete set of eight lanes has been considered. So, if the series hasn't been completed, the last lane flag (carry bit) is cleared. If the last lane test described earlier is true, the flag is set by setting the carry bit. In either case, both alternatives lead to return from subroutine statements, which engages the calling routine.

In normal operation, the calling routine will arrange a loop including a JSR 'NEXTLN' statement. While a test of the clear carry bit is true, it will again call 'NEXTLN.' In this manner, all eight lanes in one direction are accessed in sequentially-descending order. When the carry bit is set by the previous call of 'NEXTLN' to indicate it has assigned the last lane address, the main routine will branch out of the loop and continue on with its other functions.

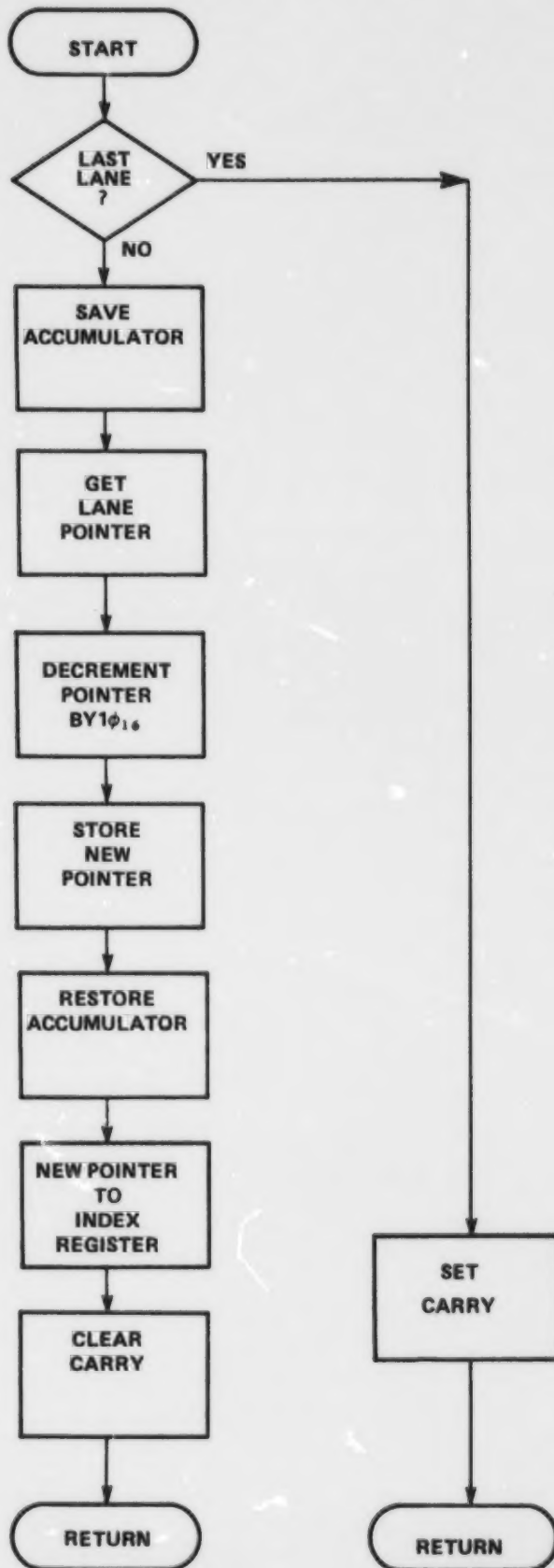
6.2.3/ Parameter Index

Routine: 'NEXTLN'

Description: Lane scan control.

Parameter	Description
INDEX+1	- the least significant byte of the index register storage area. Defines lane and data columns.
LSTLN	- a label used as the destination of a branch statement.
INDEX	- the most significant byte of the index register storage area. Defines the RAM page.

6.2.4/ Flow Chart



6.3/ 'MULT'

6.3.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 165, Line 381, extending to Line 396.

2

6.3.2/ Program Explanation

The operation for performing multiplication here is the same as performing it by long hand. Since the numbers are binary, the only choice is whether to multiply by zero or 1; multiplying by zero obviously gives a zero result, while multiplying by 1 produces the same number that you started with in the multiplicand. Therefore, binary multiplication is reduced to the following.

- If the current bit in the multiplier is 1, add the multiplicand to the partial product.
- Ensure that numbers line up correctly by:
 - shifting the multiplier left 1 bit so that the bit to be examined is placed in the carry, and
 - shifting the product left 1 bit so that the next addition is lined up correctly.

The subroutine starts in the typical manner by defining the origin which, in this case, is C9B0. Next, the accumulators are cleared, which effectively clears the product. The index register is loaded with the value eight, which dictates the number of iterations. Then the product and multiplier (TEMP04) are both shifted to the left. This procedure shifts the multiplier into the carry, and if the carry bit is 1, the product is added to the multiplicand (TEMP05) to form the new product. Once this is done, the counter, index register in this case, is decremented, and it branches back for another iteration until all eight have been completed. Upon completion, the product is stored in temporary locations TEMP06 and TEMP07 for use by the calling routine, after the execution of the return from subroutine statement.

The entire process takes between 190 and 230 μ s, depending on the number of 1 bits in the multiplier.

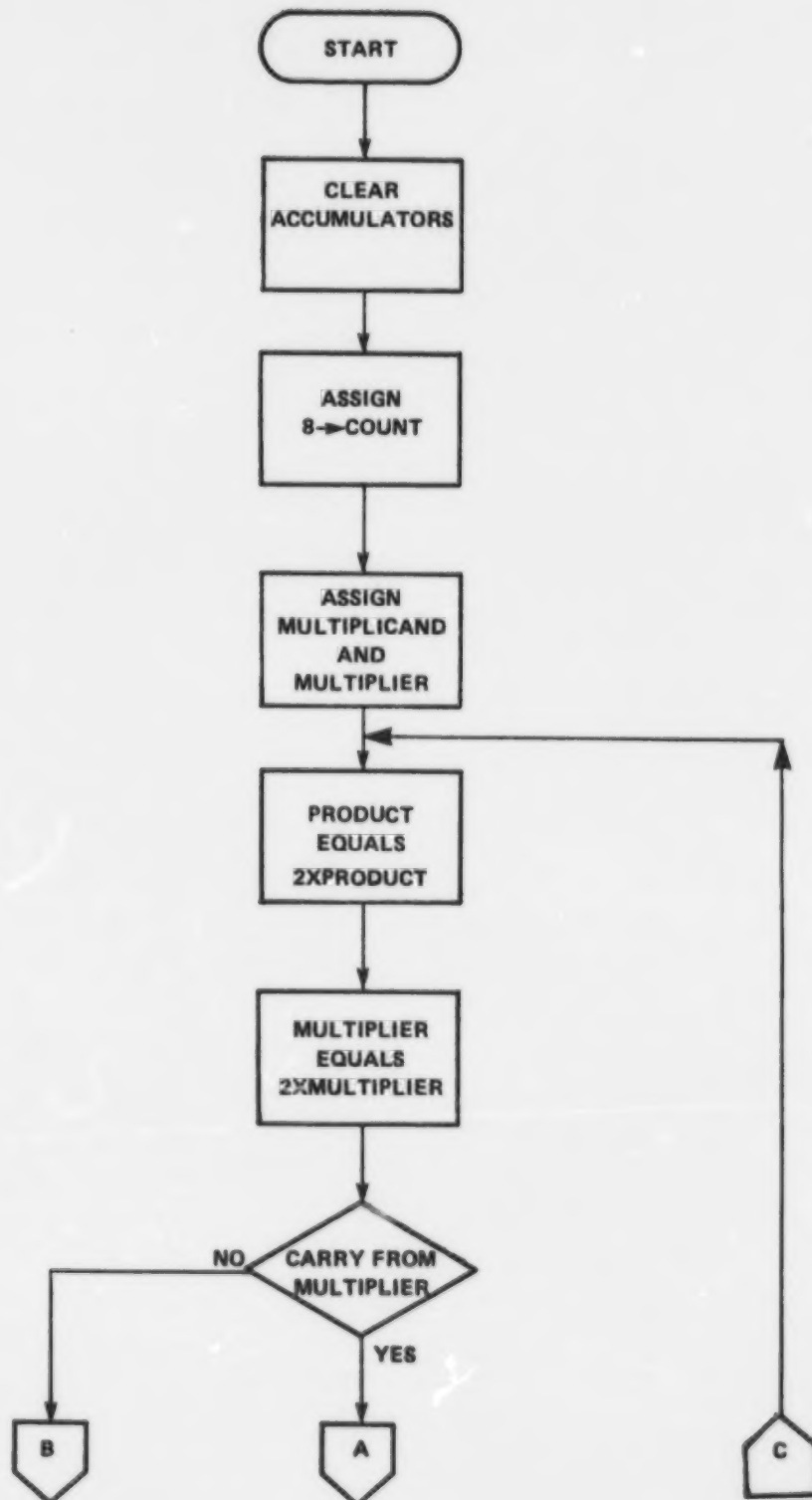
6.3.3/ Parameter Index

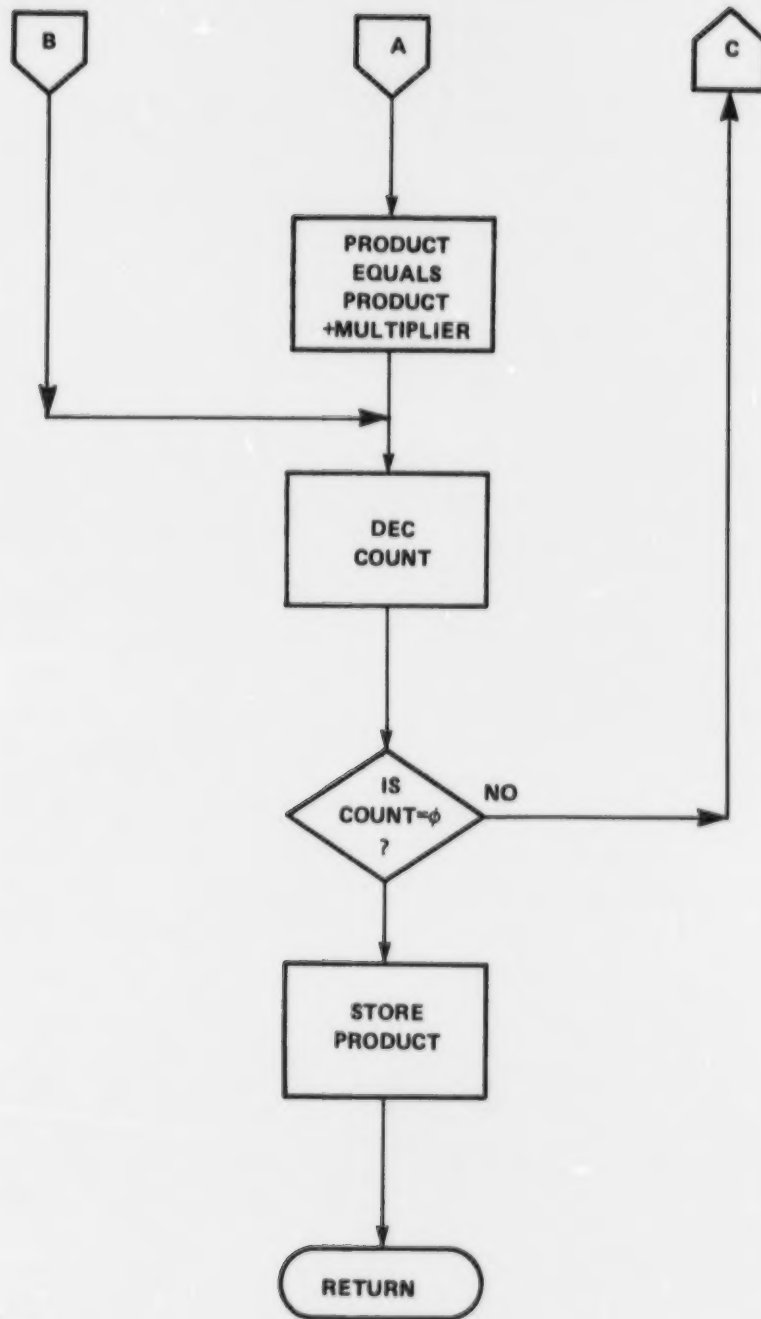
Routine: 'MULT'

Description: Provides for multiplication of two 8-bit numbers.

Parameter	Description
MM1	- a label for branch statement destination.
MM2	- a label for branch statement destination.
TEMP04	- a parameter used to store the multiplier.
TEMP05	- a parameter used to store the multiplicand.
TEMP06	- the most significant byte of the resulting product.
TEMP07	- the least significant byte of the resulting product.

6.3.4/ Flow Chart





6.4/ 'DIV'

6.4.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 165, Line 403, extending to Line 418.

6.4.2/ Program Explanation

The technique used for division in this routine is successive subtractions. Since the numbers are binary, the only question is whether the divisor can be subtracted from what is left of the dividend. If the divisor can be subtracted from the eight most significant bits of the dividend without a borrow, the corresponding bit in the quotient is 1; otherwise, it is zero.

After the familiar definition of origin, C9E0 in the case, the subroutine is initialized by setting the counter to eight and clearing the quotient. Next, the dividend (TEMP05) and quotient, temporarily in Accumulator 'A,' are shifted to line up properly. Then a trial subtraction is performed, and if there is no borrow, 1 is added to the quotient. After the counter is decremented, it is checked for zero, and depending on this outcome, the routine either branches for more iterations or stores the results. Upon completion, the quotient resides in TEMP06, and the remainder in TEMP07. In these locations, the calling routine can access the results when the subroutine's control is relinquished via a return from subroutine statement.

This subroutine takes between 170 and 210 μ s to perform a division, depending upon the number of 1 bits in the quotient.

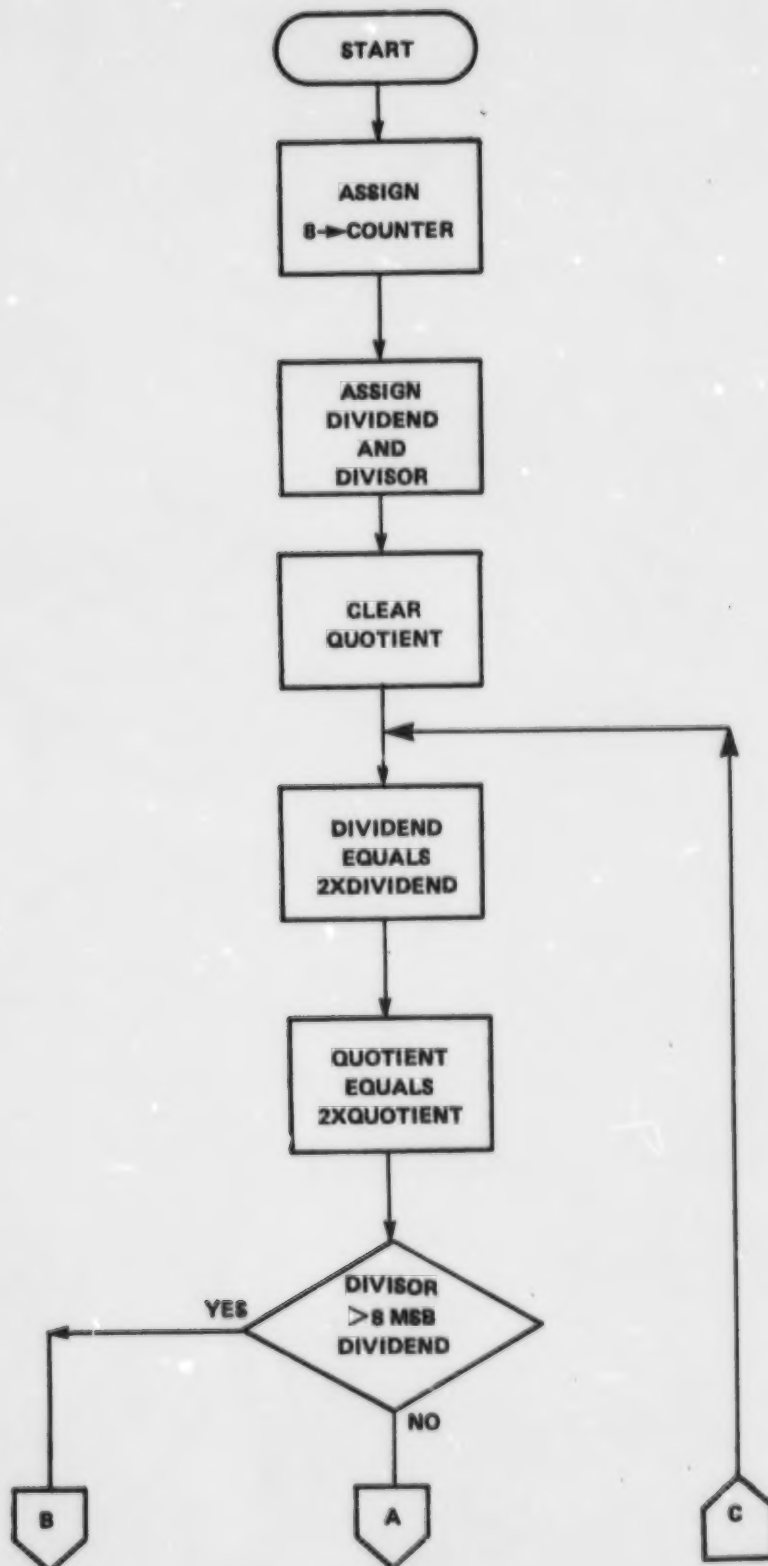
6.4.3/ Parameter Index

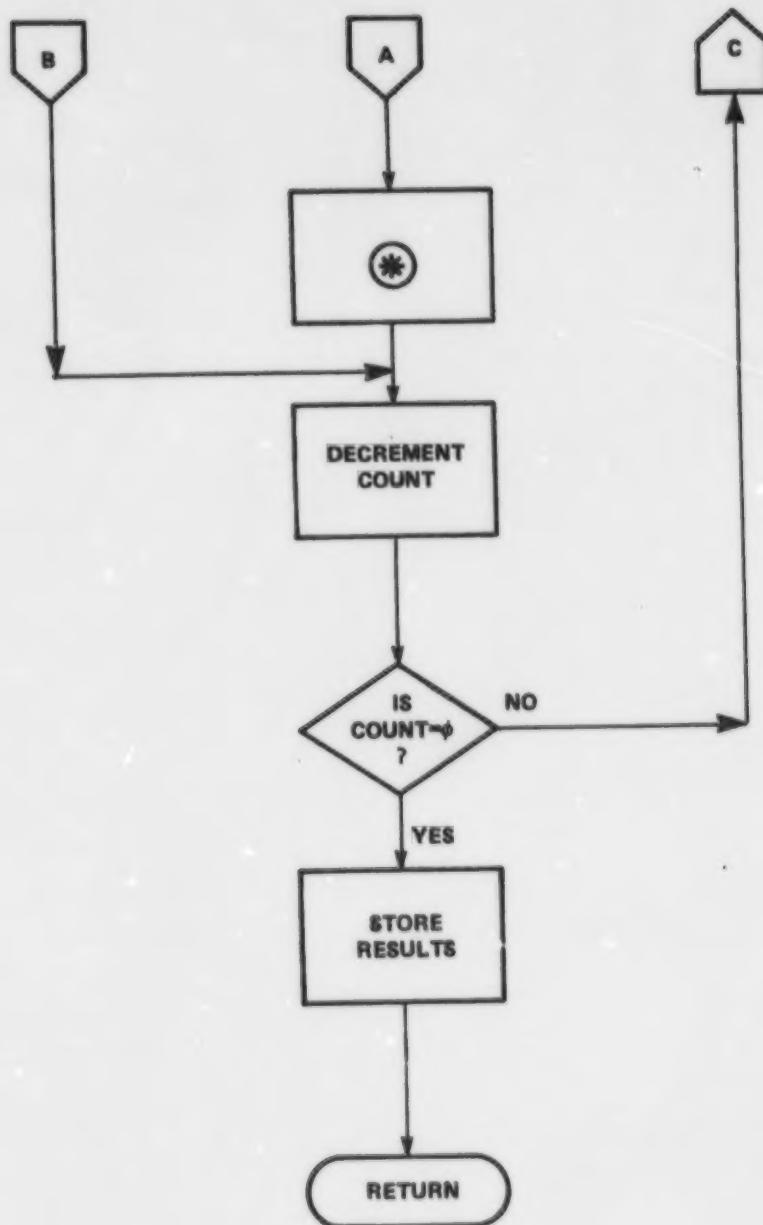
Routine: 'DIV'

Description: Provides for division of two 8-bit numbers.

Parameter	Description
MD1	- a label for branch statement destination.
MD2	- a label for branch statement destination.
TEMP04	- a variable for temporary assignment of the divisor.
TEMP05	- a variable for temporary assignment of the dividend.
TEMP06	- temporary storage area for the quotient.
TEMP07	- temporary storage area for the remainder.

6.4.4/ Flow Chart





8 MSB_s OF DIVIDEND = 8 MSB_s OF DIVIDEND - DIVISOR
QUOTIENT = QUOTIENT + 1

6.5/ 'CMP16'

6.5.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 162, Line 219, extending to Line 234.

6.5.2/ Program Explanation

During the various computations involved in determining the PCS functions, it is necessary to compare 16-bit numbers. This subroutine is a generalized routine for doing such comparisons.

After the familiar introduction by defining the origin, C000, the accumulator is stored to ensure error-free operation upon return to the calling routine. Then the MSB of one of the numbers is loaded into the accumulator using index mode. Next, it is compared to the MSB of the second number which has been previously assigned to TEMP02. If the indexed byte proves to be larger than TEMP02, then the carry bit is set; if less, the carry bit is cleared. On the other hand, if they prove to be equal, then the LSB is compared with similar results as above.

The results of the comparison are transferred to the calling routine via the carry bit. The carry bit will be set if the indexed 16 number is greater than that stored in TEMP02,03. Otherwise, the carry bit will be cleared.

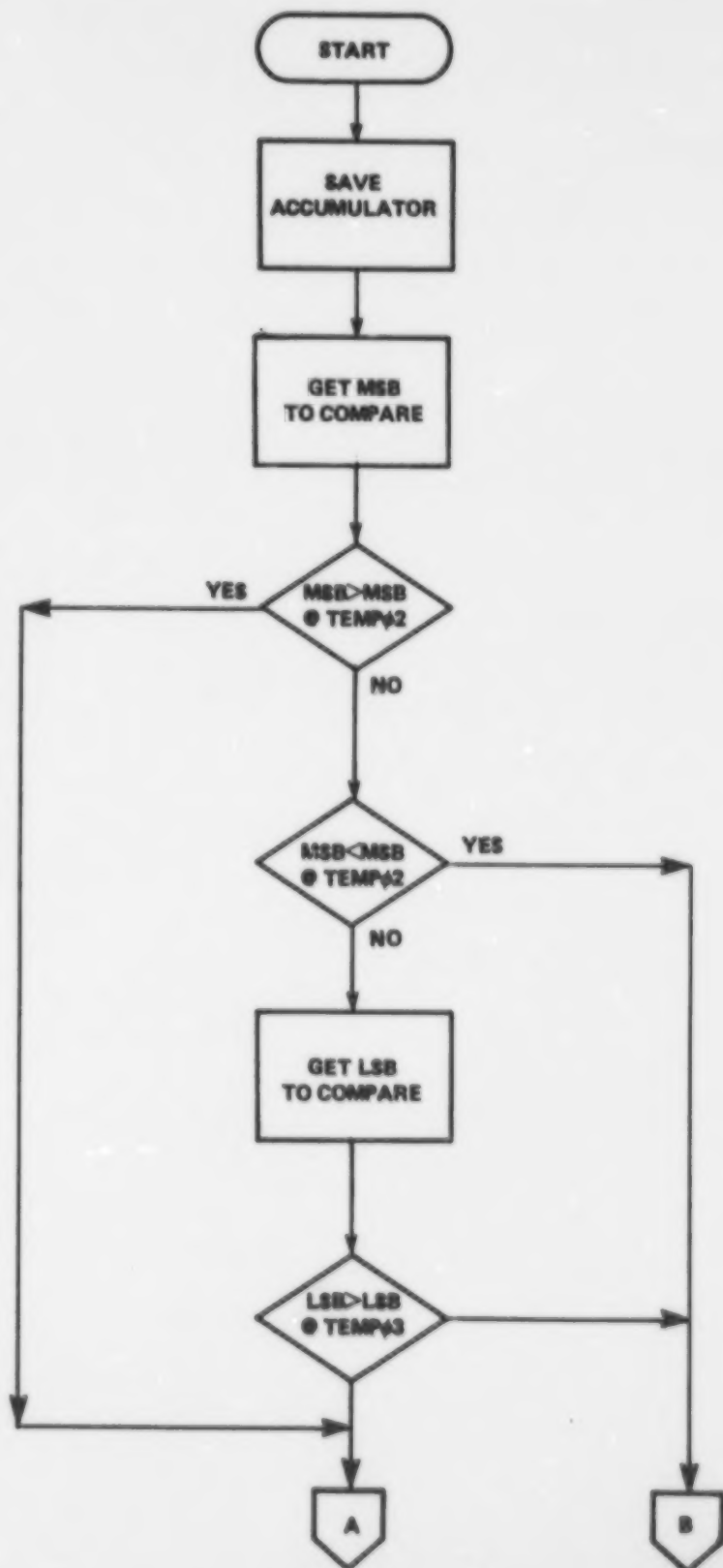
6.5.3/ Parameter Index

Routine: 'CMP16'

Description: A generalized subroutine to compare two 16-bit numbers.

Parameter	Description
TEMP02	- storage for the MSB of one of the numbers to be compared.
TEMP03	- storage for the LSB of one of the numbers to be compared.
ONEBIG	- the destination for a branch statement when the TEMP02,03 variable is smaller.
ONESML	- the destination for a branch statement when the TEMP02,03 variable is larger.

6.5.4/ Flow Chart





6.6/ 'PRPRT/PRPRT8'

6.6.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 164, Line 395, extending to Line 353.

6.6.2/ Program Explanation

1/ Theory¹

For any number N:

$$(29/30)N = N - N(4/128) = N - 4(N/128)$$

and:

$$(9/10)N = N - N(13/128) = N - 13(N/128).$$

For a binary number, dividing by 128 corresponds to a shift of 7 bits toward the least significant digit. Then $N(1 - 4/128)$ would be accomplished by shifting N right 7 bits and then subtracting the result from N four times.

Alternatively, the proportioning might be done as follows:

$$N - 4(N/128) = N - N/32$$

or simply a 5-bit shift towards the least significant digit. Using this method for proportioning 9/10 of a number:

$$\begin{aligned} N - 13N/128 &= N - N(1/128 + 4/128 + 8/128) \\ &= N - (N/128 + N/32 + N/16) \end{aligned}$$

where dividing by 32 is a 5-bit shift and dividing by 16 is a 4-bit shift.

2/ Implementation

It will be noted that only one subtraction for each bit shift would be necessary for any proportion of 1/128. In the above example, a subtraction is made with the number shifted 4 bits, another shifted 5 bits and the third subtraction after shifting 7 bits. Since only one subtraction is made for each fractional part of the original number, a binary proportion control word can be set to vary the proportion of the original number the result is to be.

If each bit of the proportion control word represents an individual fractional part, any proportion can be represented in a binary coded, 7-bit word. Since 8 bits are available, fractional parts of 256 can be used.

¹Developed by Caltrans District 11, 1979.

Proportion Control Word

Bit #	7	6	5	4	3	2	1	0
Fractional Part	1/2	1/4	1/8	1/16	1/32	1/64	1/128	1/256

An example of reproportioning a number to 9/10 of its original value follows. Since $9/10 = 1 - \frac{26}{256}$, the Bits 0, 3 and 4 would be set in the proportion control word (PCW). The PCW can then be shifted left 1 bit at a time into carry. Whenever carry is set, the original number is shifted and subtracted from the original value. If the bit shifted to carry is not set, the original number is shifted only.

It should be noted that subtracting the largest fraction yields better resolution. For instance, suppose that the value to be reproportioned is 250, and the proportion wanted in the result is $9/10 = 1 - \frac{26}{256}$. The result should be about 224.61. Suppose 1/256 of the original value is subtracted 26 times. The fraction 250/256 is less than 1, so when a subtraction is made (250-0), the result remains 250. If, 2/256 of the original value is subtracted 13 times instead, the result would be 250 - 13, or 237. If the largest fractional parts are subtracted out in succession, i.e., 16/256, 8/256 and 2/256, the result is:

$$250 - 16 - 8 - 2 = 224$$

This is much closer; in fact it only varies 0.9% from the actual value.

Even better resolution can be obtained by 'rounding off' the successive subtractions. Suppose that when the number is shifted to obtain the fraction to be subtracted, the bit shifted to carry is set. This means that the portion shifted out of the word is at least 1/2 of the least significant bit. Then to round the subtraction off, the original word is decremented. In the above example:

$$250 - 16 - 1 - 8 - 1 - 1 - 1 = 224$$

Shifting the PCW left instead of right allows the value placed in it to be the number of 1/256 to be subtracted from the original value. For

example, if $PCW = 10_{10} = 1010_2$, the PCW will direct subtraction of $1/32(8/256)$ and $1/128(2/256)$ or $10/256$ from the original value.

6.6.3/ Parameter Index

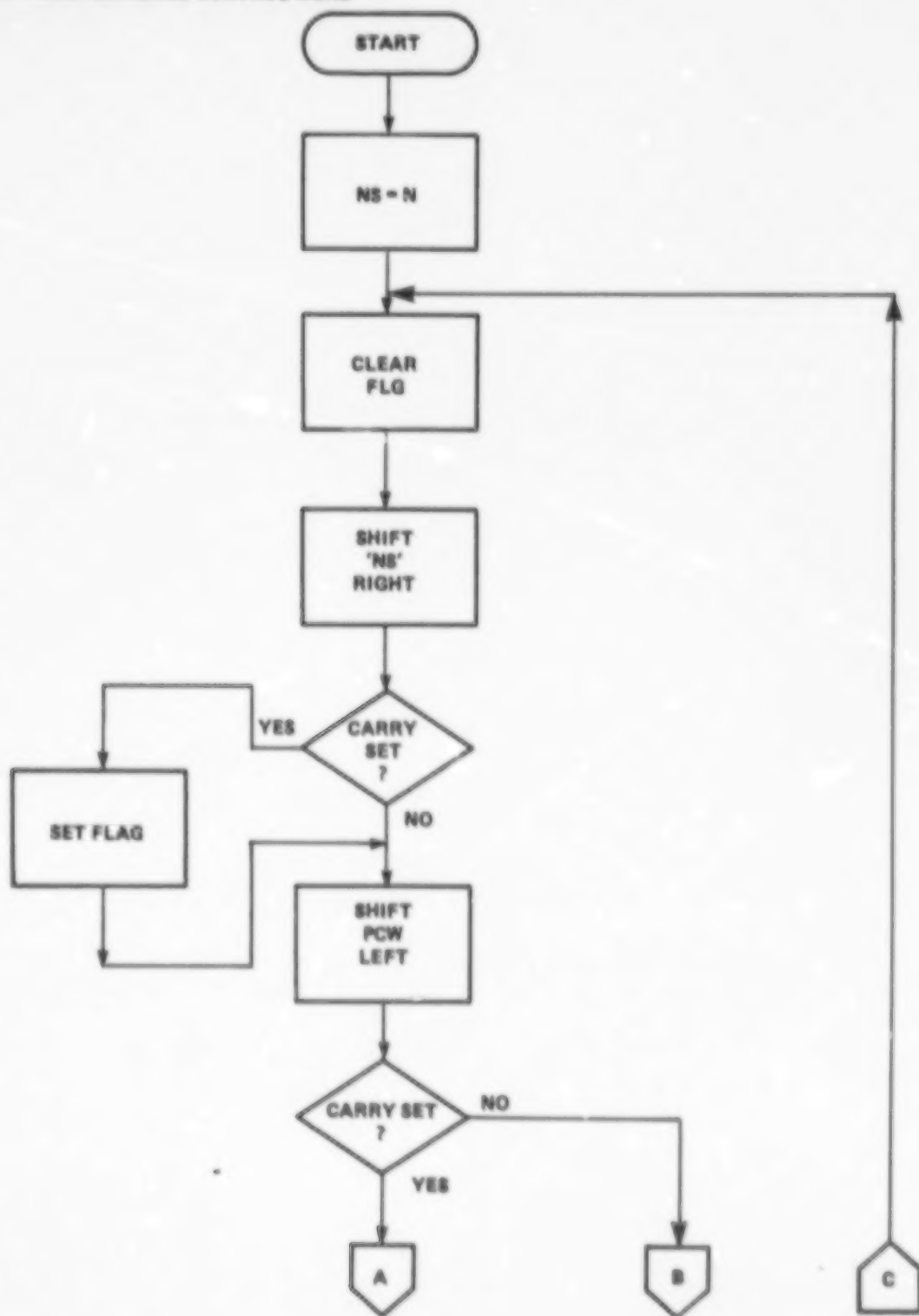
Routine: 'PRPRT/PRPRT8'

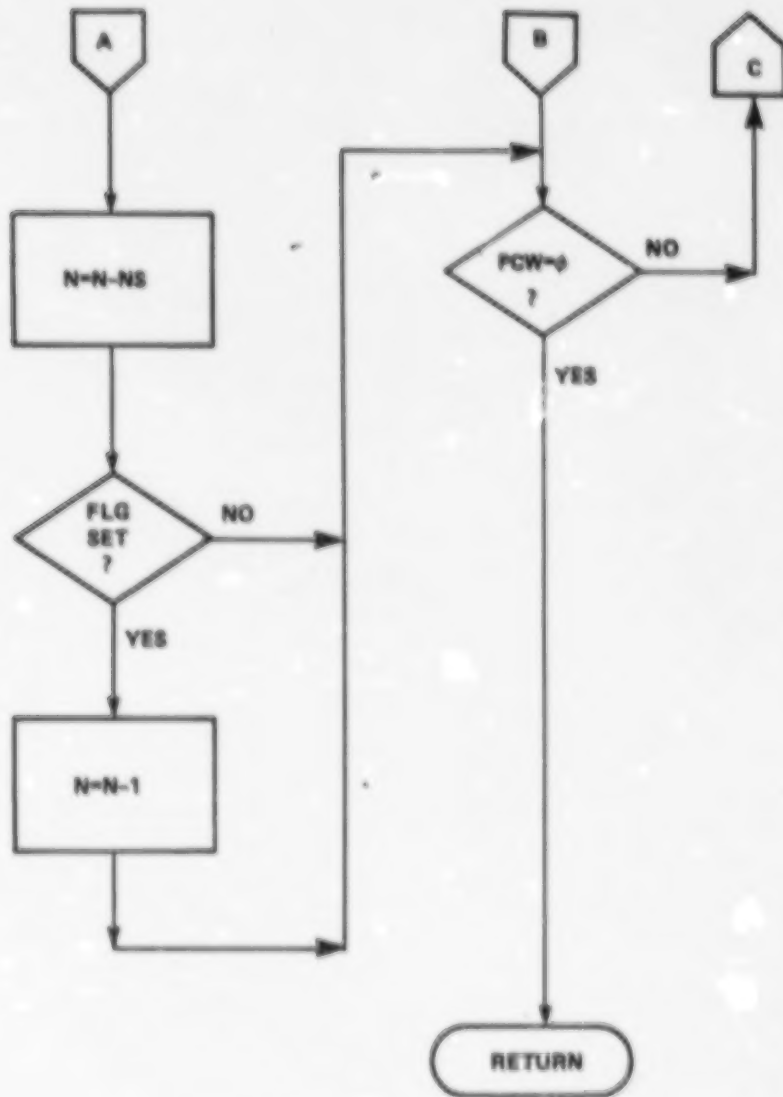
Description: Proportions 8 or 16 bits to provide pseudo running totals.

Parameters	Description
CHECK	- label for destination of branch statement.
AGAIN	- label for destination of branch statement.

6.6.4/ Flow Chart

N = ORIGINAL VALUE
NS = SHIFTED 'N'
FLG = ROUND OFF FLAG
PCW = PROPORTIONED CONTROL WORD





6.7/ 'INIT'

6.7.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 166, Line 436, extending to Line 725.

6.7.2/ Program Explanation

The initialization routine serves three functions:

- 1/ to zero memory,
- 2/ to define and calculate variables, and
- 3/ to output the first header.

Zeroing memory is rather a simple process. Basically it defines the boundaries in memory to be \$88 and \$7DF, and then steps through and clears addresses while incrementing the lower boundary condition. The lower boundary condition is set at \$88 so as not to disturb the communications portion of Page 0. The upper boundary is arbitrary.

Before getting into the section dealing with variable definitions, the lane disable variables are set. Scanning through 'LDNW1' downstream description byte for Direction 1 bit by bit, it is determined whether or not the lane is equipped with such a detector. If it is, in which case a '1' is found in that bit position, then the 'LNDIS1,' lane disable, function for that particular lane is cleared. Otherwise, the lane's binary bit position is entered as that of the lane disable parameter. This operation is repeated for Direction 2. When this is completed, it allows any of the lane and/or lane data scanning routines to determine whether any particular lane or data area is eligible for consideration.

The section for variable definition, which appears next, does as its name implies. Variables are transferred, cleared, initialized and generally conjured up. The function of any variable here may be found in the 'Parameter Index' (Section 6.7.3.). The latter two-thirds of the section deals with assigning the speed comparison and lane default values. Then the program gets into variable computation.

In order to store the various types of data, it must be determined how much space and, therefore, where the data pointers should be located. The process starts by counting the number of non-zero volume count descriptors and multiplying the sum by 2. This defines the space required for the storage of both value and long vehicle counts for 1 h, since each non-zero descriptor indicates a most and least significant

byte-sum to be stored. With the hourly requirements satisfied, the quantity is multiplied by 24 and stored as the length of the first day volume buffer (VOBUF1, VOBUFF1+1). Since the length of buffer required per day is now known, a simple multiplication by 5 gives us the maximum storage requirements. This new value, offset by \$0400, gives us the pointer to the start of the long vehicle count buffer. Next, in three distinctive groups, all the pointers are initialized, followed with output of the initial headers for volume, length and speed, before returning to the calling routine.

6.7.3/ Parameter Index

Routine: 'INIT'

Description: System initialization.

Parameter	Description
TEMP01	- temporary storage location used in varied applications.
TEMP02	- temporary storage location used in varied applications.
LDNW1	- downstream lane descriptor byte for Direction 1.
LDNW2	- downstream lane descriptor byte for Direction 2.
LNDIS1	- lane disable byte. A non-0 value indicates the lane is unused.
DTCTRM	- MSB detector enable mask. (Bits match 'DETINM,' detectors; 1 allows controller to see detector.)
LDESW1	- upstream lane descriptor byte in Direction 1 (Bit 0 = 1 for Lane 1 detector, for example.)
LDNW2	- downstream lane descriptor byte in Direction 2.
DTCTRL	- LSB of detector enabling mask.

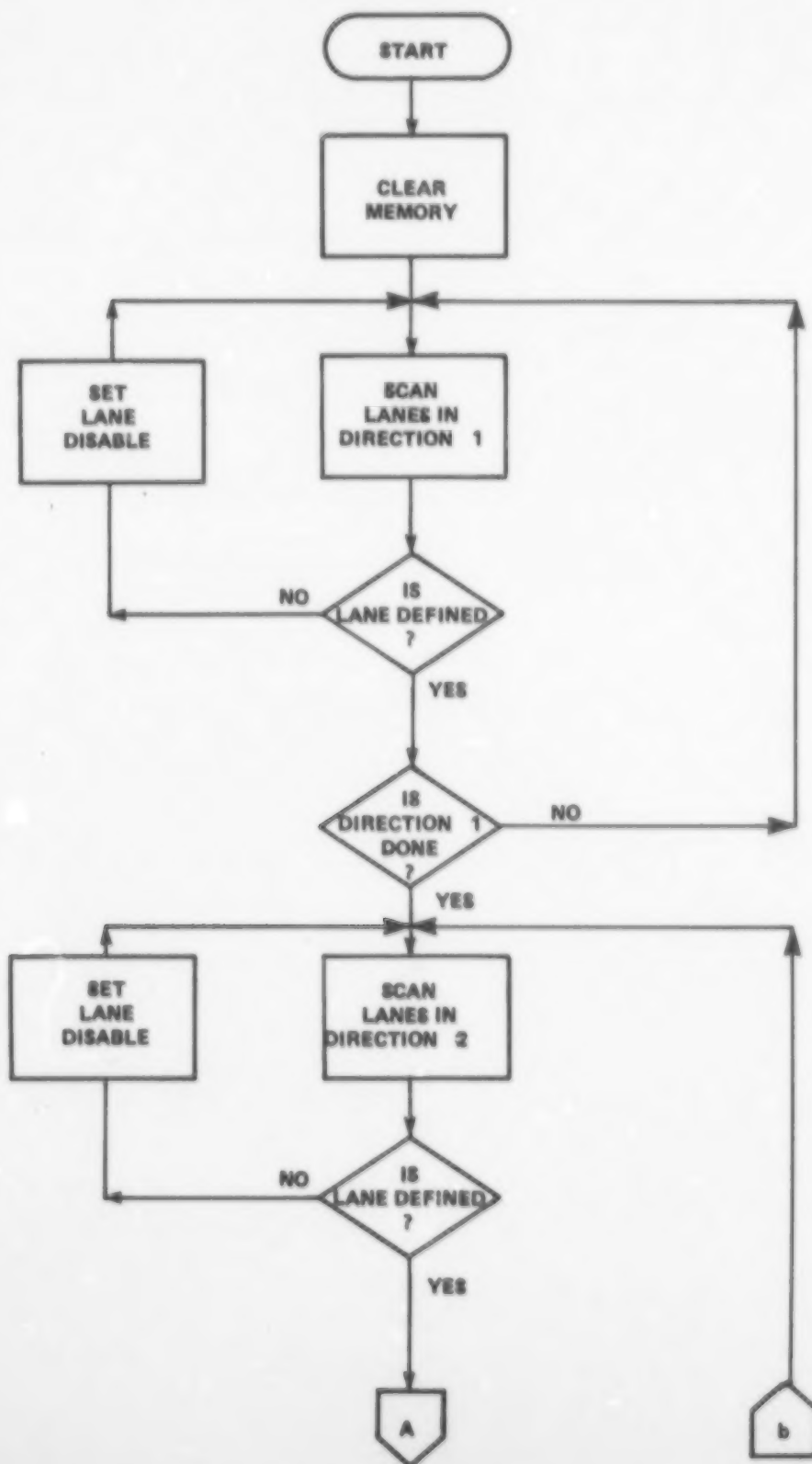
Parameter	Description
LD SW2	- upstream lane descriptor byte in Direction 2.
VOL DAY	- number of days volume data collected.
COUNT4	- a temporary storage location used in varied applications.
SPD DAY	- number of days speed data collected.
LEN DAY	- number of days length data collected.
CYCLE	- a counter used to allocate address of day's pointer in circular transmit buffer.
KAY1	- flag to clear lane detector areas for Direction 1.
KAY2	- flag to clear lane detector areas for Direction 2.
PCW1	- proportion control word for 1 min data. (Set to '1A' [26/256] for 1 min).
VOBUF1	- length of an individual day's volume buffer.
SPDAY1	- pointer to the beginning of the speed buffer.

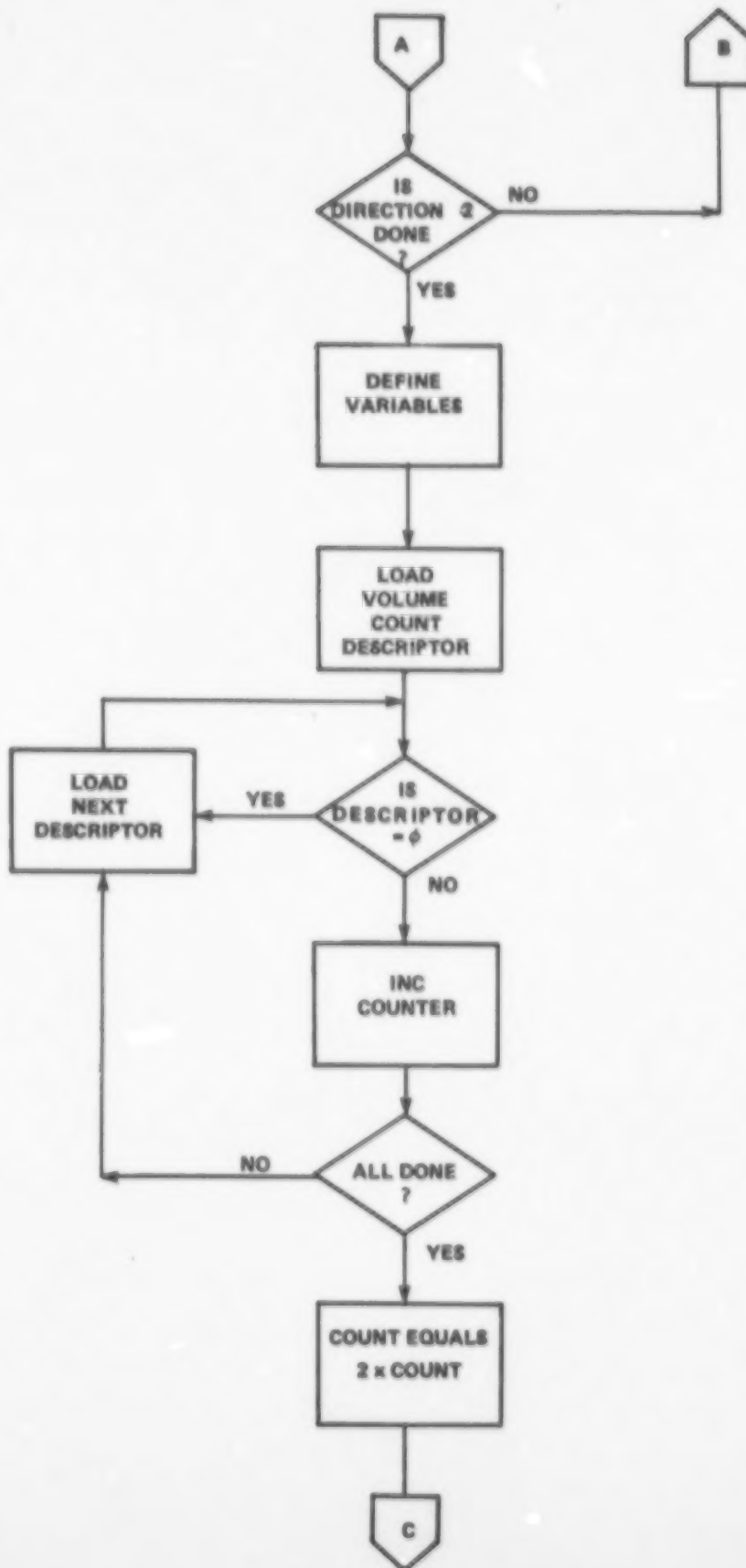
Parameter	Description
SPBUF	- length of an individual day's speed buffer.
OC10CM	- error threshold value for 1 min detector occupancy.
SPEED	- initial speed buffer pointer at 0300.
TRUCK	- threshold value for discriminating and classifying measured vehicle lengths.
DAYMAX	- the maximum number of days of data allowed within given memory size.
SPD	- base location for the MSB of converted speed classifications.
LS	- base location for individual lane's centre to centre loop spacing in Direction 1.
LSA	- base location for individual lane's centre to centre loop spacing in Direction 2.
LD	- base location for individual lane's loop dimension in Direction 1.
LDA	- base location for individual lane's loop dimension in Direction 2.
VOLDW1	- count descriptor byte for Volume 1.

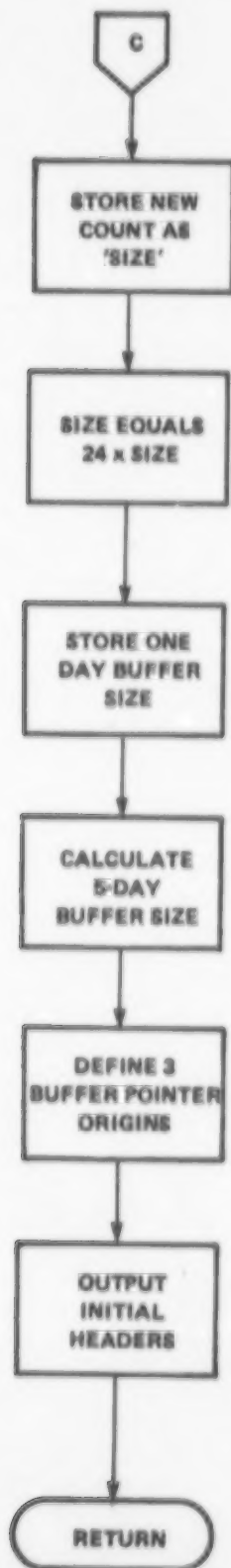
Parameter	Description
SIZE	- amount of memory space required to store all volume counts in both directions for 1 h.
MULT	- reference to the subroutine for multiplication.
TEMP03	- a temporary storage area used for varied applications.
TEMP04	- a temporary storage area used for varied applications.
TEMP05	- a temporary storage area used for varied applications.
TEMP06	- a temporary storage area used for varied applications.
TEMP07	- a temporary storage area used for varied applications.
LENGTH	- initial length buffer pointer.
LNBUF1	- length of an individual day's length buffer.
START	- initial volume buffer pointer at 0400.
VODAY1	- pointer to beginning of the volume buffer.
WW	- same as 'VODAY1' but to be assigned a storage location in communications area.

Parameter	Description
PTR	- pointer to beginning of volume data.
VODAYL	- pointer to beginning of current day's length buffer.
LNDAY1	- pointer to beginning of length's transmit buffer.
PTRL	- pointer to beginning of length data.
VODAYS	- pointer to beginning of current day's speed buffer.
PTRS	- pointer to beginning of speed data.
YEAR	- current calendar year (BCD).
MONTH	- current calendar month (BCD).
DAOFMO	- current day of the month (BCD).
DAOFWK	- current day of the week (BCD).

6.7.4/ Flow Chart







6.8/ 'HEADER'

6.8.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 168, Line 746, extending to Line 919.

6.8.2/ Program Explanation

Prior to providing the headers on day changes, this routine looks after the transfer of speed information as well. It does so by indexed addressing of the 'SPED,' accumulated days speed information, and placing it in the speed transmit buffer. Since there are 12 classifications defined in the speed requirement, the process is repeated 12 times. It should be noted that 3 bytes are transferred for every speed group (format details in Section 3.3); hence, the 'SPED' address can be seen to be offset by two different hexadecimal values. Upon completion of the speed data transfer, the rest of the routine concerns itself with setting buffer pointers and providing headers.

The header information, and data for that matter, are arranged in circular buffers. This is accomplished by initializing the buffer pointer to a known location ('INIT' routine, Section 6.7.2) and then systematically incrementing the data and headers through memory until the maximum number of days to be stored is reached. Then the information overlays itself, generating the circular format. An illustration of the process may be seen in Figure 6.1. Recalculating the buffer pointers is straightforward, since the present position is always used and the buffer length required is known; therefore, the new pointers are the result of a simple summation. The variable 'CYCLE' keeps track of the number of days stored relative to the defined maximum, and when the limit has been reached, it directs the pointers to the beginning of the buffer for another cycle. This function should not be confused with 'VOLDAY' which keeps track of the number of days of data available at any given time. Under normal operation, 'VOLDAY' will increment daily up to the maximum number of days to be stored, retaining this value until the system is reset.

Once the buffer points have been established, it is a simple matter of reading the date time information and outputting these four functions in three different headers. Control is then granted to the calling routine with an RTS statement.

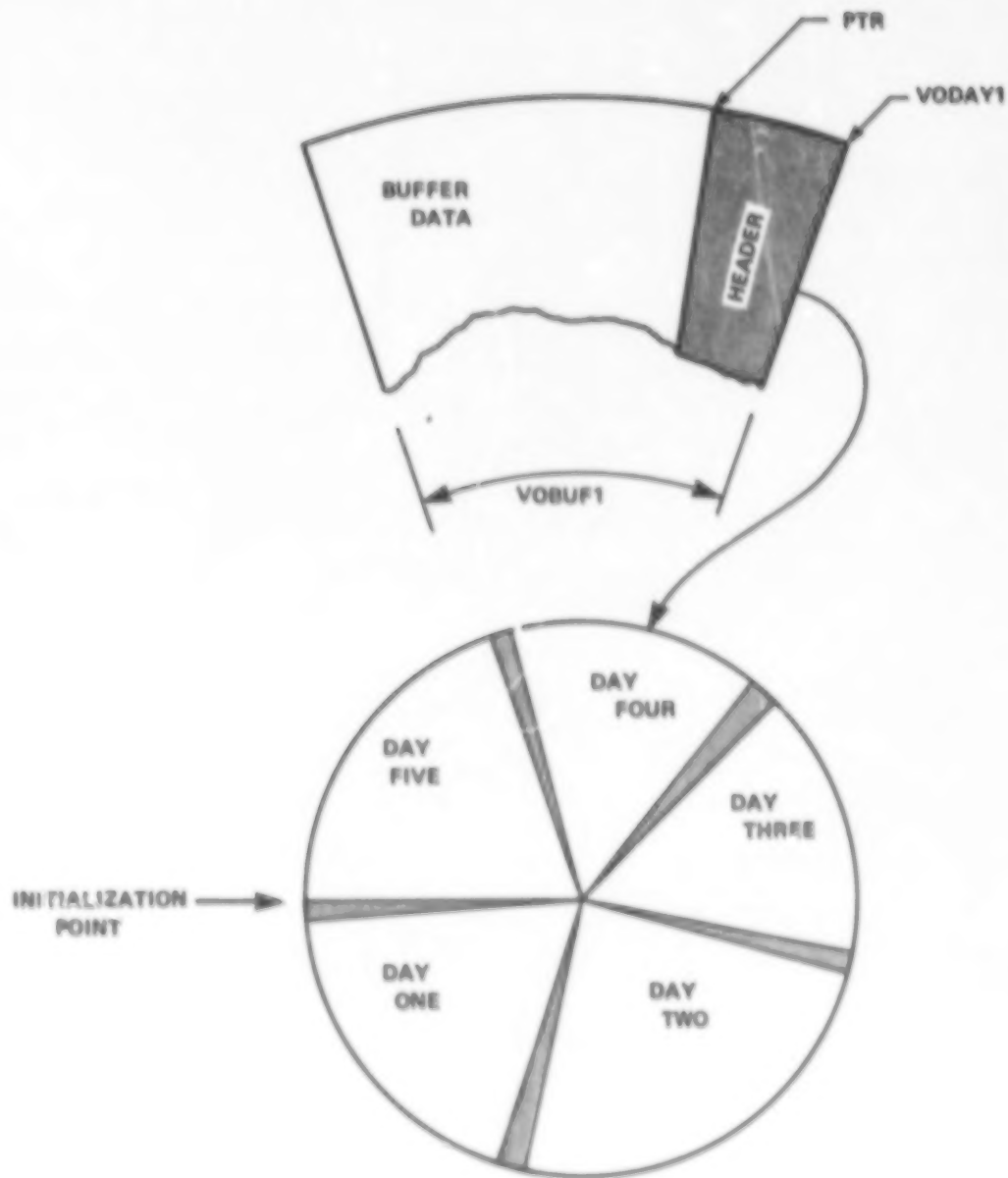


Figure 6.1/ Typical Five-Day Buffer Structure

6.8.3/ Parameter Index

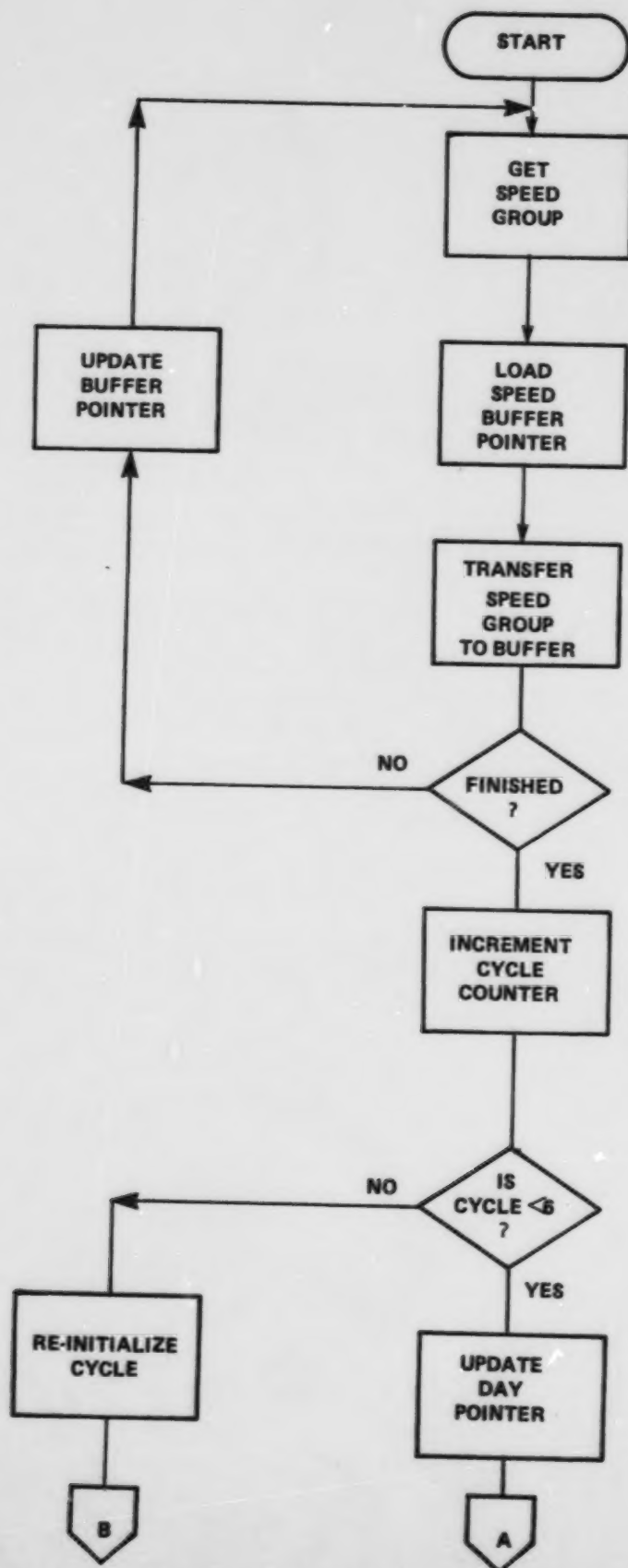
Routine: 'HEADER'

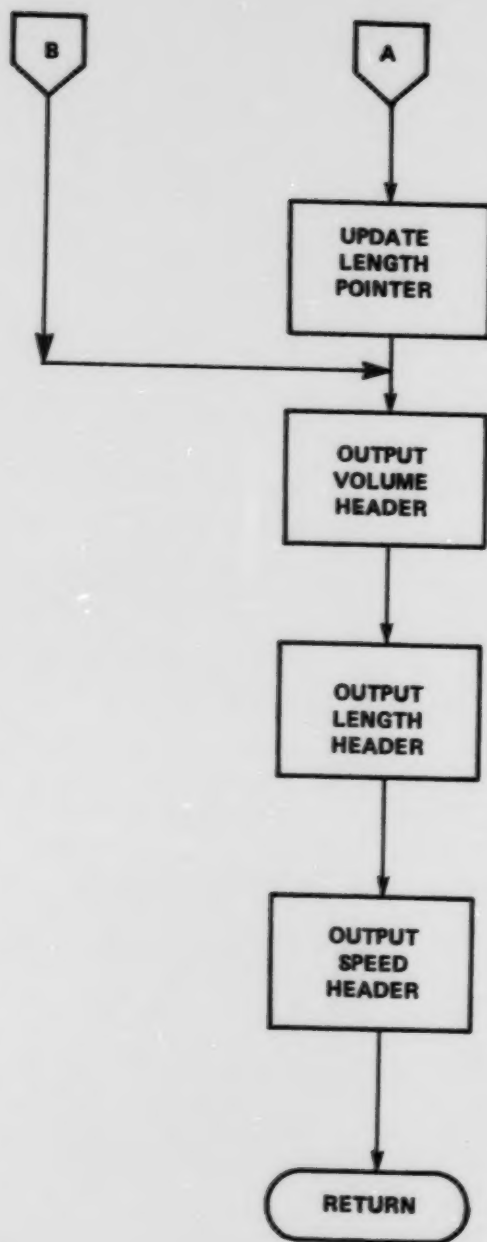
Description: Speed output and header control.

Parameter	Description
TEMP03	- a temporary storage area used in varied applications.
TEMP06	- a temporary storage area used in varied applications.
SPED	- a temporary base address for the classified daily speed data.
PTRS	- pointer to beginning of speed data.
TEMP07	- a temporary storage area used in varied applications.
CYCLE	- a parameter used to control the cycling of the circular buffers.
VOLDAY	- number of days volume data collected.
SPDDAY	- number of days of speed data collected.
LENDAY	- number of days of length data collected.
BEGIN	- label for destination of branch statement.

Parameter	Description
VODAY1	- pointer to beginning of day's volume buffer.
VOBUF1	- length of an individual day's volume buffer.
PTR	- pointer to beginning of volume data.
VODAYL	- pointer to beginning of current day's length buffer.
PTRL	- pointer to beginning of length data.
VODAYS	- pointer to beginning of current day's speed buffer.
START	- initial volume buffer pointer at 0400.
LENGTH	- initial length buffer pointer.
SPEED	- initial speed buffer pointer at 0300.
YEAR	- current calendar year (BCD).
MONTH	- current calendar month (BCD).
DAOFMO	- current day of the month (BCD).
DAOFWK	- current day of the week (BCD).

6.8.4/ Flow Chart





6.9 'INPUT'

6.9.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 171, Line 945, extending to Line 1028, which includes both directions.

6.9.2/ Program Explanation

This, the 'INPUT' routine, is one of the most important operations of all the software, since without fast accurate detector sampling, the rest of the process is pointless. The first step is to set up the MSB of the port addresses, which is hexadecimal 50. In PCS, the four ports used to accommodate 32 lanes are 5001, 5002, 5003 and 5006. Having defined part of the port address, the detector input areas and pointers are then cleared to ensure the integrity of the process. Next, the detector hardware assignment table is consulted.

The object of the table is to supply the input port number, the second byte to match 50 already supplied, and the bit position within the port for any and all the 32 detectors. The processing portion of the program can step through the table to the addressing details for any detector, plus acquire a reference byte for comparison to determine whether the detector is, in fact, occupied. In fact, that is how the main body of the program functions.

Once the pointer to the hardware assignment table has been established, and the port defined and accessed, the information is checked against that detector's reference byte. Negative results initiate a similar test of the next lane with reassigned pointers, while a positive result allows this detector to be added to the list of currently unverified detector inputs. The subject of data verification is treated in 'PCS2.' Next, as in the negative case, detector position bits are repositioned, tests are done to determine the status of the input sampling process and more detectors are sampled, if appropriate.

Upon completion of these tasks, the routine terminates and relinquishes control to the calling routine. This leaves the system with a list of detectors which are, and are not, occupied.

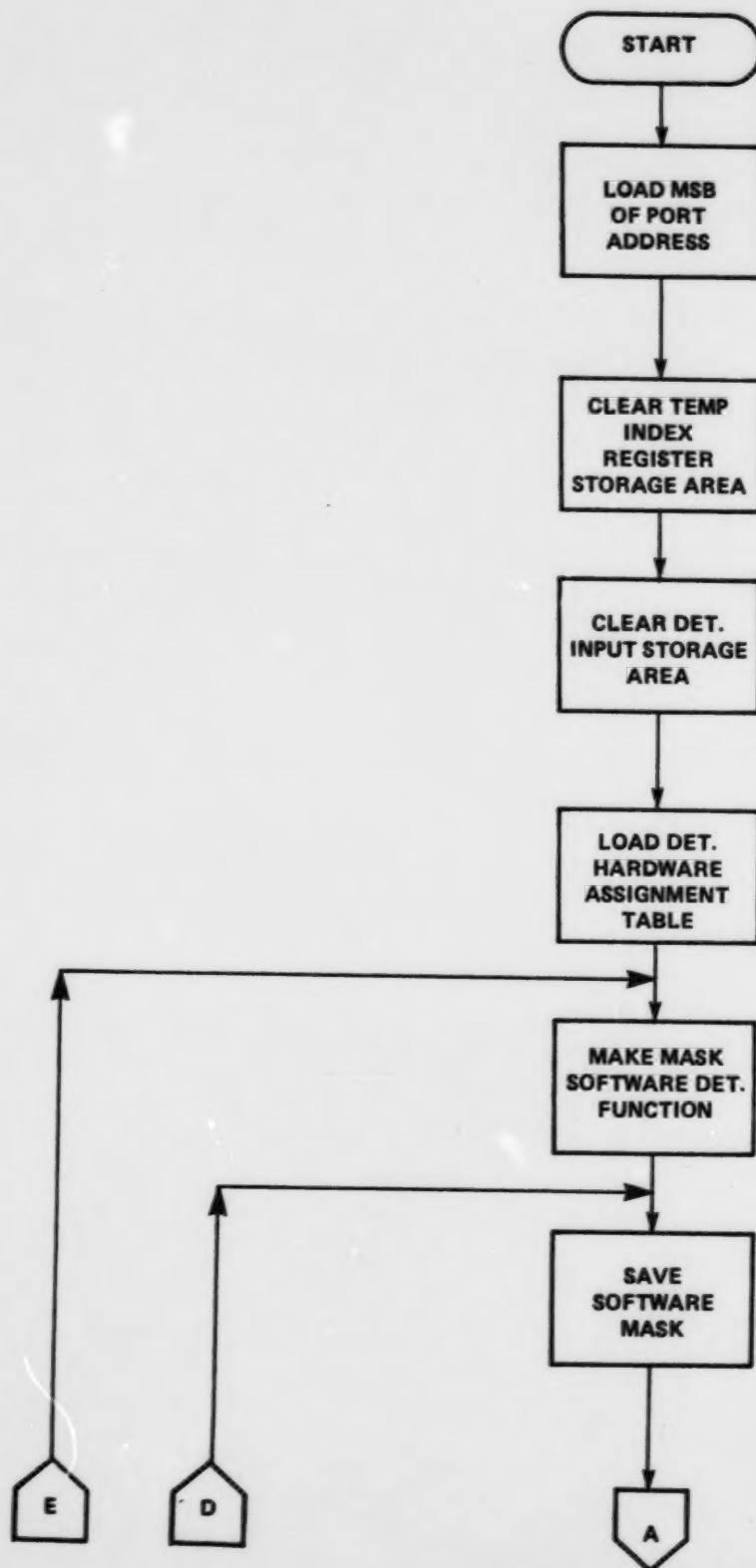
6.9.3/ Parameter Index

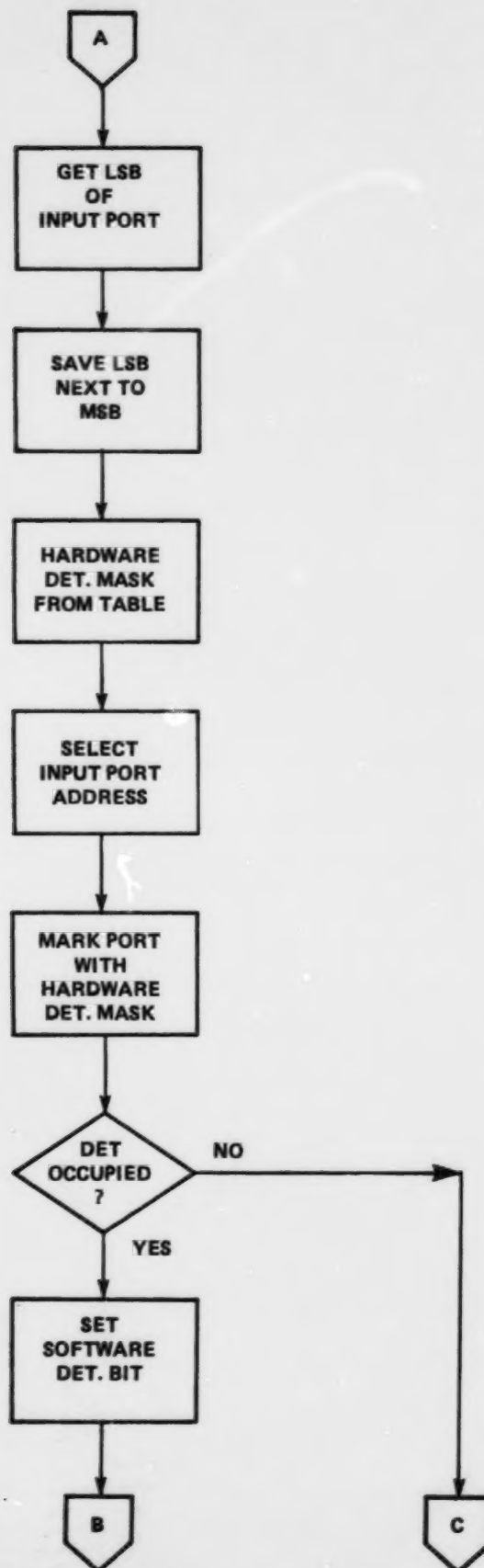
Routine: 'INPUT'

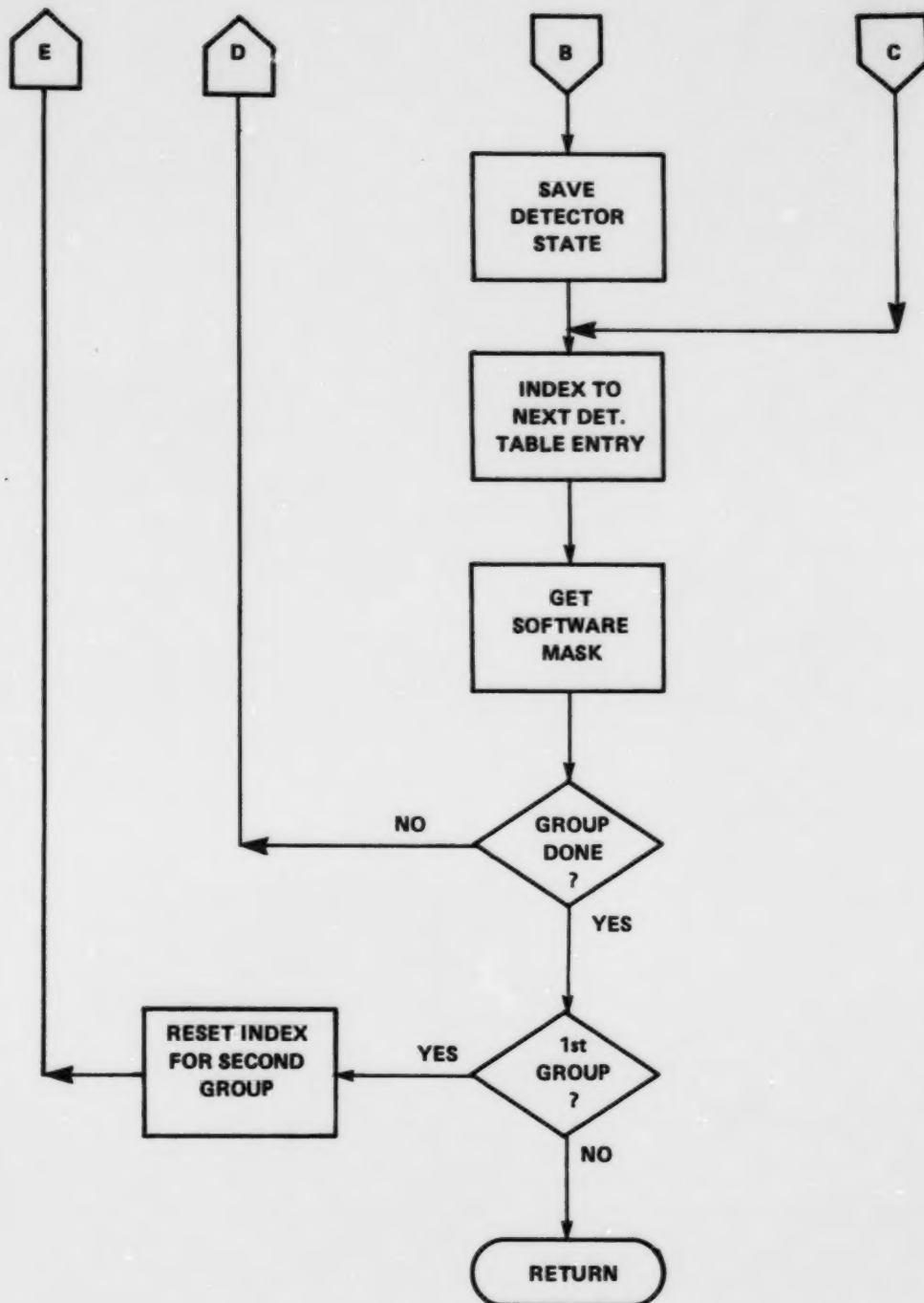
Description: Detector input scan control.

Parameter	Description
TEMP01	- a temporary storage area used for varied applications.
INDEX	- a variable used for the storage of the software detector index.
DATA0M	- MSB of current unverified detector data.
DTRTBL	- label for detector hardware table.
TEMP04	- a temporary storage area used for varied applications.
TEMP02	- a temporary storage area used for varied applications.
NXTDET	- branch destination for next lane consideration.
DTCTRM	- MSB of detector enable mask.
IPT2	- label for branch destination.
DONE	- label for branch destination.
IPT1	- label for branch destination.

6.9.4/ Flow Chart







6.10/ 'PCS2'

6.10.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 183, Line 1911, extending to Line 1962, which includes both directions.

6.10.2/ Program Explanation

This single error correction is a logical process which discriminates all incoming signals from both 'INPUT' and 'INPUTT.' The purpose of the sequence is to ensure that spurious data detector changes don't filter through as valid data. For example, a valid vehicle start is represented by a sequence of three data samples, such as low, high, high. In the same manner, a valid vehicle end is represented by high, low, low. Any other sequence represents either no or an invalid change (Figure 6.2). As a result of this process, the unverified data provided by the input routines are either accepted or disqualified by the verification routine. If accepted, the appropriate state change bits are set to form a very effective technique for eliminating erroneous input data.

DATA ϕ = C CURRENT DETECTOR DATA (DATA ϕ M, DATA ϕ L)
 DATA 1 = B NEXT MOST CURRENT DETECTOR DATA (DATA1M, DATA1L)
 DATA 2 = A 2nd FROM CURRENT DETECTOR DATA (DETINM, DETINL)

VERIFIED DETECTOR DATA = $B_c = (A \oplus B \cdot B \oplus C) \oplus B$
 STATE CHANGE DATA = $S_t = (A \oplus C \cdot A \oplus B)$

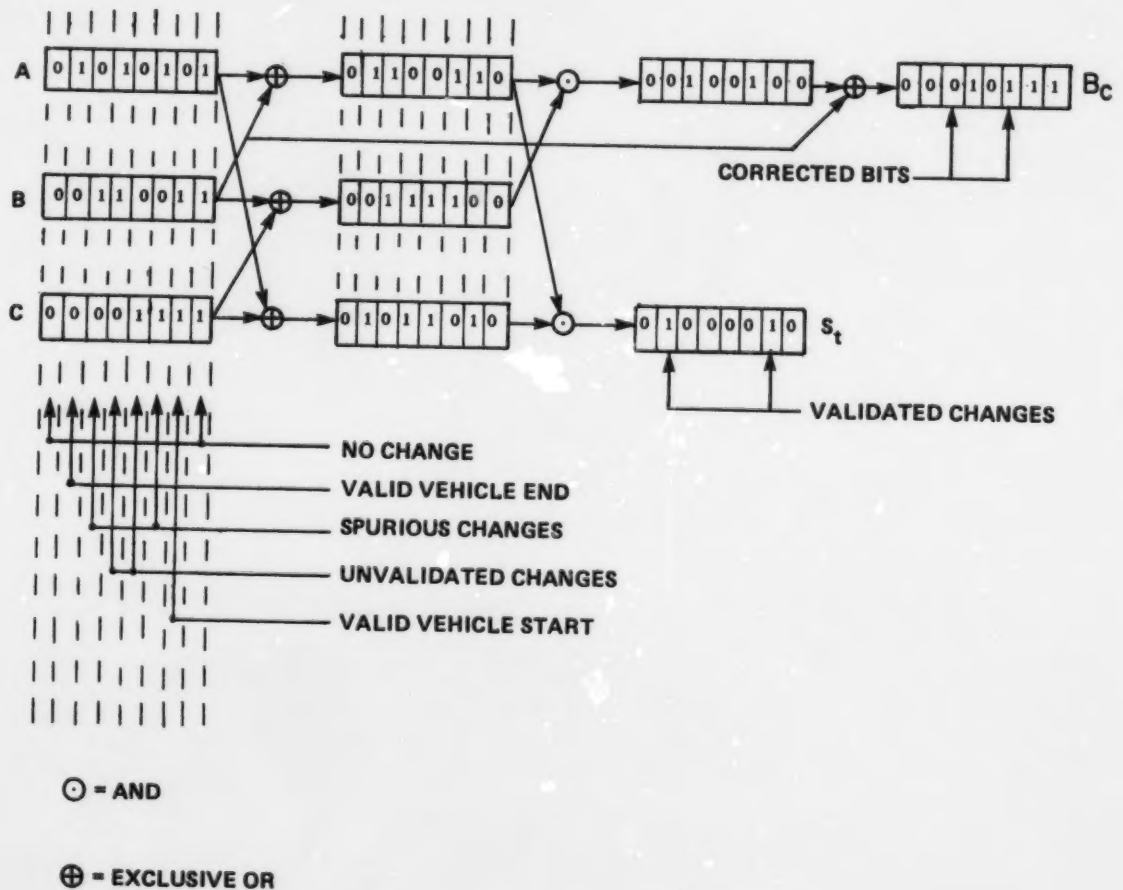


Figure 6.2/ Single Error Correction

6.10.3/ Parameter Index

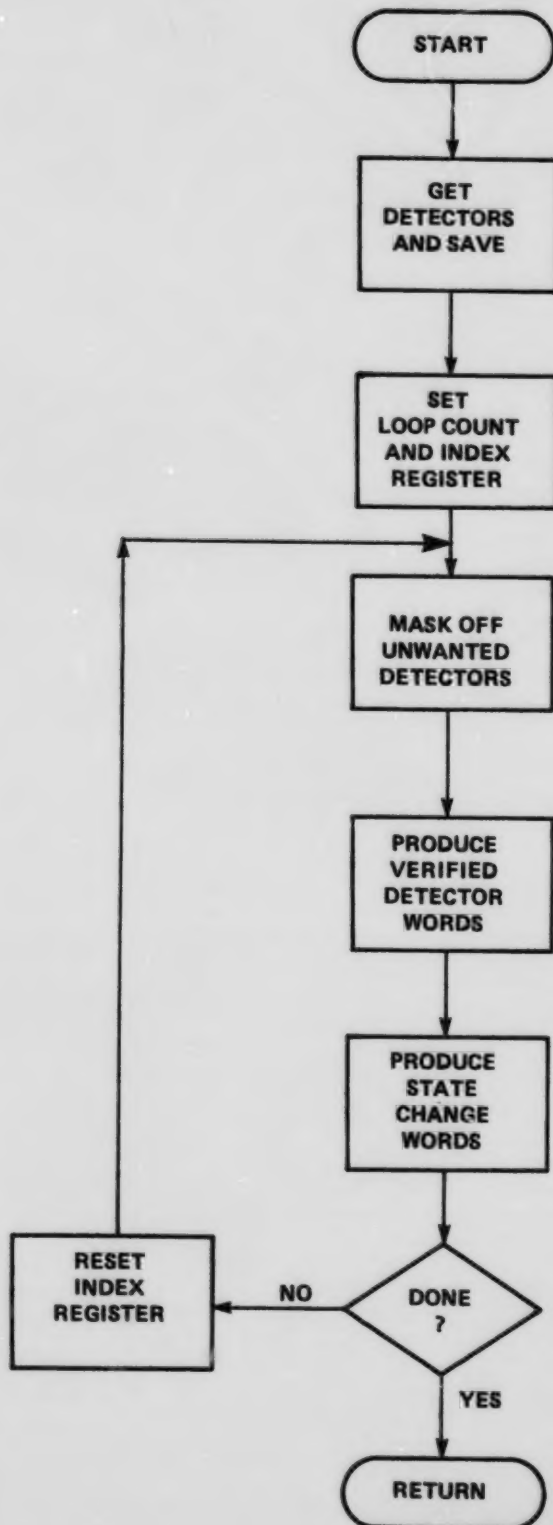
Routine: 'PCS2'

Description: Single error correction routine.

Parameter	Description
INPUT	- label for detector sampling routine in Direction 1.
INPUTT	- label for detector sampling routine in Direction 2.
S0	- label for branch destination.
TEMP04	- a temporary storage area used for varied applications.
TEMP05	- a temporary storage area used for varied applications.
DATA0L	- LSB of current unverified detector data.
TEMP06	- a temporary storage area used for varied applications.
DATA0M	- MSB of current unverified detector data.
DTCTRM	- MSB of detector enable mask.
TEMP07	- a temporary storage area used for varied applications.

Parameter	Description
TEMP05	- a temporary storage area used for varied applications.
S1	- label for branch destination.

6.10.4/ Flow Chart



6.11/ 'PCS3'

6.11.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 185, Line 1989, extending to Line 2135, which includes both directions.

6.11.2/ Program Explanation

This routine provides the initial service to the detector inputs. It adds counts for the occupancy, volume and the speed loop transition timers. In the case of volume and its associated occupancy, it undergoes only data manipulation from this point, whereas speed still requires several input values.

The process is introduced by incrementing two counters or timers, depending upon your point of view. These counters record the number of 1/60 of a second counts experienced between the up and downstream loops for each enabled lane. The exercise is actually done twice, since notice is given to vehicles both entering and leaving each detector. The transition timing flags are kept high for any lane which is eligible to be incremented and dropped low when a vehicle traverses the downstream detectors.

The next operation is to see if the upstream detector is occupied. This proving to be true, the routine increments the 6 s occupancy and the long vehicle occupancy before updating the transition timing flags. On the other hand, if it proves to be false, that is, the particular lane in question is not occupied, then the state change bit is examined. Here, there are two possibilities: either a vehicle could have left the detector area setting the state change bit (see 'PCS2'), or there may not have been any vehicles present at all. In the latter case, the process is simply started over again for the next lane in the sequence.

If there has been a state change, the 6 s volume count is incremented to indicate the passage of the vehicle. Then the state change bit is reset, followed by the updating of the transition timer flag and the detector error bit. At this point, the program rejoins the other alternatives and selects the next lane for processing by the use of the subroutine 'NEXTLN.' Upon completion of all the lanes, the control is returned to the calling routine.

6.11.3/ Parameter Index

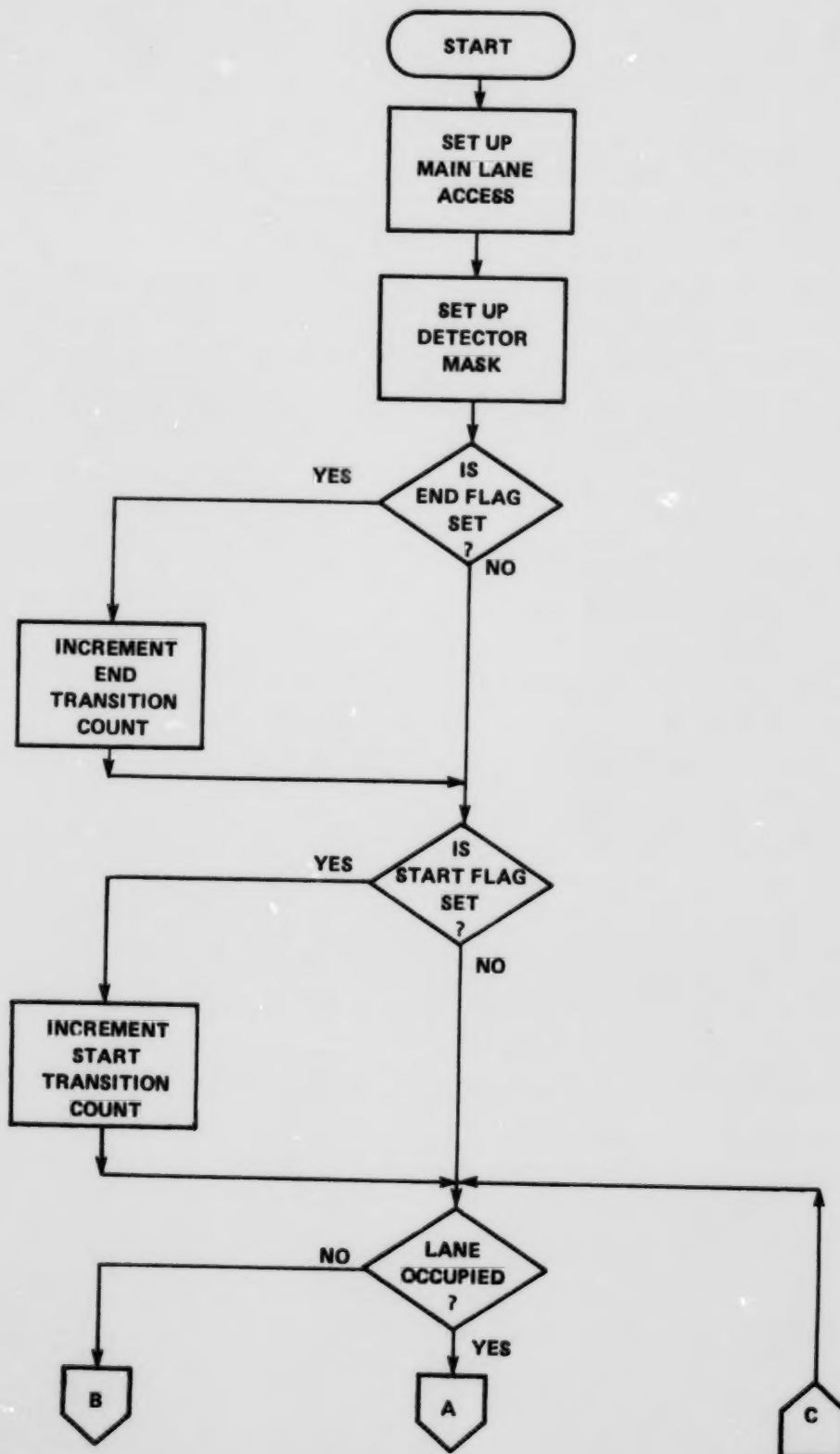
Routine: 'PCS3'

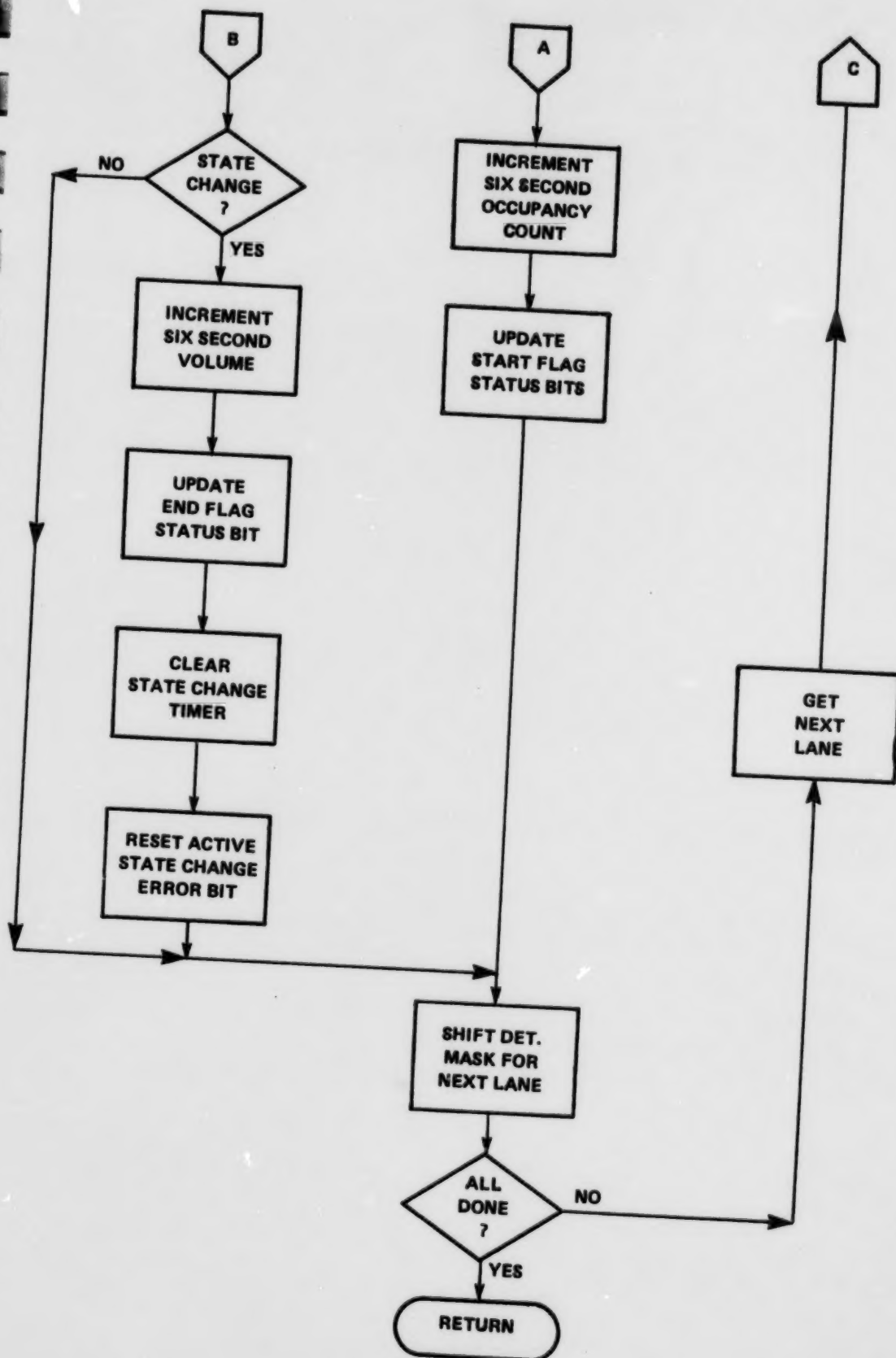
Description: Upstream detector servicing routine.

Parameter	Description
SETUP	- subroutine call to initialize lane data pointer.
TBIT7	- this parameter represents the predefined value of \$80.
TEMP03	- a temporary storage area used for varied applications.
TEMP01	- a temporary storage area used for varied applications.
G0	- Direction 1 vehicle end transition timing flag.
T20	- label for internal branch statement.
BIE	- vehicle end transition timer.
G0T	- Direction 1 vehicle start transition timing flag.
T21	- label for internal branch statement.
BIS	- vehicle start transition timer.
DETINM	- MSB of verified detector data.

Parameter	Description
T16	- label for internal branch statement.
STCHGM	- MSB of detector state change word.
T14	- label for internal branch statement.
VSIX1	- parameter holds the lane's 6 s count.
STCHG1	- state change timer.
DET1	- a byte containing the lane's detector error flags.
OSIX1	- parameter holds the lane's 6 s occupancy count.
OCC	- variable that contains the loop's occupancy by vehicle.
NEXTLN	- subroutine call to invoke the lane scan control routine.
T1	- label for internal branch statement.

6.11.4/ Flow Chart





6.12/ 'PCS3B'

6.12.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 188, Line 2160, extending to Line 2246, which includes both directions.

6.12.2/ Program Explanation

The purpose of the downstream detectors is to simply mark the end of a vehicle's excursion on the test section. In terms of the software, the routine must update the transition timing flags so as to allow proper termination of vehicle transition timers. (See 'PCS3.')

The program starts by setting the lane pointer via a subroutine call, then loading the lane detector mask for the highest number lane. Then the verified detector data are compared against the mask to determine whether or not a vehicle is present. If the test is true, a vehicle is present; then the vehicle start transition flag is dropped, disallowing any further counts for its respective counter found in 'PCS3.' On the other hand, if no vehicle is present, a further test for state change must be conducted. If the state has not changed, then the program concludes that there wasn't any action necessary for this lane and goes on to the next. But where the state change indicates a vehicle has just left, the vehicle end transition flag is dropped, disallowing any further counts in its respective counter. Either way, the program steps through the lanes until completion, whereby control is relinquished to the calling routine.

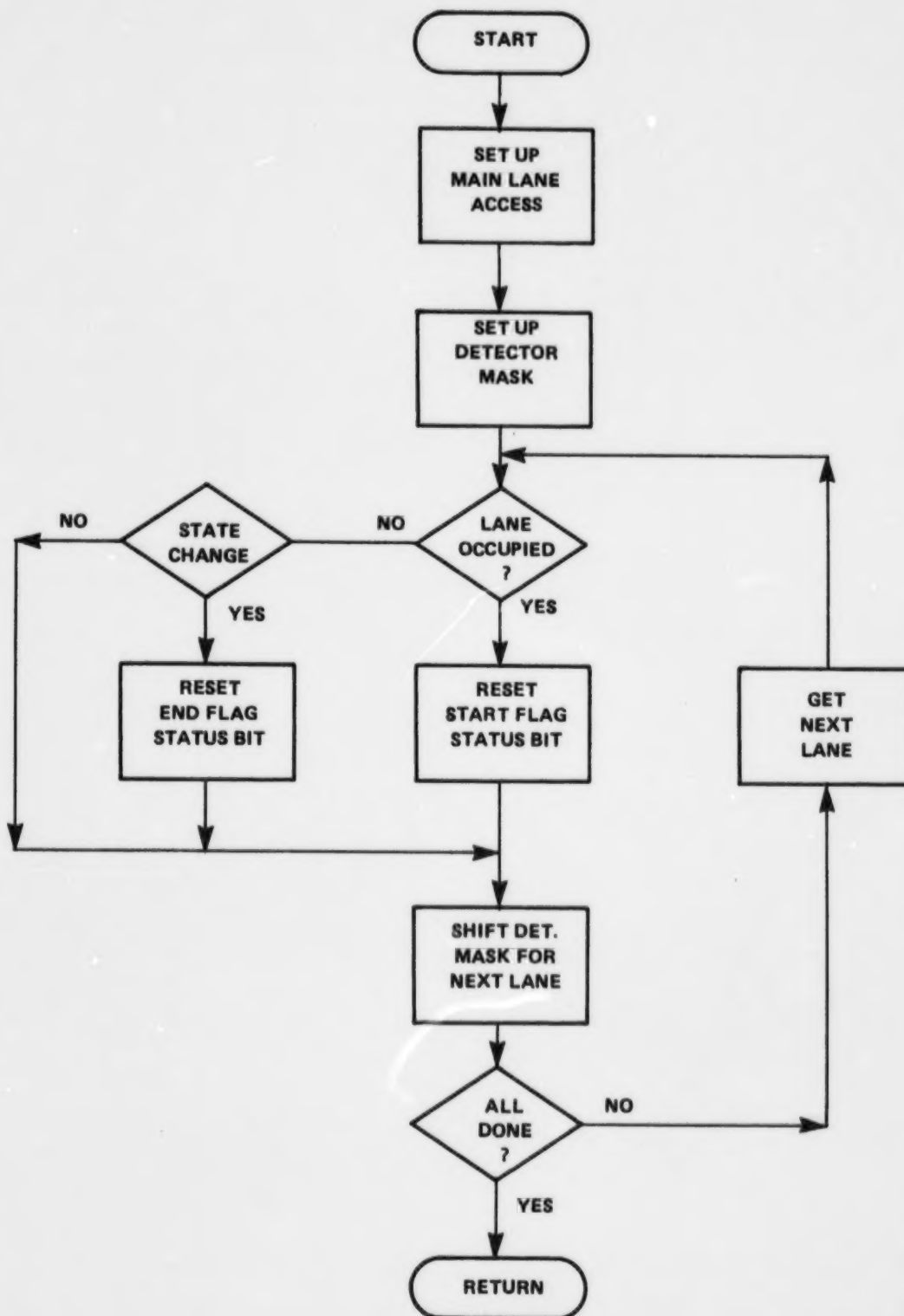
6.12.3/ Parameter Index

Routine: 'PCS3b'

Description: Downstream detector servicing routine.

Parameter	Description
SETUP	- subroutine call to initialize lane data pointer.
TBIT7	- the parameter represents the predefined value of \$80.
DETINM	- MSB of verified detector data offset by \$20 for downstream.
TB16	- label for internal branch statement.
STCHGM	- MSB of detector state change word offset by \$20 for downstream.
TB14	- label for internal branch statement.
GO	- Direction 1 vehicle end transition timing flag.
GOT	- Direction 1 vehicle start transition timing flag.
NEXTLN	- subroutine call to invoke the lane scan control routine.
TB1	- label for internal branch statement.

6.12.4/ Flow Chart



6.13/ 'PCS4'

6.13.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 172, Line 1061, extending to Line 1240, which includes both directions.

6.13.2/ Program Explanation

The purpose of this routine is to use the 6 s volume/occupancy counts to calculate hourly volume and the running totals for volume/occupancy. The accumulation of the hourly volume count is very straightforward, while the running totals are somewhat more involved.

The routine starts, after setting the lane index pointer, by examining the data clear flag 'KAY1.' If this indicator is non-zero, the lane's data area is cleared of its present values. In a routine which, in part, calculates pseudo running totals, this is of obvious importance. As can be seen in Section 6.6.2, proportioning is done by taking 9/10 of a volume and adding the current 6 s count. Therefore, residue in data area to start with is undesirable. It is not necessary to dwell on the process, since this running total feature is available but not utilized by a standard PCS station.

The remainder of the routine manipulates data in preparation for proportioning, as well as accumulating the value count into the desired hourly format. Information from here goes into the 'PCS5' series of routines to further process information into average running totals.

6.13.3/ Parameter Index

Routine: 'PCS4'

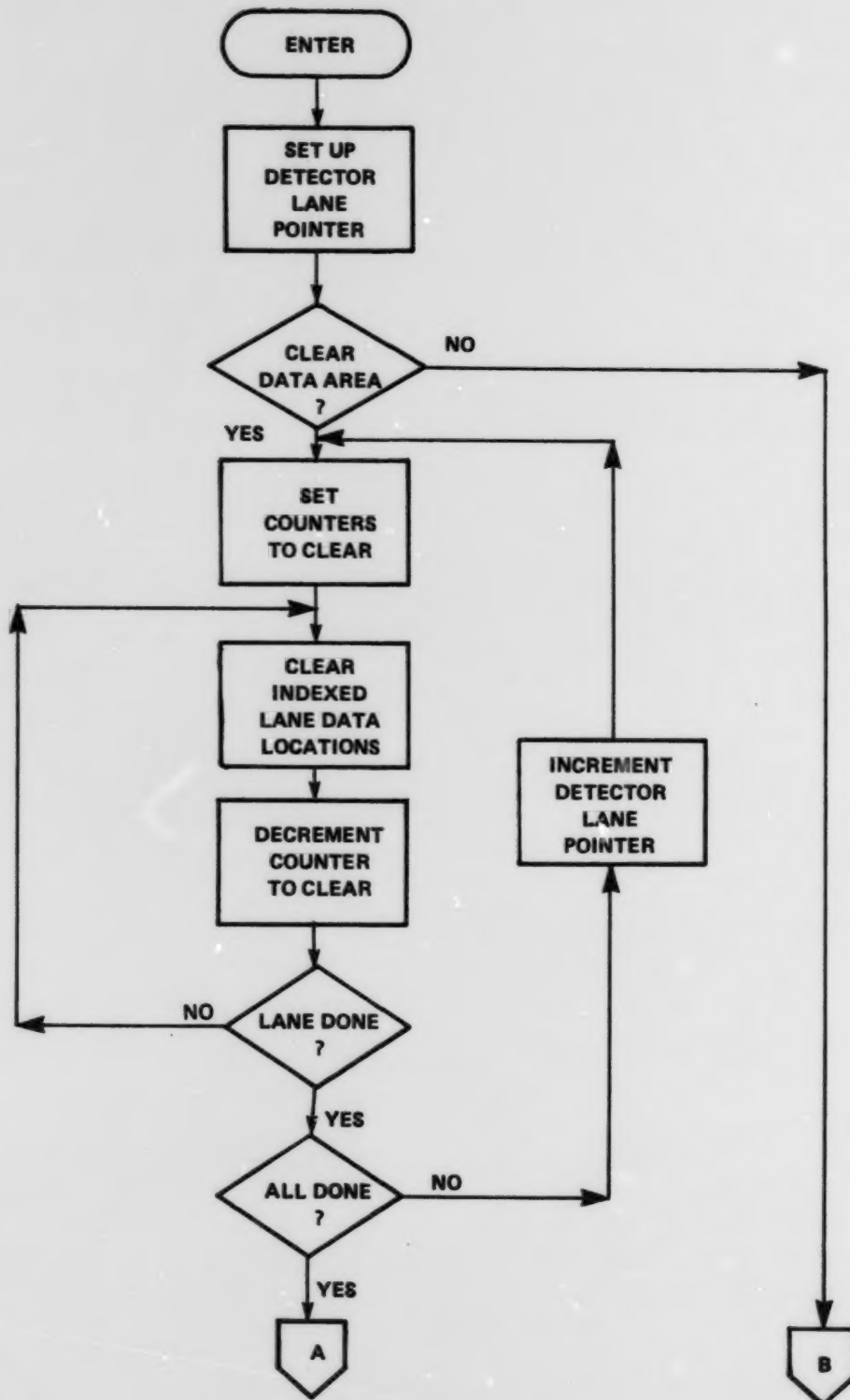
Description: Lane data handling routine.

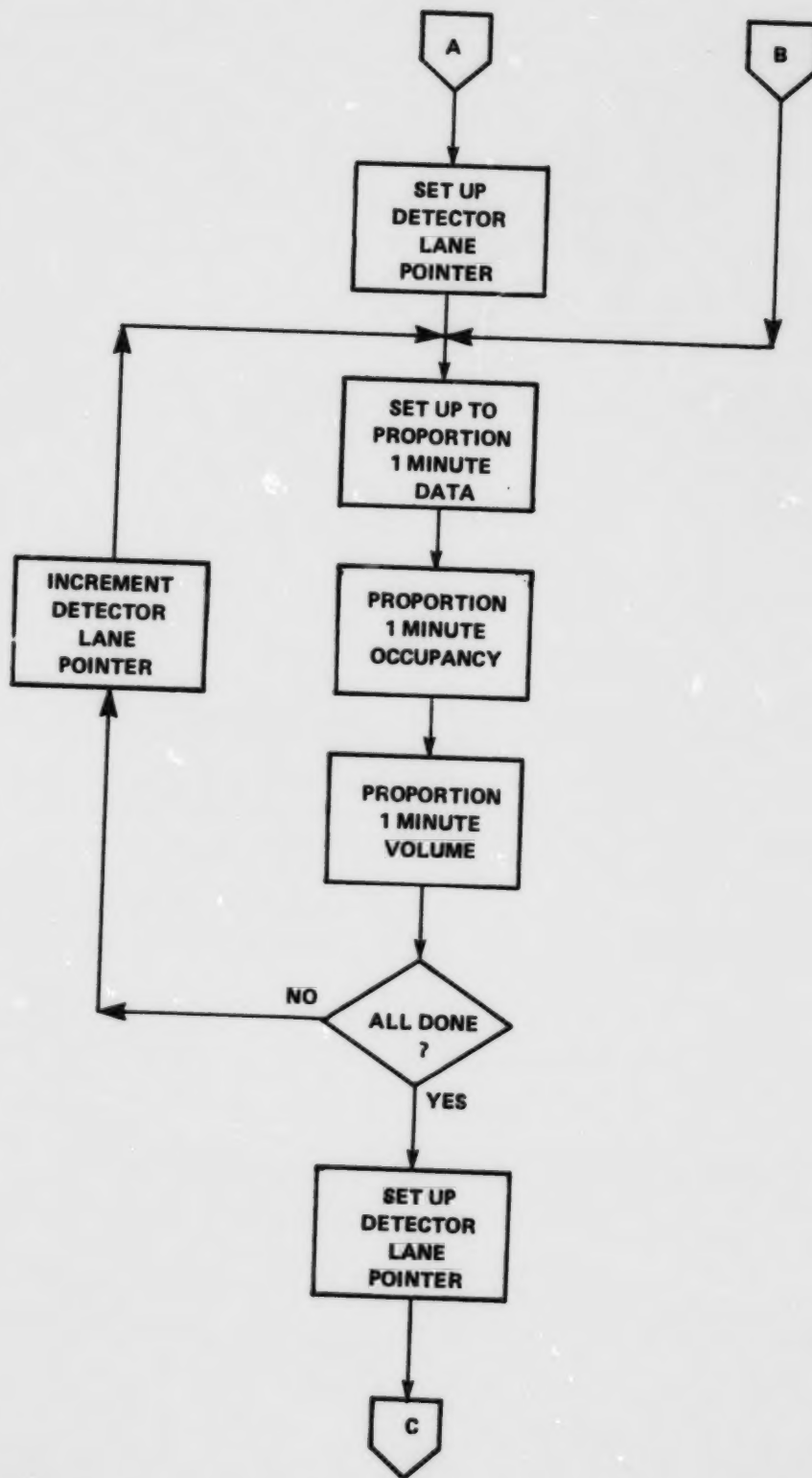
Parameter	Description
SETUP	- subroutine call to initialize lane data pointer.
TEMP04	- a temporary storage area used for varied applications.
KAY1	- clear flag for detector data area.
PROP1	- label for internal branch statement referencing 1 min average running total proportioning.
OSIX1	- byte containing 6 s occupancy.
D2	- label for internal branch statement.
NEXTLN	- subroutine call to advance lane data pointer.
D1	- label for internal branch statement.
PCW1	- proportion control word, set to '1A' (26/256) for 1 min.
OCMN1M	- MSB of occupancy for 1 min running total.

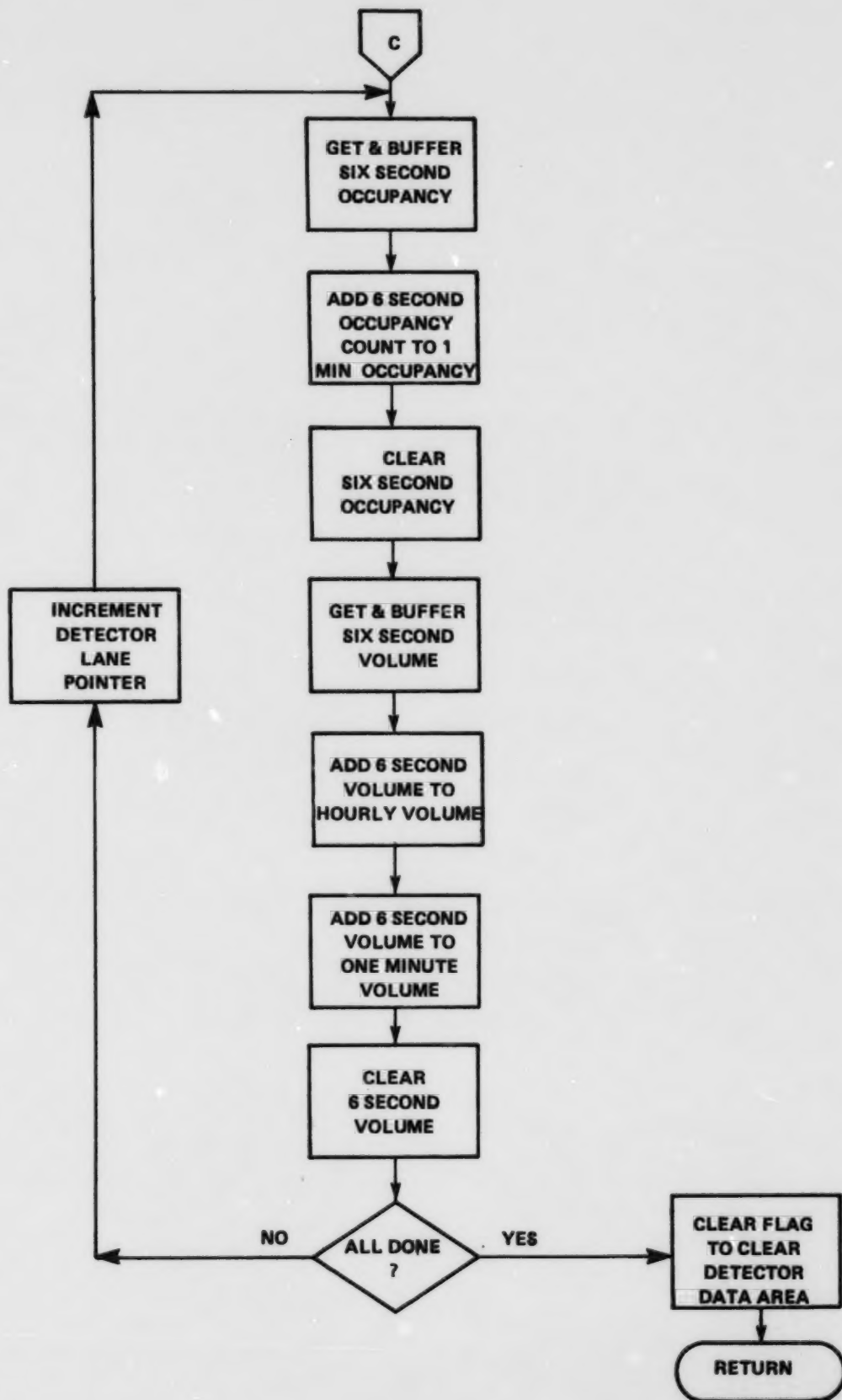
Parameter	Description
PRO16	- label for branch statement destination to set up for 2-byte proportioning.
VMN1	- 1 min running total volume.
PRO8	- label for branch statement destination to set up for 1-byte proportioning.
NEXTLN	- subroutine call to invoke the lane scan control routine.
OCC1L	- LSB of an occupancy count.
D3	- label for internal branch statement destination.
OCC1M	- MSB of an occupancy count.
OCMN1L	- LSB of occupancy for 1 min running total.
D5	- label for internal branch statement destination.
VSIX1	- byte containing 6 s volume count.
VOL1	- volume count.
VD1L	- LSB of the hourly accumulated volume count (cleared hourly).
D56	- label for internal branch statement destination.

Parameter	Description
VD1M	- MSB of the hourly accumulated volume count (cleared hourly).
D50	- label for internal branch statement destination.
INDEX	- stores values of the index register.
TEMP05	- a temporary storage area used for varied applications.
TEMP04	- a temporary storage area used for varied applications.
PRPRT8	- subroutine call to invoke proportioning for pseudo running totals.

6.13.4/ Flow Chart







6.14/ 'PCS5'

6.14.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 174, Line 1270, extending to Line 1455, which includes both directions.

6.14.2/ Program Explanation

Although the running and average totals are not actively used now, the potential in the future for control function could prove invaluable.

The program starts by clearing all the old average running totals. Then it steps through all the lanes to determine which are eligible for consideration by discriminating the detector error flag 'DET1,' set by the 'PCS3' series of routines. Next the eligible lanes are checked to see if they have been enabled, 'INIT' routine, for use in this particular installation before proceeding.

Once the lanes have been decided upon, the running totals for both volume and occupancy update the average running total table (ART). This is done for all lanes involved. Upon completion, the remainder of the program is concerned with proportioning the summed running totals based on the number of lanes. This process relies on the proportioning subroutine 'PRPRT' and the predefined lane proportioning constants. An explanation of the latter may be seen in Section 2.4. As a result of 'PCS4' and 'PCS5,' there are running and average running totals for both volume and occupancy. These features are not utilized in this phase of PCS, but are available if any control operations require them.

6.14.3/ Parameter Index

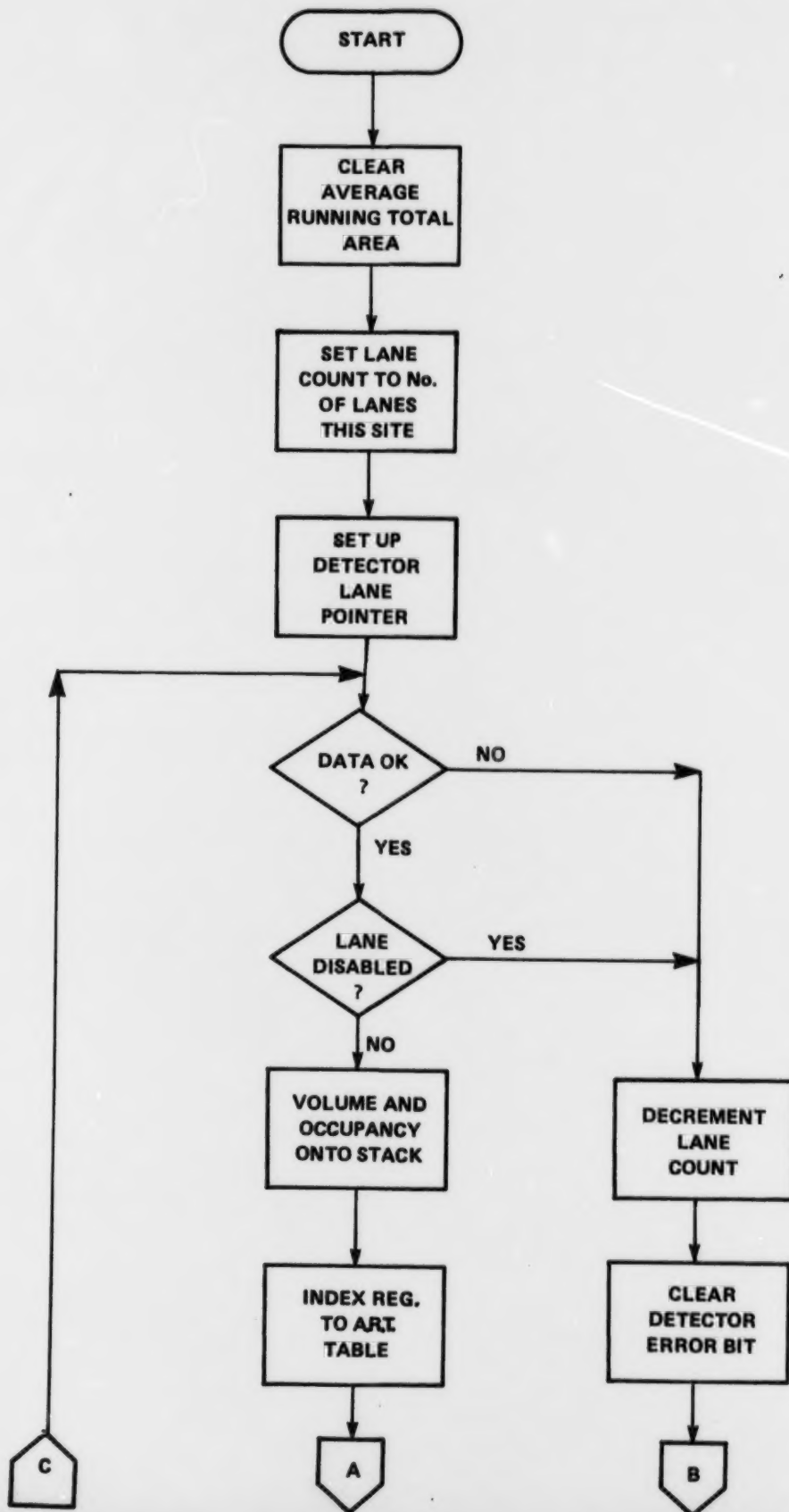
Routine: 'PCS5'

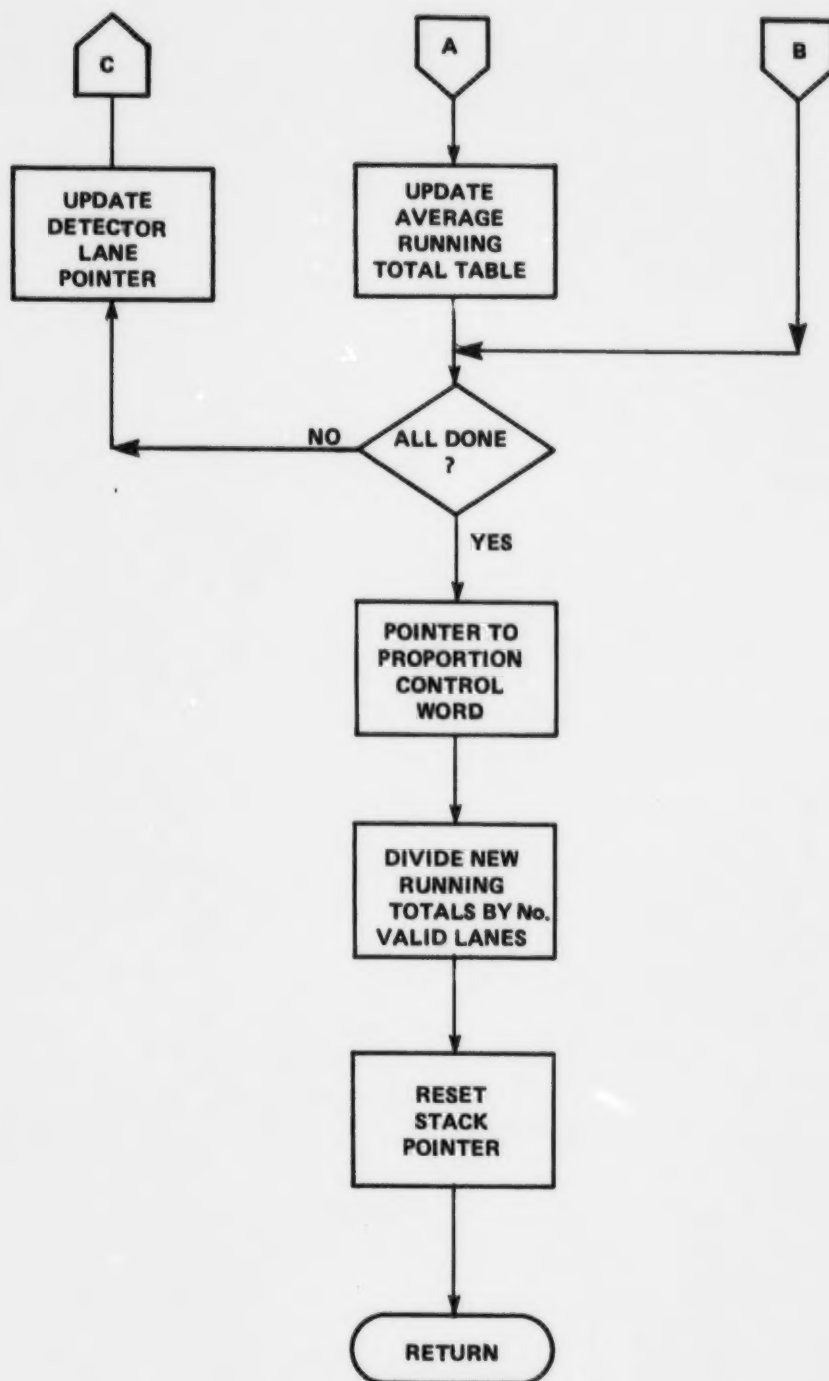
Description: Average running total routine.

Parameter	Description
AR1MOM	- MSB of average running 1 min occupancy.
LOOP1	- label for internal branch statement.
SETUP	- subroutine call to initialize lane data pointer.
DET1	- detector error flag.
E5	- label for internal branch statement.
NLOOP2	- label for internal branch statement.
LNDIS1	- lane disable flag. (Ø allows lane data to be processed.)
E3	- label for internal branch statement.
VMN1	- 1 min volume running total.
PRPRT	- a subroutine call enabling the proportioning routine for pseudo running total (Section 6.6).

Parameter	Description
OCMN1M	- MSB of 1 min occupancy running total.
OCMN1L	- LSB of 1 min occupancy running total.
NEXTLN	- subroutine call to invoke the lane scan control routine.
LOOP2	- label for internal branch statement.
PCWTAB	- label for internal branch statement to proportion control word table in routine.
PIKUP	- label for internal branch statement.
LOOP4	- label for internal branch statement.
INDEX	- temporary storage for index register representing, in this case, ART table pointer.
AR1MVL	- LSB of average running 1 min volumes.
OUT	- label for internal branch statement.
LOOP5	- label for internal branch statement.
PCLN1-8	- predefined lane proportioning constants.

6.14.4/ Flow Chart





6.15/ 'PCS6'

6.15.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 178, Line 1484, extending to Line 1628, which includes both directions.

6.15.2/ Program Explanation

The whole purpose of this routine is to monitor, in a minor way, the lane's detector status. Although only one type of error is checked for, several more will inevitably prove desirable as time goes on. With this in mind, Bits 1 to 7 are reserved for individual failures, while Bit 8 is set if there is a failure of any nature. The software is designed to check for suspiciously long occupancies by comparing the 1 min values with a preset limit.

The routine is introduced by the definition of two error parameters, 'O1BIT' and 'ERRBIT,' to take the values \$82 and \$80, respectively. Next, there is an imposing statement which, if pondered, reveals that the value of the 1 min occupancy inhabits \$0201. With this established, the occupancy limit, established in 'INIT,' is compared to the 1 min occupancy with the use of 'CMP16' found in Section 5.5. In the case where there is no violation of the limit, the routine tries the next lane. On the other hand, if occupancy is too large, a detector error is flagged. The #O1BIT value is superimposed on 'DET1' if the lane has been enabled. The only area to be completed is the error flags for external use.

So far the description has been limited to the process of setting 'DET1,' which is a variable for internal use. This variable is set and reset to reflect on continuing checks of the detectors. This is all well and good, but there is a need to know whether a failure has taken place which would affect the integrity of the data transfer to the transmit buffer. For this purpose, the rest of the routine sets the 'DETER1' byte, which logs any detector errors and can only be reset by external sources. Therefore, once the 'INIT' routine has reset 'DETER1,' it can be monitored anytime to determine the status of the lane's loop detectors. Where any failure will be indicated by setting the appropriate bit, it will be held until the system is either reset or manually changed. With this complete, control is returned to the calling routine.

6.15.3/ Parameter Index

Routine: 'PCS6'

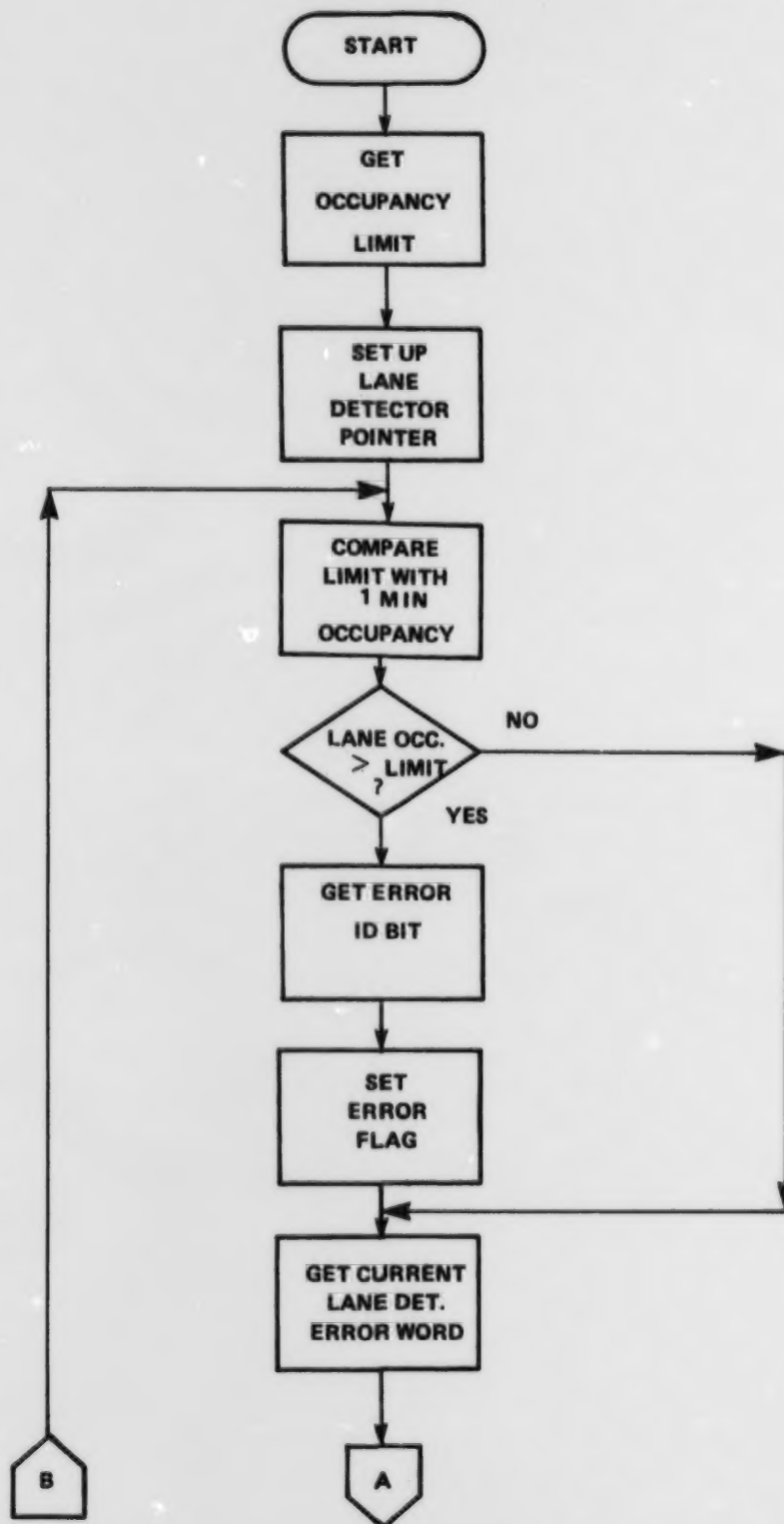
Description: Detector failure check routine.

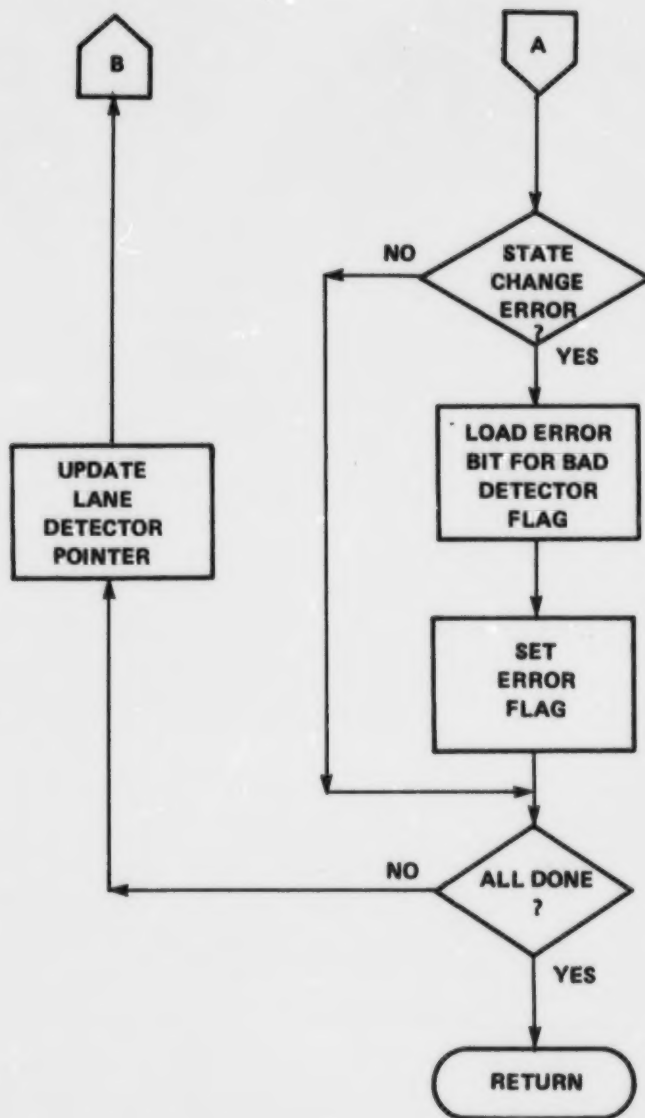
Parameter	Description
01BIT	- a parameter defined to have the value \$82.
ERRBIT	- a parameter defined to have the value \$80.
OCMN1M	- MSB of 1 min occupancy running total.
TEMP04	- a temporary storage area used for varied applications.
OC10CM	- 1 min occupancy limit.
TEMP02	- a temporary storage area used for varied applications.
SETUP	- subroutine call to initialize lane data pointer.
OCTEST	- label for internal branch statement which is set up for 16-bit comparison.
L07	- label for internal branch statement.
L01	- label for internal branch statement.

Parameter	Description
ERSET	- label for internal branch to set detector error flag 'DET1.'
NEXTLN	- subroutine call to invoke the lane scan control routine.
L011	- label for internal branch statement.
DETER1	- eight-lane detector error byte.
TEMP03	- a temporary variable used for varied applications.
DET1	- detector error byte.
L013	- label for internal branch statement.
TEMP01	- a temporary variable used for varied applications.
L012	- label for internal branch statement.
LNDIS1	- lane disable byte. (A non-0 value indicates the lane is unused.)
ER9	- label for internal branch statement.
INDEX	- a variable used for storing the index register. Also uses 'INDEX+1.'

Parameter	Description
TEMP06	- a temporary storage area used for varied applications.
TEMP05	- a temporary storage area used for varied applications.
CMP16	- call for the generalized subroutine to compare two 16 bit numbers.

6.15.4/ Flow Chart





6.16/ 'PCS7'

6.16.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 180, Line 1653, extending to Line 1768, which includes both directions. See Page 190, Line 2270 to Line 2386 for 'PCS7A.'

6.16.2/ Program Explanation

This routine provides the transfer of the hourly volume data into the transmit buffer according to the configuration defined in initialization. To accomplish this, the routine first gets the current hour, which is in BCD, and converts it to binary. Then it locates the right location in the buffer for the given time. To do this, the start of the volume buffer is loaded and, if it happens to be the end of hour zero, this is taken as the correct buffer location. For any other hour, the value of 'SIZE' is continuously added to the start pointer 'PTR,' while the hour value is decremented until the correct location is reached. From this location onwards for a distance of 'SIZE,' the memory is zeroed to remove all traces of volume information for the time slot which is about to be used. The rest of the routine, which is the majority, deals with the transfer of data.

The process of summing and categorizing data is basically under the control of two types of variables, 'VOLW1' and 'NVOL1,' for each direction. The routine just steps through the eligible lane data, first noting the number of volume counts to be assessed. For each count, to be assessed, it then consults in sequence the various lane configurations to be summed for the particular count. Along with clearing the hourly volume count from the locations from which they are extracted, the process is allowed to work until completion, where it returns control, once again, to the calling routine. A printout of a typical day's hourly volume counts obtained by telemetry link can be seen in Figure 6.3.

1. PCS STATION I.C. : CONTROLLER #21, STATION #52 -- LAKE SHORE
 2. HIGHWAY : 2 (EAST OF CREDIT RIVER BRIDGE)
 3. DATE : 4/27/14, TUESDAY

4. VOLUME COUNT :

HOUR	WESTBOUND (2 LANES)	EASTBOUND (2 LANES)
1	135.	88.
2	86.	45.
3	31.	25.
4	27.	18.
5	16.	18.
6	49.	73.
7	201.	570.
8	340.	1871.
9	558.	1457.
10	452.	611.
11	568.	656.
12	644.	680.
13	688.	725.
14	695.	668.
15	721.	754.
16	897.	733.
17	1287.	804.
18	1466.	702.
19	1110.	736.
20	802.	578.
21	555.	444.
22	419.	323.
23	310.	312.
24	248.	192.
TOTAL	12355.	13083.

5. TRUCK COUNT (LENGTH > 6.5 M) :

HOUR	WESTBOUND (2 LANES)	EASTBOUND (2 LANES)
1	8.	5.
2	6.	2.
3	3.	1.
4	2.	0.
5	0.	0.
6	10.	4.
7	16.	34.
8	48.	167.
9	63.	125.
10	44.	43.
11	57.	32.
12	49.	43.
13	50.	39.
14	53.	49.
15	34.	42.
16	56.	57.
17	77.	42.
18	72.	26.
19	41.	27.
20	17.	15.
21	14.	10.
22	10.	8.
23	8.	7.
24	5.	4.
TOTAL	751.	782.

6. SPEED COUNT :

	OVER 130 KM/H
120-130	4.
110-120	6.
100-110	10.
90-100	35.
80-90	32.
70-80	169.
60-70	902.
50-60	2919.
40-50	15395.
30-40	2603.
UNDER 30 KM/H	2198.
TOTAL	24288.

Figure 6.3/ Typical Volume Count Output

6.16.3/ Parameter Index

Routine: 'PCS7'

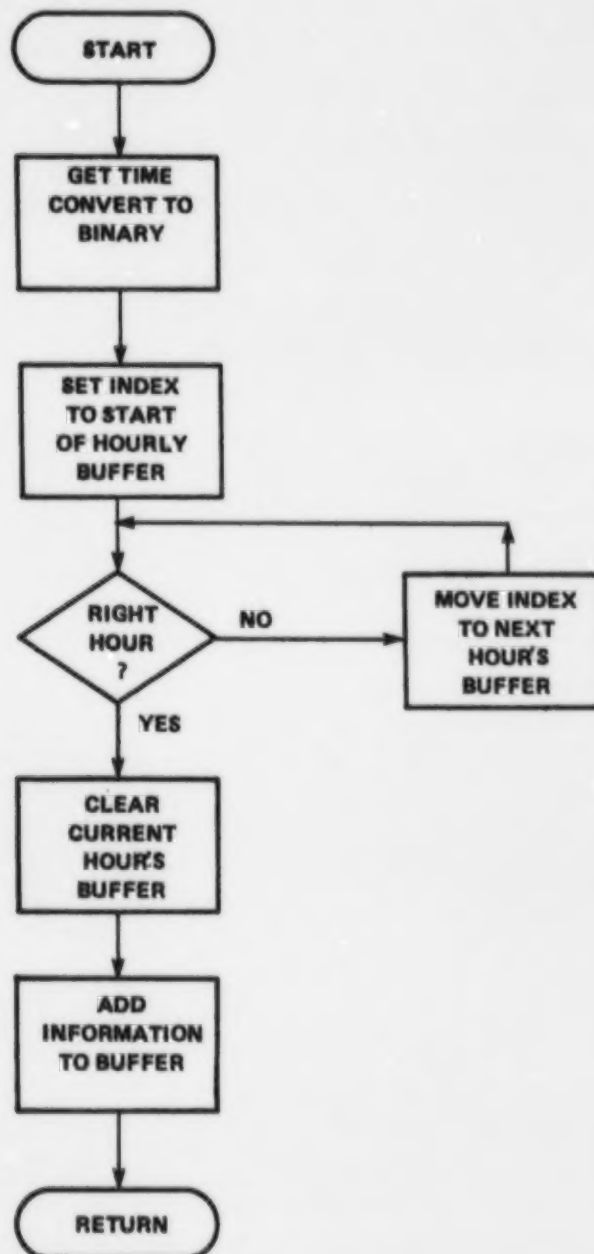
Description: Hourly data transfer routine.

Parameter	Description
HR	- hour of the day in BCD (24-h clock).
G70	- label for internal branch statement.
G71	- label for internal branch statement.
G1	- label for internal branch statement.
G5	- label for internal branch statement.
PTR	- pointer to beginning of volume data.
TEMP04	- a temporary variable used for varied applications.
G9	- label for internal branch statement.
SIZE	- amount of memory space required to store all volume counts in both directions for 1 h.

Parameter	Description
TEMP05	- a temporary variable used for varied applications.
G51	- label for internal branch statement.
NVOL1	- number of volume counts to be calculated in Direction 1.
TEMP01	- a temporary storage area used in varied applications.
TEMP03	- a temporary storage area used in varied applications.
TEMP06	- a temporary storage area used in varied applications.
TEMP07	- a temporary storage area used in varied applications.
VOLDW1	- count descriptor byte for Volume 1.
SPC1	- MSB of index for referencing lane volume data.
SPC2	- LSB of index for referencing lane volume data.
G15	- label for internal branch statement.
G10	- label for internal branch statement.

Parameter	Description
NVOL2	- number of volume counts to be calculated in Direction 2.
G60	- label for internal branch statement.
G45	- label for internal branch statement.
G30	- label for internal branch statement.
G40	- label for internal branch statement.
VD1M	- MSB of hourly volume count.
VD1L	- LSB of hourly volume count.
G52	- label for internal branch statement.
G36	- label for internal branch statement.
G50	- label for internal branch statement.

6.16.4/ Flow Chart



6.17/ 'PCSB'

6.17.1/ Program Listing Reference

The relevant program listing may be found in Appendix A, starting on Page 191, Line 2412, extending to Line 2703, which includes both directions.

6.17.2/ Program Explanation

This routine calculates and classifies vehicular speed and assesses their length. It, like most of the software, is split into two routines, one for each direction. Since these two routines, 'PCS8' and 'PCS8A,' require much mathematical manipulation, they are executed alternately to avoid occupying too much of the allotted cycle time.

The first function of the routine is to assign a limit to the variable 'COUNT6,' which will be used in the exclusion of certain speed data later on in the program. This is followed by a set of instructions which determine if the routine is to be executed this time around. Given that it is, the Direction 1 vehicle 'end' transition timing flag is checked for the first lane. If the flag is set (see 'PCS3/PCS3B'), then the routine knows the vehicle has not yet finished the test section and goes on to the next lane. On the other hand, on finding that the vehicle has completed the section, eligibility is then checked. Since the transition timer is an 8-bit counter with 1/60 of a second increments every 256/60 s, the counter will reset and set the appropriate transition counter roll over flag found in 'C1E.' Therefore, for a lane to be eligible, the roll over flag must be clear to indicate relevant timing data. If the check reveals that the flag is set for the particular channel, then all the appropriate speed and length parameters are cleared. Assuming all is well, the processing continues.

The transition times are loaded and, here again, eligibility is checked. This time, timing values which would result in speeds in excess of 136 mph are eliminated outright. Such values result from unusual vehicle behaviour in and about the test section and tend to clutter up the upper speed classification. Data which are still found to be correct are then manipulated, with the math subroutines, in accordance with the relationship:

$$\text{Speed} = \frac{1}{2} \left[\frac{LS}{BIE} + \frac{LS}{BIS} \right]$$

Similarly, vehicle length is calculated according to :

$$\text{Length} = \text{OCC} * \text{speed} - \text{LD}$$

Examples of both calculations may be found in Section 2.3. All that is left to be done now is to classify the speed.

The mechanics of grouping the speed are obvious. Each group has a threshold value; therefore, a given speed is compared to these values systematically until the appropriate group is found. As can be seen, in hard copy, both the most and least significant bytes of the threshold values are similarly compared.

The process is repeated for all necessary lanes before control is returned to the calling routine. A printout of a typical speed grouping length count obtained by the telemetry link can be seen in Figure 6.4.

1. PCS STATION I.O. : CONTROLLER #21, STATION #52 -- LAKESHORE
 2. HIGHWAY : 2 (EAST OF CREDIT RIVER BRIDGE)
 3. DATE : 42/ 9/14, TUESDAY

4. VOLUME COUNT :

HOUR	WESTBOUND (2 LANES)	EASTBOUND (2 LANES)
1	135.	88.
2	86.	45.
3	31.	25.
4	27.	18.
5	16.	18.
6	59.	73.
7	201.	570.
8	380.	1871.
9	558.	1457.
10	452.	611.
11	568.	656.
12	644.	680.
13	688.	725.
14	695.	668.
15	721.	754.
16	897.	733.
17	1287.	808.
18	1486.	702.
19	1110.	736.
20	802.	578.
21	555.	444.
22	419.	323.
23	310.	312.
24	248.	192.
TOTAL	12355.	13083.

5. TRUCK COUNT (LENGTH > 6.5 M) :

HOUR	WESTBOUND (2 LANES)	EASTBOUND (2 LANES)
1	8.	5.
2	6.	2.
3	3.	1.
4	2.	0.
5	0.	0.
6	10.	4.
7	16.	34.
8	48.	167.
9	63.	125.
10	48.	43.
11	57.	32.
12	49.	43.
13	50.	39.
14	53.	49.
15	38.	42.
16	56.	57.
17	77.	42.
18	72.	26.
19	41.	27.
20	17.	15.
21	14.	10.
22	10.	8.
23	3.	7.
24	5.	4.
TOTAL	751.	782.

6. SPEED COUNT :

OVER 130 KM/H	19.
120-130	4.
110-120	6.
100-110	10.
90-100	35.
80-90	32.
70-80	169.
60-70	902.
50-60	2919.
40-50	15395.
30-40	2603.
UNDER 30 KM/H	2198.
TOTAL	24288.

Figure 6.4/ Typical Speed Classification
 (Speed Limit at 50 km/h)

6.17.3/ Parameter Index

Routine: 'PCS8'

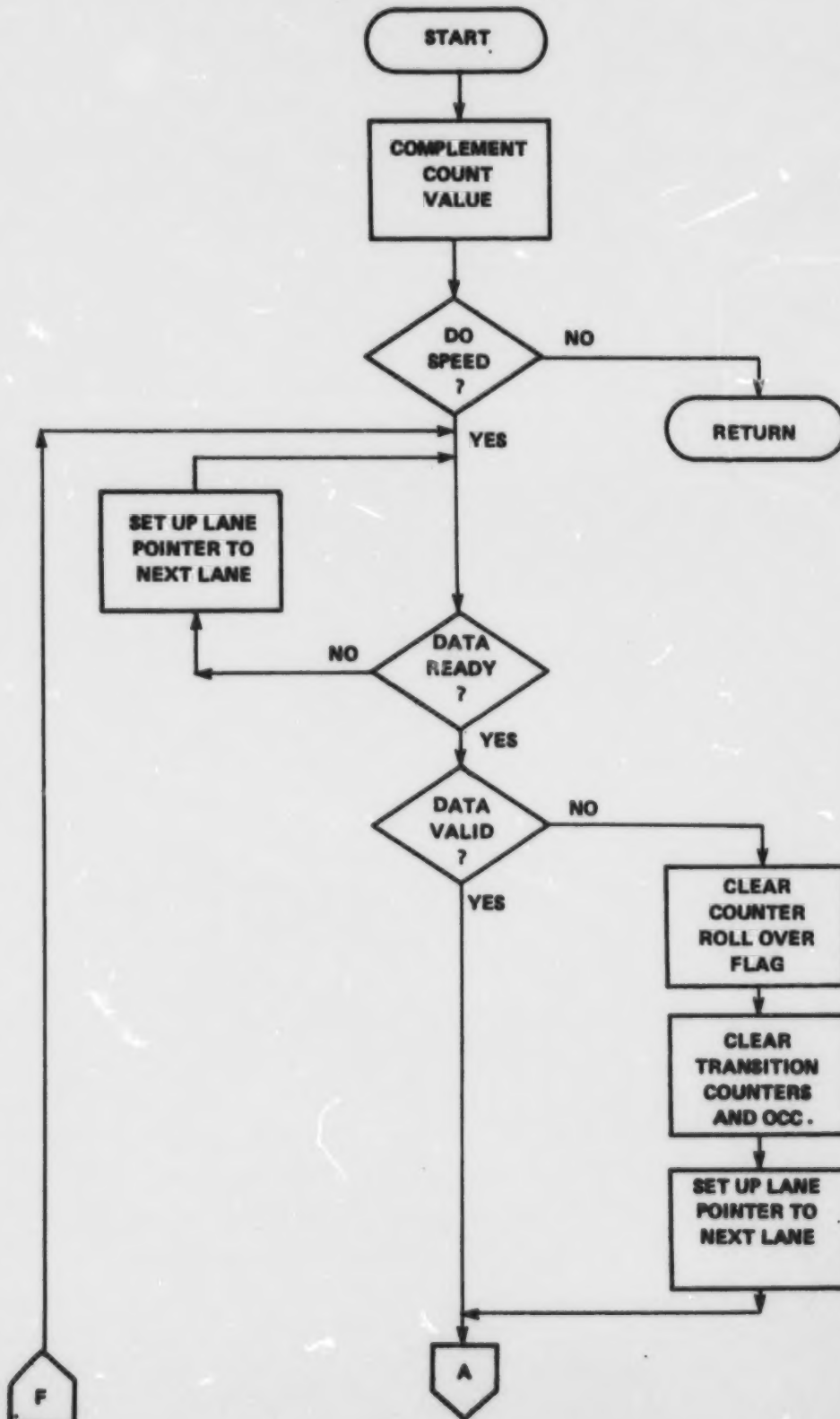
Description: Vehicle speed and length classification.

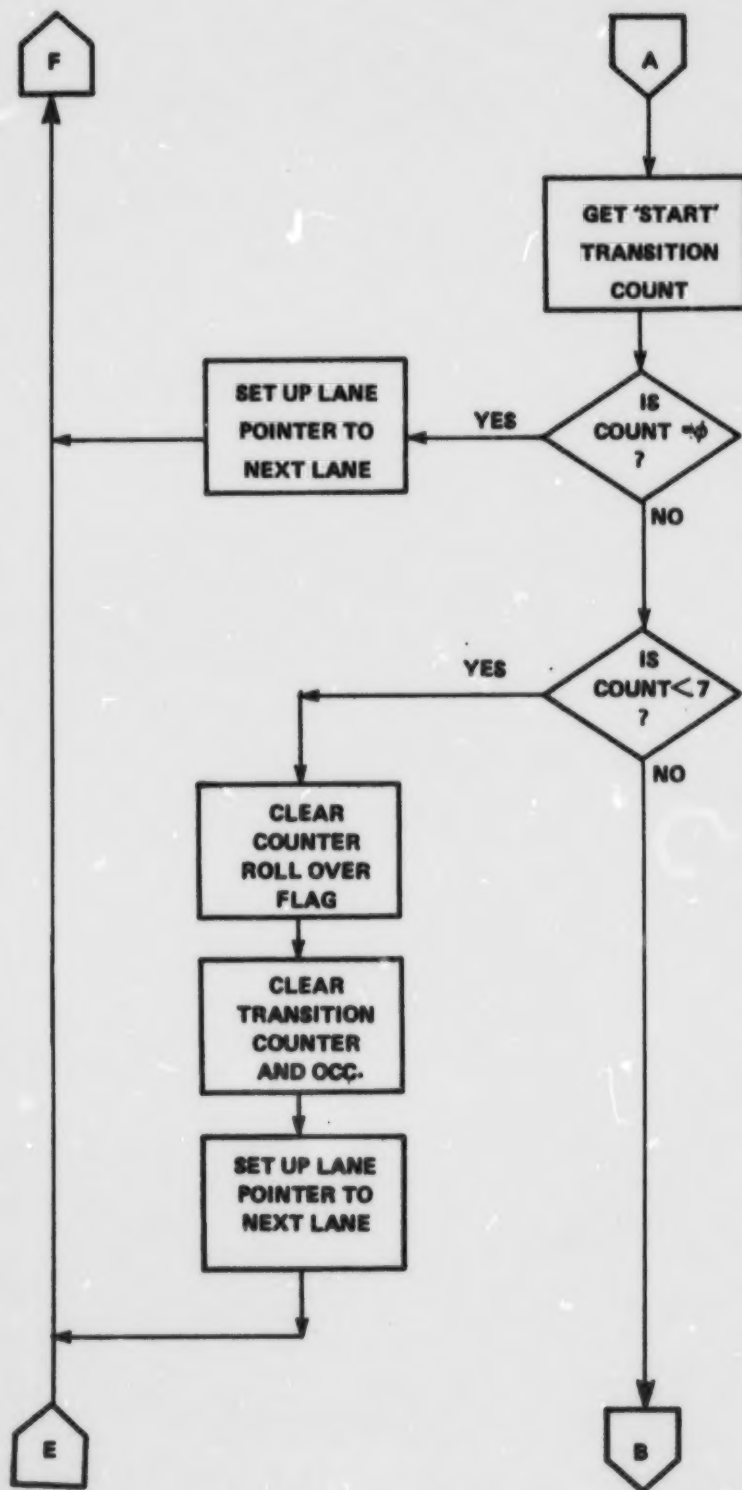
Parameter	Description
COUNT6	- stores the limit of transition time to be a data disqualifier.
COUNT3	- toggling value for alternating speed calculations.
SP99	- label for internal branch statement.
INDEX	- a variable used for the storage of index register values.
COUNT1	- storage area for lane bit mask.
GO	- Direction 1 vehicle end transition timing flag.
SP11	- label for internal branch statement.
C1E	- transition counter roll over flag.
SP49	- label for internal branch statement.
B1E	- 8-bit indexed transition timer for vehicle ends.

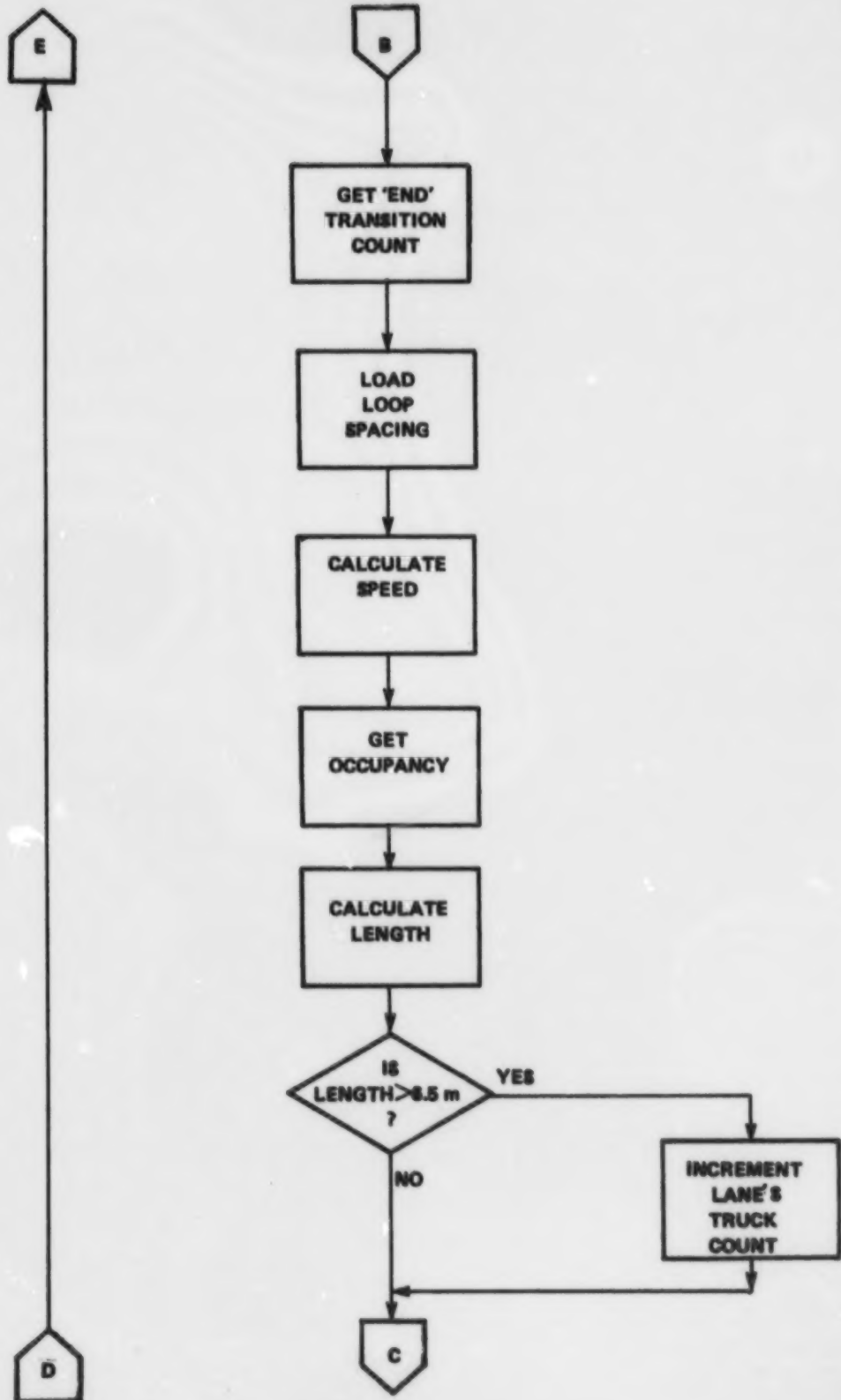
Parameter	Description
OCC	- vehicle occupancy used in length calculation derived by upstream detectors.
B1S	- 8-bit indexed transition timer for vehicle starts.
TEMP02	- a temporary storage area used for varied applications.
TEMP04	- a temporary storage area used for varied applications.
LS	- variable for loop spacing.
TEMP05	- a temporary storage area used for varied applications.
DIV	- subroutine call to invoke the 8-bit division routine.
MULT	- subroutine call to invoke the 8-bit multiplication routine.
LD	- a variable for the loop dimensions.
TRUCK	- the length limit equivalent to 6.5 m.
LENL	- LSB for the storage of the hourly long vehicle count.
LENH	- MSB for the storage of the hourly long vehicle count.

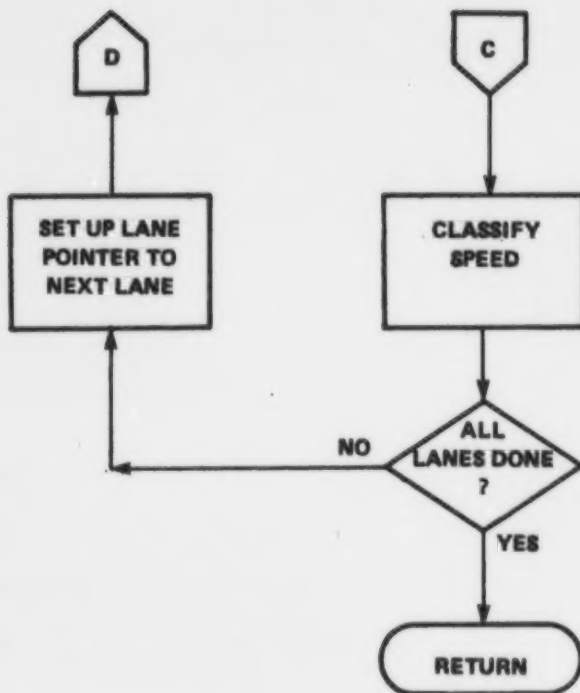
Parameter	Description
SPED	- an indexed value which holds the 12 groups of daily speed totals.
SPD	- an indexed value which represents the MSB of the speed classification thresholds.
REM	- an indexed value which represents the LSB of the speed classification threshold.
NEXTLN	- subroutine call to advance lane data pointer.

8.17.4/ Flow Chart









7/ SYSTEM DEVELOPMENT

To every system there are improvements, and to all software there are modifications. PCS is no exception to this; there is literally no end to changes that could be made. Of the myriad of possibilities, some are more beneficial than others.

An improvement that would be very beneficial is an addition to the initialization routine, which would assess the memory size and calculate the maximum number of days to be stored. Along with this, the memory zeroing process could be extended to cover all but the stack, independent of memory size.

An oversight propagated from Phase I software deals with lanes equipped with only one lane detector. This requires the single detector, by definition, to be classified as a downstream detector for software purposes, while wired as an upstream detector for value counts. It is desirable to have such a single detector classified as upstream within the initialization routine, not downstream.

Another desirable feature would be to have a total of all speed data classified and excluded from calculation to compare to volume data.

There are also more detector checking routines that could be employed. The routine used now has provisions for six more failure descriptions. And, of course, there are running and average running total control data not being initialized at all.

A word of caution is in order with respect to modification. The cross-reference table in Appendix A is useful to trace the origin and use of variables. When even minor changes are made to a routine, the implication of it must be traced through the total system. Also, ad hoc modification has its limits. The author is of the opinion that, if a major addition or change proves necessary, the entire software package should be rewritten with those PCS objectives in mind. PCS has ample fourth generation modified software already and, as a result, is becoming less receptive to change.

8/ ACKNOWLEDGEMENTS

A significant contribution in both technical and philosophical matters by Mr. R. Bur is gratefully acknowledged. His continued co-operation in all stages of the project was a key factor in its success.

9/ BIBLIOGRAPHY

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PAGE 003 DEFINE .SATO SUB

00117 0007 A LSA EQU 97
 00118 0008 A CIE EQU 98
 00119 0009 A C1E EQU 99
 00120 0010 A C2E EQU 9A
 00121 0011 A C3E EQU 9B
 00122 0012 A S2E EQU 9C
 00123 0013 A S3E EQU 9D
 00124 0014 A S4E EQU 9E
 00125 0015 A S5E EQU 9F
 00126 0016 A S6E EQU 99
 00127 0017 A S7E EQU 9A
 00128 0018 A S8E EQU 9B
 00129 0019 A S9E EQU 9C
 00130 0020 A S10E EQU 9D
 00131 0021 A S11E EQU 9E
 00132 0022 A S12E EQU 9F
 00133 0023 A S13E EQU 99
 00134 0024 A S14E EQU 9A
 00135 0025 A S15E EQU 9B
 00136 0026 A S16E EQU 9C
 00137 0027 A S17E EQU 9D
 00138 0028 A S18E EQU 9E
 00139 0029 A S19E EQU 9F
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 00164 0054 A S44E EQU 9C
 00165 0055 A S45E EQU 9D
 00166 0056 A S46E EQU 9E
 00167 0057 A S47E EQU 9F
 00168 0058 A S48E EQU 99
 00169 0059 A S49E EQU 9A
 00170 0060 A S50E EQU 9B
 00171 0061 A S51E EQU 9C
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 00178 0068 A S58E EQU 9C
 00179 0069 A S59E EQU 9D
 00180 0070 A S60E EQU 9E
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 00184 0074 A S64E EQU 9B
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 00189 0079 A S69E EQU 99
 00190 0080 A S70E EQU 9A
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 00193 0083 A S73E EQU 9D
 00194 0084 A S74E EQU 9E
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 00220 0110 A S100E EQU 9C
 00221 0111 A S101E EQU 9D
 00222 0112 A S102E EQU 9E
 00223 0113 A S103E EQU 9F
 00224 0114 A S104E EQU 99
 00225 0115 A S105E EQU 9A
 00226 0116 A S106E EQU 9B
 00227 0117 A S107E EQU 9C
 00228 0118 A S108E EQU 9D
 00229 0119 A S109E EQU 9E
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 00231 0121 A S111E EQU 99
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 00234 0124 A S114E EQU 9C
 00235 0125 A S115E EQU 9D
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 00240 0130 A S120E EQU 9B
 00241 0131 A S121E EQU 9C
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 00243 0133 A S123E EQU 9E
 00244 0134 A S124E EQU 9F
 00245 0135 A S125E EQU 99
 00246 0136 A S126E EQU 9A
 00247 0137 A S127E EQU 9B
 00248 0138 A S128E EQU 9C
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PAGE 006 TRY .SATO PPRT
00291 0 PCW-PROPORTION OF M TO BE SUBTRACTED
00292 0
00293 0 CALLING SEQUENCE
00294 0
00295 0 PLACE PCW IN ACCA
00296 0
00297 0 MOTOROLA N408AN CROSS-ASSEMBLER PAGE 2
00298 0
00299 0 SET THE INDEX REGISTER TO POINT TO M OR M - MSB
00300 0 JRR PPRTS OR PPRT
00301 0
00302 0 ON RETURN (ACCA)-PROPORTION OF M REQUIRED - MSB
00303 0 AND (ACCB)-PROPORTION OF M REQUIRED - LSB
00304 0
00305A C080 0MS PPRTS
00306 0
00307A C080 3A PSHA PCW ON STACK
00308A C081 E6 00 LDAB X ORIGINAL VALUE
00309A C083 4F CLRA CLEAR MSB
00310A C084 26 2F C085 BSA P10 ON WITH PROGRAM
00311 0
00312A C086 0MS PPRT
00313A C089 2A PSHA PCW ON STACK
00314A C091 A6 00 LDAB X ORIGINAL VALUE - MSB
00315A C093 E6 01 A LBAA 1,X ORIGINAL VALUE - LSB
00316A C095 3A PSHA PUT ON STACK
00317A C096 37 PSMB SPACE FOR ROUND-OFF FLAG
00318A C097 34 DES POINT INDEX REG. TO STACKED DATA
00319A C098 30 TEX
00320 0
00321 0 THE STACK NOW LOOKS LIKE THIS!
00322 0
00323 0 +0 ROUND OFF FLAG
00324 0 +1 ORIGINAL VALUE - LSB
00325 0 +2 ORIGINAL VALUE - MSB
00326 0 +3 PROPORTION CONTROL WORD
00327 0
00328A C099 4F 00 A AGAIN CLR 0,X CLEAR ROUND OFF FLAG
00329 0
00330 0
00331 0 MOTOROLA N408AN CROSS-ASSEMBLER PAGE 3
00332A C099 44 02 A LSR 2,X SHIFT MSB
00333A C09D 46 01 A RGR 1,X SHIFT LSB
00334A C09F 24 02 C0C3 BCC P1 IF NO CARRY, GO ON
00335A C0C1 4C 00 A INC 0,X SET ROUND-OFF FLAG
00336 0
00337A C0C3 48 03 A P1 ASL 3,X CHECK FOR PCW BIT SET
00338A C0C5 24 0B C094 BCC CHECK IF NO BIT SET, DON'T SUBTRACT
00339A C0C7 E0 01 A SUBB 1,X SUBTRACT PROPORTION - LSB
00340A C0C9 A2 02 A SBCA 2,X SUBTRACT PROPORTION - MSB
00341A C0CB 4B 00 A TST 0,X IS ROUND-OFF FLAG SET?
00342A C0CD 27 05 C084 BEQ CHECK IF NOT, CHECK TO SEE IF RETURN
00343A C0CF C0 01 A SUBB 001 SUBTRACT ONE FROM LSB
00344A C0D1 24 01 C084 BCC CHECK IF NO OVERFLOW, CHECK ON RETURN
00345A C0D3 4A DECA SUBTRACT OVERFLOW FROM MSB
00346 0
00347A C094 4B 03 A CHECK TST 3,X CHECK PCW FOR ANY BIT SET!
00348A C0D4 26 E1 C08F BNE AGAIN IF ONE MORE BIT SET, GO BACK THROUGH

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PAGE 007 TRY	.SALO PRPXT
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008770	8328	4C				INCA	
008780	8329	97	97	A		STAA	CYCLE
008790	8330	94	70	A		LBAA	VOLBAY
008800	8331	00	02	A		808A	9902
008810	8332	27	94	8334		808	810
008820	8333	96	97	A		LBAA	CYCLE
008830	8334	97	70	A		STAA	VOLBAY
008840	8335	96	97	A	H10	LBAA	CYCLE
008850	8336	80	03	A		808A	9903
008860	8337	27	C6	8338		808	808IN
008870	8338	7E	8347	A		JMP	83
008880	8339	8E	91	A	84	LBX	VEBAY1
008890	8340	96	03	A		LBAA	YEAR
008900	8341	07	00	A		STAA	0-X
008910	8342	96	04	A		LBAA	808IN
008920	8343	07	01	A		STAA	1-X
008930	8344	96	08	A		LBAA	8407ND
008940	8345	07	02	A		STAA	2-X
008950	8346	96	09	A		LBAA	8407NK
008960	8347	07	03	A		STAA	3-X
008970	8348						
008980	8349	8E	48	A		LBX	VEBAY1
008990	8350	96	03	A		LBAA	YEAR
009000	8351	07	00	A		STAA	0-X
009010	8352	96	04	A		LBAA	808IN
009020	8353	07	01	A		STAA	1-X
009030	8354	96	05	A		LBAA	8407ND
009040	8355	07	02	A		STAA	2-X
009050	8356	96	09	A		LBAA	8407NK
009060	8357	07	03	A		STAA	3-X
009070	8358						
009080	8359	8E	4A	A		LBX	VEBAY1
009090	8360	96	03	A		LBAA	YEAR
009100	8361	07	00	A		STAA	0-X
009110	8362	96	04	A		LBAA	808IN
009120	8363	07	01	A		STAA	1-X
009130	8364	96	05	A		LBAA	8407ND
009140	8365	07	02	A		STAA	2-X
009150	8366	96	09	A		LBAA	8407NK
009160	8367	07	03	A		STAA	3-X
009170	8368						
009180	8369						
009190	8370	3P				818	
009200							
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009240							
009250							
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009270							
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MOTOROLA NISSAN CROSS-ASSEMBLER PAGE 1
 8
 8 NISSAN IS THE PROPERTY OF MOTOROLA 899, INC.
 8 COPYRIGHT 1976 BY MOTOROLA INC
 8
 8 MOTOROLA 8600 CROSS ASSEMBLER, RELEASE 1.1
 8 CALTRANS 78 N.Y.C MODIFIED, RELEASE 1.0
 8

IS THIS PROGRAM MATERIAL FOR DESIGN STUDY ONLY

1981 00 00

RELATIVE LEVEL 4.73

11

PCB1, 48 REV. 1-00

1998

100

ASSIGNMENTS (PORT NO., 0 BIT NO.) AND THE INTERNAL SOFTWARE

BIOGRAPHICAL INFORMATION

1997

1984 1985

CLM

STAD
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STAD

INTERVIEW: A. K.

1700

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1. 1990

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1

0-1

Year	1980
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MAY 1967[illegible]

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RECEIVED 1991

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07X TEMPO-00

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2165	2166	2167
2168	2169	2170
2171	2172	2173
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2303	2304</	

904 1971

PAGE 023 FROM .S010 FC09

[illegible]

PAGE 024 YOUR -BA10 PCSS

01335A CS02 08 INX
01336A CS03 12 PCW FROM STACK
01337
01338
01339 MOTOROLA M6800 CROSS-ASSEMBLER PAGE 4
01340A CS04 20 EA C4FO S BRA LOOPS BACK FOR NEXT ART
01341
01342A CS04 31 OUT INS
01343A CS07 39 OUTI RTS
01344A CS08 FF A PCNTAB FCB 6OFF
01345A CS09 00 A FCB PCLM1 PCW FOR 0 LANES
01346A CS0A 80 A FCB PCLM2 STORE PROPORTION CONTROL WORDS
01347A CS0B AB A FCB PCLM3 IN FROM FOR AVERAGING THE OCCUPANCIES
01348A CS0C CB A FCB PCLM4 AND VOLUMES FOR THE NUMBER OF VALID LANES
01349A CS0D CB A FCB PCLM5 AT THIS SITE.
01350A CS0E DB A FCB PCLM6
01351A CS0F DB A FCB PCLM7
01352A CS10 E0 A FCB PCLM8
01353
01354
01355 MOTOROLA M6800 CROSS-ASSEMBLER PAGE 1
01356 S M6800 IS THE PROPERTY OF MOTOROLA SPB, INC.
01357 S COPYRIGHT 1974 BY MOTOROLA INC
01358 S
01359 S MOTOROLA M6800 CROSS ASSEMBLER, RELEASE 1.1
01360 S CALTRANS TO M.T.C. MODIFIED, RELEASE 1.0
01361 S THIS PROGRAM MATERIAL FOR DESIGN STUDY ONLY
01362 S
01363 S 1981 08 20
01364 S
01365 S RELEASE LEVEL 6.75
01366 S
01367 S NAM PCSSA
01368 S
01369 S PCSSA.AS REV 1.00
01370 S STEVEN SKELTON
01371 S
01372 S
01373 S THIS ROUTINE Sums THE RUNNING TOTALS FOR UP TO EIGHT VALID LANES
01374 S AND DIVIDES BY THE NUMBER OF VALID LANES, PROVIDING
01375 S AN AVERAGE RUNNING TOTAL.
01376 S
01377 S
01378 S TWO SEPARATE AVERAGE RUNNING TOTALS (ART) ARE
01379 S MAINTAINED. ONE FOR VOLUME AND ONE FOR OCCUPANCY
01380 S FOR 1 MINUTE DATA.
01381 S
01382A CSB0 ORG PCSSA
01383
01384
01385
01386A CSB0 C4 04 A LDAB 604 4 VARIABLES TO CLEAR
01387A CSB2 CE 00FC A LDX 6ARIN0+910
01388A CSB5 4F 00 A LOOPAI CLR 0+X CLEAR ART
01389A CSB7 08 INX NEXT ART
01390A CSB8 5A DECB LAST ONE CLEARED?
01391A CSB9 26 FA CBDS BME LOOPAI IF NOT, CLEAR ANOTHER.
01392

PAGE 025 YOUR .8A10 PC85A

01392A	C8B9 C6 08	A	LDAB	98	COUNTER FOR VALID LAMES
01394A	C8B9 B9 C040	A	JER	SETUP	POINT TO LAME 5 AREA
01395A	C8C0 A6 8A	A	LOOPA2	LDAB	DETECTOR ERROR WORD
01396A	C8C2 48	A	LDAB	DETECTOR ERROR BIT TO CARRY	
01397A	C8C3 24 06	C8E9	BCC	EAS	IF DATA 0.X. - 00 0M
01398A	C8C3 3A	EAS	BCC	DECREMENT VALID LAME COUNT	
01399A	C8C4 44	A	LDAB	DETECTOR ERROR BIT	
01400A	C8C7 A7 8A	A	STAA	DETECTOR ERROR WORD	
01401A	C8E9 20 21	C90C	BRA	SEE IF ALL LAMES COUNTED	
01402					
01403A	C8E9 A9 8C	A	EAS	LDAB	DETECTOR ERROR WORD
01404A	C8E9 24 F6	C8E5	BNE	EAS	YES -- DECREMENT VALID LAME COUNT & SET FOR NEXT LAME
01405A	C8E9 A4 84	A	LDAB	VMM1+880,X 1 MINUTE VOLUME	
01406A	C8F1 3A	A	PSMA	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01407A	C8F2 A4 82	A	LDAB	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01408A	C8F4 3A	A	PSMA	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01409A	C8F7 A4 83	A	LDAB	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01410A	C8F7 CE 00FC	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01411A	C8F8 A9 01	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01412A	C8F8 A7 01	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01413A	C8F8 32	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01414A	C8F8 A7 00	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01415A	C901 A7 00	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01416A	C903 32	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01417					
01418					
01419					
01420A	C904 A9 03	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01421A	C906 A7 03	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01422A	C908 24 02	C90C	BCC	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01423A	C90A 4C 02	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01424					
01425					
01426A	C90C B9 C030	A	LOOPA2	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01427A	C90F 24 CF	C8E9	BCC	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01428					
01429A	C911 CE C508	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01430A	C914 5C	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01431A	C915 5C	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01432A	C916 27 03	C918	BCC	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01433A	C918 08	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01434A	C919 20 FA	C915	BCC	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01435					
01436A	C91B A6 00	A	PICKUP	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01437A	C91B CE 00FC	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01438A	C920 2A	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01439A	C921 BF EA	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01440A	C923 B9 C080	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01441A	C926 BE EA	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01442A	C928 A7 00	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01443A	C92A E7 01	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01444A	C92C EC 00FC	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01445A	C92F 27 05	C926	BCC	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01446A	C931 08	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01447A	C932 08	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01448A	C933 22	A	LDX	OCNMIN+880,X 1 MINUTE OCCUPANCY - MSB	
01449					
01450					

MOTOROLA M6800 CROSS-ASSEMBLER PAGE 4

PAGE 026 YOUR .S410 PC55A	01451	BRA	LOOPAS	BACK FOR NEXT ART	01509A	C34E	8D 29	C599	ERR	YES -- FLAG THIS DETECTOR
	01452	OUTT	INS	BACK FOR NEXT ART	01510A	C370	8D C030	A L09	JBR	LAST LAMEY
	01453	OUTT1	RTS	BACK TO CALLER	01511A	C373	24 E9	C58E	BCC	NO -- LOOP BACK
	01454				01512					
	01455				01513A	C375	C4 01	A	LDAB	SET D/P LAME PTR
	01456				01514A	C377	CE 0100	A	LX	SET DETECTOR PTR
	01457				01515A	C37A	B7 F7	A	STAB	STORE O/P LAME POINTER
	01458				01516A	C37C	A4 0A	A L012	LDAA	SET ERROR BYTE
	01459				01517A	C37E	48		ABLA	ERROR BIT SET
	01460				01518A	C37F	24 04	C585	BCC	NO
	01461				01519A	C501	8A 88	A	ORAB	SET ALARM
	01462				01520A	C503	B7 88	A	STAB	STORE ALARM
	01463				01521A	C505	84 F7	A L011	LDAB	INCREMENT O/P LAME PTR
	01464				01522A	C507	58		ABLA	STORE PTR
	01465				01523A	C508	B7 F7	A	STAB	ALL BONES
	01466				01524A	C50A	25 0C	C598	BCC	STORE DETECTOR PTR
	01467				01525A	C50C	B7 F5	A	STX	STORE DETECTOR PTR
	01468				01526A	C50E	7A F5	A	LDAA	UPDATE DETECTOR PTR
	01469				01527A	C510	88 10	A	ABDA	STORE IT1
	01470				01528A	C512	87 F4	A	STAB	LOAD DETECTOR PTR
	01471				01529A	C514	DE F5	A	LX	
	01472				01530A	C516	20 E4	C57C	L013	
	01473				01531A	C518	39		RTS	
	01474				01532					
	01475				01533					
	01476				01534A	C519	E4 0C	C5A1	ERR	LDAB
	01477				01535A	C51B	24 04	C5A1	BHE	YES -- NO BACK
	01478				01536A	C51D	AA 0A	A	ORAA	DET1,X
	01479				01537A	C51F	A7 0A	A	STAB	SET BIT
	01480				01538A	C521	39		RTS	BACK TO CALLER
	01481				01539					
	01482				01540A	C523	74 E9	A	OC7EST	LDAA
	01483				01541A	C524	78 F8	A	ABDA	INDEX+1
	01484				01542A	C526	77 FA	A	STAB	TEMP04
	01485				01543A	C528	77 FA	A	LDX	TEMP05
	01486				01544A	C52A	DE F9	A	JBR	CMP16
	01487				01545A	C52C	DE EA	A	LX	INDEX
	01488				01546A	C52F	39		RTS	MAKE OCCUPANCY COMPARISON
	01489				01547					RESTORE X
	01490				01548					
	01491				01549					
	01492				01550					
	01493				01551					
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	01543				01601					
	01544				01602					
	01545				01603					
	01546				01604					

PAGE 031 YOUR .8410 PC87

01741A	C729	AB	00	A	000A	0-X
01742A	C72B	A7	00	A	010A	0-X
01743						
01744A	C72D	0C			CLC	1-X
01745A	C72E	E9	01	A	ABCB	1-X
01746A	C72F	E7	01	A	STAB	1-X
01747A	C72G	24	02	C73A	BCC	040
01748A	C72H	4C	00	A	INC	0-X
01749						
01750A	C72I	94	A1	A	LBAA	SPC2
01751A	C72J	80	10	A	SUBA	0910
01752A	C72K	97	A1	A	STAB	SPC2
01753A	C72L	0E	A0	A	LBX	SPC1
01754A	C72M	20	C3	C742	BRA	030
01755						
01756A	C740	CA	02	A	LBAB	002
01757A	C741	87	F7	A	STAB	TEMP03
01758A	C742	84	F3	A	LBAB	TEMP01
01759A	C743	27	02	C74B	BEB	034
01760A	C744	5A			BECC	
01761A	C745	87	F3	A	STAB	TEMP01
01762A	C746	94	F8	A	LBAB	TEMP07
01763A	C747	4C			INCA	
01764A	C748	97	F3	A	STAB	TEMP07
01765A	C749	00	07	A	SUBA	0909
01766A	C750	24	0E	C4E2	BHE	030
01767						
01768A	C751	39			RTB	
01769						
01770A	C752	FF	A		PCB	00FF
01771						
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01795						
01796A	C400				GRB	INPUT
01797						
01798A	C400	84	50	A	LBAA	0450

01799A C400 84 50 A

MOTOROLA MASSAM CROSS-ASSEMBLER PAGE 1

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MOTOROLA MASAM CROSS ASSEMBLER, RELEASE 1.1

CALTRANS TO H.T.C MODIFIED, RELEASE 2.0

THIS PROGRAM MATERIAL FOR DESIGN STUDY ONLY

1981 08 08

RELEASE LEVEL 0.75

MAN PC81A

PC81A, AS REV. 1.00

STEVEN SKELTON

FOR TYPE 324 CABINET

THIS ROUTINE PROVIDES CORRESPONDENCE BETWEEN HARDWARE DETECTOR

ASSIGNMENTS (PORT NO., 8 BIT NO.) AND THE INTERNAL SOFTWARE

DETECTOR ASSIGNMENTS

GRB INPUT

LBAA 0450

PAGE	032	LUCK	-0010	PC010
017994	C002	97	F3	A
018000	C004	97	EA	A
018001	C005	97	EA	A
018002	C007	97	EB	A
018003				B
018004				B
018005				B
018006	C009	97	CC	A
018007	C008	97	NC	A
018008	C009	CC	C03F	A
018009	C010	97	F8	A
018010	C012	C4	01	A
018011				B
018012	C014	37		IP2
018013	C013	44	00	A
018014	C017	97	F4	A
018015	C019	96	01	A
018016	C019	96	01	A
018017	C019	96	01	A
018018	C019	96	01	A
018019	C021	9E	EA	A
018020	C023	5A	CC	A
018021	C025	E4	68	A
018022	C027	E7	CC	A
018023				B
018024	C029	9E	F8	A
018025	C028	00		INX
018026	C03C	00		INX
018027	C028	9F	F8	A
018028	C03F	33		POLB
018029				B
018030	C030	30		
018031	C031	24	E1	C014
018032	C033	70	00C8	A
018033	C034	26	00C8	A
018034	C036	86	10	IP3
018035	C03A	97	EB	A
018036	C03C	20	94	C012
018037				B
018038	C03E	39		90
018039				B
018040				B
018041				B
018042				B
018043	C03F	02	A	91RT18
018044	C040	01	A	FCB
018045	C041	02	A	FCB
018046	C042	02	A	FCB
018047	C043	07	A	FCB
018048	C044	04	A	FCB
018049	C045	02	A	FCB
018050	C046	08	A	FCB
018051	C047	02	A	FCB
018052	C048	10	A	FCB
018053	C049	02	A	FCB
018054	C04A	20	A	FCB
018055	C04B	02	A	FCB
018056	C04C	00	A	FCB

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01827A C440	02	A	FCB	002	LAME SIXTEEN
01828A C44E	00	A	FCB	7B17	
01829					
01840A C40F	04	A	FCB	004	DIRECTION TWO
01841A C450	01	A	FCB	7B10	LAME NINE
01842A C451	04	A	FCB	004	
01843A C452	02	A	FCB	7B11	LAME TEN
01844A C453	04	A	FCB	004	
01845A C454	04	A	FCB	7B12	LAME ELEVEN
01846A C455	04	A	FCB	004	
01847A C456	08	A	FCB	7B13	LAME TWELVE
01848A C457	04	A	FCB	004	
01849A C458	10	A	FCB	7B14	LAME THIRTEEN
01870A C459	04	A	FCB	004	
01871A C45A	20	A	FCB	7B15	LAME FOURTEEN
01872A C45B	04	A	FCB	004	
01873A C45C	40	A	FCB	7B16	LAME FIFTEEN
01874A C45D	04	A	FCB	004	
01875A C45E	08	A	FCB	7B17	LAME SIXTEEN
01876					
01877A C40F	FFFF	A	FCB	00FFFF	
01878A C461	FFFF	A	FCB	00FFFF	
01879A C463	FF	A	FCB	00FF	
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01880A HARRAN CROSS-ASSEMBLER PAGE 1

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